

Notes: These are notes live-tex'd from a graduate
course in 4-Manifolds taught by Philip Engel at the
University of Georgia in Spring 2021. As such, any
errors or inaccuracies are almost certainly my own.

## 4-Manifolds

## Lectures by Philip Engel. University of Georgia, Spring 2021

D. Zack Garza

University of Georgia
dzackgarza@gmail.com
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## 1 Tuesday, January 12

### 1.1 Background

From Phil's email:
Personally, I found the following online references particularly useful:

- Dietmar Salamon: Spin Geometry and Seiberg-Witten Invariants [5]
- Richard Mandelbaum: Four-dimensional Topology: An Introduction [2]
- This book has a nice introduction to surgery aspects of four-manifolds, but as a warning: It was published right before Freedman's famous theorem. For instance, the existence of an exotic R^4 was not known. This actually makes it quite useful, as a summary of what was known before, and provides the historical context in which Freedman's theorem was proven.
- Danny Calegari: Notes on 4 -Manifolds [1]
- Yuli Rudyak: Piecewise Linear Structures on Topological Manifolds [4]
- Akhil Mathew: The Dirac Operator [3]
- Tom Weston: An Introduction to Cobordism Theory [6]

A wide variety of lecture notes on the Atiyah-Singer index theorem, which are available online.

### 1.2 Introduction

Definition 1.2.1 (Topological Manifold)
Recall that a topological manifold (or $C^{0}$ manifold) $X$ is a Hausdorff topological space locally homeomorphic to $\mathbb{R}^{n}$ with a countable topological base, so we have charts $\varphi_{u}: U \rightarrow \mathbb{R}^{n}$ which are homeomorphisms from open sets covering $X$.

Example 1.2.2(The circle): $S^{1}$ is covered by two charts homeomorphic to intervals:

## $U_{2} \hookrightarrow \mathbb{R}$

Remark 1.2.3: Maps that are merely continuous are poorly behaved, so we may want to impose extra structure. This can be done by imposing restrictions on the transition functions, defined as

$$
t_{u v}:=\varphi_{V} \rightarrow \varphi_{U}^{-1}: \varphi_{U}(U \cap V) \rightarrow \varphi_{V}(U \cap V) .
$$

Definition 1.2.4 (Restricted Structures on Manifolds)

- We say $X$ is a PL manifold if and only if $t_{U V}$ are piecewise-linear. Note that an invertible PL map has a PL inverse.
- We say $X$ is a $C^{k}$ manifold if they are $k$ times continuously differentiable, and smooth if infinitely differentiable.
- We say $X$ is real-analytic if they are locally given by convergent power series.
- We say $X$ is complex-analytic if under the identification $\mathbb{R}^{n} \cong \mathbb{C}^{n / 2}$ if they are holomorphic, i.e. the differential of $t_{U V}$ is complex linear.
- We say $X$ is a projective variety if it is the vanishing locus of homogeneous polynomials on $\mathbb{C P}^{N}$.

Remark 1.2.5: Is this a strictly increasing hierarchy? It's not clear e.g. that every $C^{k}$ manifold is PL.

## Question 1.2.6

Consider $\mathbb{R}^{n}$ as a topological manifold: are any two smooth structures on $\mathbb{R}^{n}$ diffeomorphic?

Remark 1.2.7: Fix a copy of $\mathbb{R}$ and form a single chart $\mathbb{R} \xrightarrow{\text { id }} \mathbb{R}$. There is only a single transition function, the identity, which is smooth. But consider

$$
\begin{aligned}
X & \rightarrow \mathbb{R} \\
t & \mapsto t^{3}
\end{aligned}
$$

This is also a smooth structure on $X$, since the transition function is the identity. This yields a different smooth structure, since these two charts don't like in the same maximal atlas. Otherwise there would be a transition function of the form $t_{V U}: t \mapsto t^{1 / 3}$, which is not smooth at zero. However, the map

$$
\begin{aligned}
X & \rightarrow X \\
t & \mapsto t^{3} .
\end{aligned}
$$

defines a diffeomorphism between the two smooth structures.

Claim: $\mathbb{R}$ admits a unique smooth structure.

Proof (sketch).
Let $\tilde{\mathbb{R}}$ be some exotic $\mathbb{R}$, i.e. a smooth manifold homeomorphic to $\mathbb{R}$. Cover this by coordinate charts to the standard $\mathbb{R}$ :


## Fact

There exists a cover which is locally finite and supports a partition of unity: a collection of smooth functions $f_{i}: U_{i} \rightarrow \mathbb{R}$ with $f_{i} \geq 0$ and $\operatorname{supp} f \subseteq U_{i}$ such that $\sum f_{i}=1$ (i.e., bump functions). It is also a purely topological fact that $\tilde{\mathbb{R}}$ is orientable.

So we have bump functions:


Take a smooth vector field $V_{i}$ on $U_{i}$ everywhere aligning with the orientation. Then $\sum f_{i} V_{i}$ is a smooth nowhere vector field on $X$ that is nowhere zero in the direction of the orientation. Taking the associated flow

$$
\begin{aligned}
\mathbb{R} & \rightarrow \tilde{\mathbb{R}} \\
t & \mapsto \varphi(t) .
\end{aligned}
$$

such that $\varphi^{\prime}(t)=V(\varphi(t))$. Then $\varphi$ is a smooth map that defines a diffeomorphism. This follows from the fact that the vector field is everywhere positive.

## Slogan 1.2.9

To understand smooth structures on $X$, we should try to solve differential equations on $X$.

Remark 1.2.10: Note that here we used the existence of a global frame, i.e. a trivialization of the tangent bundle, so this doesn't quite work for e.g. $S^{2}$.

## Question 1.2.11

What is the difference between all of the above structures? Are there obstructions to admitting any particular one?

## Answer 1.2.12

1. (Munkres) Every $C^{1}$ structure gives a unique $C^{k}$ and $C^{\infty}$ structure. ${ }^{1}$
2. (Grauert) Every $C^{\infty}$ structure gives a unique real-analytic structure.
3. Every PL manifold admits a smooth structure in $\operatorname{dim} X \leq 7$, and it's unique in $\operatorname{dim} X \leq 6$, and above these dimensions there exists PL manifolds with no smooth structure.
4. (Kirby-Siebenmann) Let $X$ be a topological manifold of $\operatorname{dim} X \geq 5$, then there exists a

[^0]cohomology class $\mathrm{ks}(X) \in H^{4}(X ; \mathbb{Z} / 2 \mathbb{Z})$ which is 0 if and only if $X$ admits a PL structure. Moreover, if $\mathrm{ks}(X)=0$, then (up to concordance) the set of PL structures is given by $H^{3}(X ; \mathbb{Z} / 2 \mathbb{Z})$.
5. (Moise) Every topological manifold in $\operatorname{dim} X \leq 3$ admits a unique smooth structure.
6. (Smale et al.): In $\operatorname{dim} X \geq 5$, the number of smooth structures on a topological manifold $X$ is finite. In particular, $\mathbb{R}^{n}$ for $n \neq 4$ has a unique smooth structure. So dimension 4 is interesting!
7. (Taubes) $\mathbb{R}^{4}$ admits uncountably many non-diffeomorphic smooth structures.
8. A compact oriented smooth surface $\Sigma$, the space of complex-analytic structures is a complex orbifold ${ }^{2}$ of dimension $3 g-2$ where $g$ is the genus of $\Sigma$, up to biholomorphism (i.e. moduli).

Remark 1.2.13: Kervaire-Milnor: $S^{7}$ admits 28 smooth structures, which form a group.

## 2 Friday, January 15

## Remark 2.0.1: Let

$$
\begin{aligned}
V & :=\left\{a^{2}+b^{2}+c^{2}+d^{3}+e^{6 k-1}=0\right\} \subseteq \mathbb{C}^{5} \\
S_{\varepsilon} & :=\left\{|a|^{2}+|b|^{2}+|c|^{2}+|d|^{2}+|e|^{2}=1\right\}
\end{aligned}
$$

Then $V_{k} \cap S_{\varepsilon} \cong S^{7}$ is a homeomorphism, and taking $k=1,2, \cdots, 28$ yields the 28 smooth structures on $S^{7}$. Note that $V_{k}$ is the cone over $V_{k} \cap S_{\varepsilon}$.


[^1]
## Question 2.0.2

Is every triangulable manifold PL, i.e. homeomorphic to a simplicial complex?

## Answer 2.0.3

No! Given a simplicial complex, there is a notion of the combinatorial link $L_{V}$ of a vertex $V$ :


It turns out that there exist simplicial manifolds such that the link is not homeomorphic to a sphere, whereas every PL manifold admits a "PL triangulation" where the links are spheres.

Remark 2.0.4: What's special in dimension 4? Recall the Kirby-Siebenmann invariant ks $(x) \in$ $H^{4}\left(X ; \mathbb{Z}_{2}\right)$ for $X$ a topological manifold where $\mathrm{ks}(X)=0 \Longleftrightarrow X$ admits a PL structure, with the caveat that $\operatorname{dim} X \geq 5$. We can use this to cook up an invariant of 4 -manifolds.

Definition 2.0.5 (Kirby-Siebenmann Invariant of a 4-manifold)
Let $X$ be a topological 4 -manifold, then

$$
\mathrm{ks}(X):=\mathrm{ks}(X \times \mathbb{R})
$$

Remark 2.0.6: Recall that in $\operatorname{dim} X \geq 7$, every PL manifold admits a smooth structure, and we can note that

$$
H^{4}\left(X ; \mathbb{Z}_{2}\right)=H^{4}\left(X \times \mathbb{R} ; \mathbb{Z}_{2}\right)=\mathbb{Z}_{2},
$$

since every oriented 4 -manifold admits a fundamental class. Thus

$$
\mathrm{ks}(X)= \begin{cases}0 & X \times \mathbb{R} \text { admits a PL and smooth structure } \\ 1 & X \times \mathbb{R} \text { admits no PL or smooth structures }\end{cases}
$$

Remark 2.0.7: $\mathrm{ks}(X) \neq 0$ implies that $X$ has no smooth structure, since $X \times \mathbb{R}$ doesn't. Note that it was not known if this invariant was ever nonzero for a while!

Remark 2.0.8: Note that $H^{2}(X ; \mathbb{Z})$ admits a symmetric bilinear form $Q_{X}$ defined by

$$
\begin{aligned}
Q_{X}: H^{2}(X ; \mathbb{Z})^{\otimes 2} & \rightarrow \mathbb{Z} \\
\alpha \otimes \beta & \mapsto \int_{X} \alpha \wedge \beta:=(\alpha \smile \beta)([X]) .
\end{aligned}
$$

where $[X]$ is the fundamental class.

## 3 Main Theorems for the Course

Remark 3.0.1: Proving the following theorems is the main goal of this course:

## Theorem 3.0.2(Freedman).

If $X, Y$ are compact oriented topological 4-manifolds, then $X \cong Y$ are homeomorphic if and only if $\operatorname{ks}(X)=\mathrm{ks}(Y)$ and $Q_{X} \cong Q_{Y}$ are isometric, i.e. there exists an isometry

$$
\varphi: H^{2}(X ; \mathbb{Z}) \rightarrow H^{2}(Y ; \mathbb{Z})
$$

that preserves the two bilinear forms in the sense that $\langle\varphi \alpha, \varphi \beta\rangle=\langle\alpha, \beta\rangle$.
Conversely, every unimodular bilinear form appears as $H^{2}(X ; \mathbb{Z})$ for some $X$, i.e. the pairing induces a map

$$
\begin{aligned}
H^{2}(X ; \mathbb{Z}) & \rightarrow H^{2}(X ; \mathbb{Z})^{\vee} \\
\alpha & \mapsto\langle\alpha,-\rangle .
\end{aligned}
$$

which is an isomorphism. This is essentially a classification of simply-connected 4-manifolds.

Remark 3.0.3: Note that preservation of a bilinear form is a stand-in for "being an element of the orthogonal group", where we only have a lattice instead of a full vector space.

Remark 3.0.4: There is a map $H^{2}(X ; \mathbb{Z}) \xrightarrow{P D} H_{2}(X ; \mathbb{Z})$ from Poincaré, where we can think of elements in the latter as closed surfaces [ $\Sigma$ ], and

$$
\left\langle\Sigma_{1}, \Sigma_{2}\right\rangle=\text { signed number of intersections points of } \Sigma_{1} \pitchfork \Sigma_{2}
$$

Note that Freedman's theorem is only about homeomorphism, and is not true smoothly. This gives a way to show that two 4 -manifolds are homeomorphic, but this is hard to prove! So we'll black-box this, and focus on ways to show that two smooth 4-manifolds are not diffeomorphic, since we want homeomorphic but non-diffeomorphic manifolds.

Definition 3.0.5 (Signature)
The signature of a topological 4- manifold is the signature of $Q_{X}$, where we note that $Q_{X}$ is a symmetric nondegenerate bilinear form on $H^{2}(X ; \mathbb{R})$ and for some $a, b$

$$
\left(H^{2}(X ; \mathbb{R}), Q_{x}\right) \xrightarrow{\text { isometric }} \mathbb{R}^{a, b}
$$

where $a$ is the number of +1 s appearing in the matrix and $b$ is the number of -1 s . This is $\mathbb{R}^{a b}$ where $e_{i}^{2}=1, i=1 \cdots a$ and $e_{i}^{2}=-1, i=a+1, \cdots b$, and is thus equipped with a specific bilinear form corresponding to the Gram matrix of this basis.

$$
\left[\begin{array}{ccccc}
1 & 0 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 \\
0 & 0 & \ddots & 0 & 0 \\
0 & 0 & 0 & -1 & 0 \\
0 & 0 & 0 & 0 & -1
\end{array}\right]=I_{a \times a} \oplus-I_{b \times b}
$$

Then the signature is $a-b$, the dimension of the positive-definite space minus the dimension of the negative-definite space.

## Theorem 3.0.6(Rokhlin's Theorem).

Suppose $\langle\alpha, \alpha\rangle \in 2 \mathbb{Z}$ and $\alpha \in H^{2}(X ; \mathbb{Z})$ and $X$ a simply connected smooth 4-manifold. Then 16 divides $\operatorname{sig}(X)$.

Remark 3.0.7: Note that Freedman's theorem implies that there exists topological 4-manifolds with no smooth structure.

Theorem 3.0.8(Donaldson).
Let $X$ be a smooth simply-connected 4-manifold. If $a=0$ or $b=0$, then $Q_{X}$ is diagonalizable and there exists an orthonormal basis of $H^{2}(X ; \mathbb{Z})$.

Remark 3.0.9: This comes from Gram-Schmidt, and restricts what types of intersection forms can occur.

### 3.1 Warm Up: $\mathbb{R}^{2}$ Has a Unique Smooth Structure

Remark 3.1.1: Last time we showed $\mathbb{R}^{1}$ had a unique smooth structure, so now we'll do this for $\mathbb{R}^{2}$. The strategy of solving a differential equation, we'll now sketch the proof.

Definition 3.1.2 (Riemannian Metrics)
A Riemannian metric $g \in \Gamma\left(\operatorname{Sym}^{2} T^{\vee} X\right)$ for $X$ a smooth manifold is a metric on every $T_{p} X$, so $g_{p} \in\left(T_{p} X^{\otimes 2}\right)^{\vee}$, such that

$$
g_{p}: T_{p} X \otimes T_{p} X \rightarrow \mathbb{R} \quad g(v, v) \geq 0, \quad g(v, v)=0 \Longleftrightarrow v=0
$$

Definition 3.1.3 (Almost complex structure)
An almost complex structure is a morphism $J \in \underset{\operatorname{Vect}(X)}{\operatorname{End}}(T X)$ of vector bundles over $X$ such that $J^{2}=-\mathrm{id}_{T X}$.

Definition 3.1.4 (Integrable)
An almost-complex structure is integrable $J$ if it comes from a complex structure in the following sense: for a complex manifold $M \in \operatorname{Mfd}(\mathbb{C})$, take holomorphic coordinates $z=x+i y$ and set $J \frac{\partial}{\partial x}:=\frac{\partial}{\partial y}$ and $J \frac{\partial}{\partial y}:=-\frac{\partial}{\partial x}$.

Remark 3.1.5: A manifold $M \in \operatorname{smMfd}(\mathbb{R})$ admits an almost-complex structure iff $T M$ admits a reduction of structure group $\mathrm{GL}_{2 n}(\mathbb{R}) \rightarrow \mathrm{GL}_{n}(\mathbb{C})$.

Remark 3.1.6: Let $e \in T_{p} X$ and $e \neq 0$, then if $X$ is a surface then $\left\{e, J_{p} e\right\}$ is a basis of $T_{p} X$, where $J_{p}$ is the restriction of $J$ to $T_{p} X$ :


Exercise 3.1.7 (?)
Show that $\left\{e, J_{p} e\right\}$ are linearly independent in $T_{p} X$. In particular, $J_{p}$ is determined by a point in $\mathbb{R}^{2} \backslash\{$ the $x$-axis $\}$

Proof (That R2 admits a unique smooth structure (sketch)).
Let $\tilde{\mathbb{R}}^{2}$ be an exotic $\mathbb{R}^{2}$.

### 3.1.1 Step 1

Choose a metric on $\tilde{\mathbb{R}}^{2}$, say $g:=\sum f_{I} g_{i}$ with $g_{i}$ metrics on coordinate charts $U_{i}$ and $f_{i}$ a partition of unity.

### 3.1.2 Step 2

Find an almost complex structure on $\tilde{\mathbb{R}}^{2}$. Choosing an orientation of $\tilde{\mathbb{R}}^{2}$, the metric $g$ defines a unique almost complex structure $J_{p} e:=f \in T_{p} \tilde{\mathbb{R}}^{2}$ such that

- $g(e, e)=g(f, f)$
- $g(e, f)=0$.
- $\{e, f\}$ is an oriented basis of $T_{p} \tilde{\mathbb{R}}^{2}$

This is because after choosing $e$, there are two orthogonal vectors, but only one choice yields an oriented basis.


### 3.1.3 Step 3

We then apply a theorem:
Theorem 3.1.8(Almost-complex structures on surfaces come from complex structures).
Any almost complex structure on a surface comes from a complex structure, in the sense that there exist charts $\varphi_{i}: U_{i} \rightarrow \mathbb{C}$ such that $J$ is multiplication by $i$.

So

$$
d \varphi(J \cdot e)=i \cdot d \varphi_{i}(e),
$$

and $\left(\tilde{\mathbb{R}}^{2}, J\right)$ is a complex manifold. Since it's simply connected, the Riemann Mapping Theorem shows that it's biholomorphic to $\mathbb{D}$ or $\mathbb{C}$, both of which are diffeomorphic to $\mathbb{R}^{2}$.

Remark 3.1.9: See the Newlander-Nirenberg theorem, a result in complex geometry.

## 4 Sheaves, Bundles, Connections (Lecture 3, Wednesday, January 20)

### 4.1 Sheaves

Definition 4.1.1 (Presheaves and Sheaves)
Recall that if $X$ is a topological space, a presheaf of abelian groups $\mathcal{F}$ is an assignment $U \rightarrow \mathcal{F}(U)$ of an abelian group to every open set $U \subseteq X$ together with a restriction map $\rho_{U V}: \mathcal{F}(U) \rightarrow \mathcal{F}(V)$ for any inclusion $V \subseteq U$ of open sets. This data has to satisfying certain conditions:
a. $\mathcal{F}(\emptyset)=0$, the trivial abelian group.
b. $\rho_{U U}: \mathcal{F}(U) \rightarrow \mathcal{F}(U)=\mathrm{id}_{\mathcal{F}(U)}$
c. Compatibility if restriction is taken in steps: $U \subseteq V \subseteq W \Longrightarrow \rho_{V W} \circ \rho_{U V}=\rho_{U W}$.

We say $\mathcal{F}$ is a sheaf if additionally:
d. Given $s_{i} \in \mathcal{F}\left(U_{i}\right)$ such that $\rho_{U_{i} \cap U_{j}}\left(s_{i}\right)=\rho_{U_{i} \cap U_{j}}\left(s_{j}\right)$ implies that there exists a unique $s \in \mathcal{F}\left(\bigcup_{i} U_{i}\right)$ such that $\rho_{U_{i}}(s)=s_{i}$.


Example 4.1.2(?): Let $X$ be a topological manifold, then $\mathcal{F}:=C^{0}(-, \mathbb{R})$ the set of continuous functionals form a sheaf. We have a diagram


## Link to diagram

Property (d) holds because given sections $s_{i} \in C^{0}\left(U_{i} ; \mathbb{R}\right)$ agreeing on overlaps, so $\left.s_{i}\right|_{U_{i} \cap U_{j}}=\left.s_{j}\right|_{U_{i} \cap U_{j}}$, there exists a unique $s \in C^{0}\left(\bigcup_{i} U_{i} ; \mathbb{R}\right)$ such that $\left.s\right|_{U_{i}}=s_{i}$ for all $i$ - i.e. continuous functions glue.

Remark 4.1.3: Recall that we discussed various structures on manifolds: PL, continuous, smooth, complex-analytic, etc. We can characterize these by their sheaves of functions, which we'll denote $\mathcal{O}$. For example, $\mathcal{O}:=C^{0}(-; \mathbb{R})$ for topological manifolds, and $\mathcal{O}:=C^{\infty}(-; \mathbb{R})$ is the sheaf for smooth manifolds. Note that this also works for PL functions, since pullbacks of PL functions are again PL. For complex manifolds, we set $\mathcal{O}$ to be the sheaf of holomorphic functions.

Example 4.1.4(Locally Constant Sheaves): Let $A \in \mathrm{Ab}$ be an abelian group, then $\underline{A}$ is the sheaf defined by setting $\underline{A}(U)$ to be the locally constant functions $U \rightarrow A$. E.g. let $X \in \operatorname{Mfd}_{\text {Top }}$ be a topological manifold, then $\underline{\mathbb{R}}(U)=\mathbb{R}$ if $U$ is connected since locally constant $\Longrightarrow$ globally constant in this case.

## Warning 4.1.5

Note that the presheaf of constant functions doesn't satisfy (d)! Take $\mathbb{R}$ and a function with two different values on disjoint intervals:


Note that $\left.s_{1}\right|_{U_{1} \cap U_{2}}=\left.s_{2}\right|_{U_{1} \cap U_{2}}$ since the intersection is empty, but there is no constant function that restricts to the two different values.

### 4.2 Bundles

Remark 4.2.1: Let $\pi: \mathcal{E} \rightarrow X$ be a vector bundle, so we have local trivializations $\pi^{-1}(U) \xrightarrow{h_{u}}$ $Y^{d} \times U$ where we take either $Y=\mathbb{R}, \mathbb{C}$, such that $h_{v} \circ h_{u}^{-1}$ preserves the fibers of $\pi$ and acts linearly on each fiber of $Y \times(U \cap V)$. Define

$$
t_{U V}: U \cap V \rightarrow \mathrm{GL}_{d}(Y)
$$

where we require that $t_{U V}$ is continuous, smooth, complex-analytic, etc depending on the context.


Example 4.2.2(Bundles over $S^{1}$ ): There are two $\mathbb{R}^{1}$ bundles over $S^{1}$ :


Note that the Mobius bundle is not trivial, but can be locally trivialized.

Remark 4.2.3: We abuse notation: $\mathcal{E}$ is also a sheaf, and we write $\mathcal{E}(U)$ to be the set of sections $s: U \rightarrow \mathcal{E}$ where $s$ is continuous, smooth, holomorphic, etc where $\pi \circ s=\mathrm{id}_{U}$. I.e. a bundle is a sheaf in the sense that its sections form a sheaf.

Example 4.2.4(?): The trivial line bundle gives the sheaf $\mathcal{O}:$ maps $U \xrightarrow{s} U \times Y$ for $Y=\mathbb{R}, \mathbb{C}$ such that $\pi \circ s=\mathrm{id}$ are the same as maps $U \rightarrow Y$.

Definition 4.2.5 ( $\mathcal{O}$-modules)
An $\mathcal{O}$-module is a sheaf $\mathcal{F}$ such that $\mathcal{F}(U)$ has an action of $\mathcal{O}(U)$ compatible with restriction.

Example 4.2.6(?): If $\mathcal{E}$ is a vector bundle, then $\mathcal{E}(U)$ has a natural action of $\mathcal{O}(U)$ given by $f \curvearrowright s:=f s$, i.e. just multiplying functions.

Example 4.2.7(Non-example): The locally constant sheaf $\mathbb{R}$ is not an $\mathcal{O}$-module: there isn't natural action since the sections of $\mathcal{O}$ are generally non-constant functions, and multiplying a constant function by a non-constant function doesn't generally give back a constant function.

Remark 4.2.8: We'd like a notion of maps between sheaves:
Definition 4.2.9 (Morphisms of Sheaves)
A morphism of sheaves $\mathcal{F} \rightarrow \mathcal{G}$ is a group morphism $\varphi(U): \mathcal{F}(U) \rightarrow \mathcal{G}(U)$ for all opens $U \subseteq X$ such that the diagram involving restrictions commutes:

$$
\begin{array}{cc}
\mathcal{F}(U) \xrightarrow{\varphi(U)} & \mathcal{G}(U) \\
& \downarrow^{\rho_{U V}} \\
& \rho_{U V} \\
\mathcal{F}(V) \xrightarrow{\varphi(V)} & \mathcal{F}(V)
\end{array}
$$

Example 4.2.10(An $\mathcal{O}$-module that is not a vector bundle.): Let $X=\mathbb{R}$ and define the skyscraper sheaf at $p \in \mathbb{R}$ as

$$
\mathbb{R}_{p}(U):= \begin{cases}\mathbb{R} & p \in U \\ 0 & p \notin U\end{cases}
$$

The $\mathcal{O}(U)$-module structure is given by

$$
\begin{aligned}
\mathcal{O}(U) \times \mathcal{O}(U) & \rightarrow \mathbb{R}_{p}(U) \\
(f, s) & \mapsto f(p) s
\end{aligned}
$$

This is not a vector bundle since $\mathbb{R}_{p}(U)$ is not an infinite dimensional vector space, whereas the space of sections of a vector bundle is generally infinite dimensional (?). Alternatively, there are arbitrarily small punctured open neighborhoods of $p$ for which the sheaf makes trivial assignments.

Example 4.2.11 (of morphisms): Let $X=\mathbb{R} \in \mathrm{smMfd}$ viewed as a smooth manifold, then multiplication by $x$ induces a morphism of structure sheaves:

$$
\begin{aligned}
(x \cdot): \mathcal{O} & \rightarrow \mathcal{O} \\
s & \mapsto x \cdot s
\end{aligned}
$$

for any $x \in \mathcal{O}(U)$, noting that $x \cdot s \in \mathcal{O}(U)$ again.
Exercise 4.2.12 (The kernel of a sheaf morphism is a sheaf)
Check that $\operatorname{ker} \varphi$ is naturally a sheaf and $\operatorname{ker}(\varphi)(U)=\operatorname{ker}(\varphi(U)): \mathcal{F}(U) \rightarrow \mathcal{G}(U)$
Here the kernel is trivial, i.e. on any open $U$ we have $(x \cdot): \mathcal{O}(U) \hookrightarrow \mathcal{O}(U)$ is injective. Taking the cokernel coker $(x \cdot)$ as a presheaf, this assigns to $U$ the quotient presheaf $\mathcal{O}(U) / x \mathcal{O}(U)$, which turns out to be equal to $\mathbb{R}_{0}$. So $\mathcal{O} \rightarrow \mathbb{R}_{0}$ by restricting to the value at 0 , and there is an exact sequence

$$
0 \rightarrow \mathcal{O} \xrightarrow{(x \cdot)} \mathcal{O} \rightarrow \mathbb{R}_{0} \rightarrow 0
$$

This is one reason sheaves are better than vector bundles: the category is closed under taking quotients, whereas quotients of vector bundles may not be vector bundles.

## 5 Lecture 4 (Friday, January 22)

### 5.1 The Exponential Exact Sequence

Remark 5.1.1: Let $X=\mathbb{C}$ and consider $\mathcal{O}$ the sheaf of holomorphic functions and $\mathcal{O}^{\times}$the sheaf of nonvanishing holomorphic functions. The former is a vector bundle and the latter is a sheaf of abelian groups. There is a map exp : $\mathcal{O} \rightarrow \mathcal{O}^{\times}$, the exponential map, which is the data $\exp (U): \mathcal{O}(U) \rightarrow \mathcal{O}^{\times}(U)$ on every open $U$ given by $f \mapsto e^{f}$. There is a kernel sheaf $2 \pi i \underline{Z}$, and we get an exact sequence

$$
0 \rightarrow 2 \pi i \underline{\mathbb{Z}} \rightarrow \mathcal{O} \xrightarrow{\exp } \mathcal{O}^{\times} \rightarrow \operatorname{coker}(\exp ) \rightarrow 0 .
$$

## Question 5.1.2

What is the cokernel sheaf here?

Remark 5.1.3: Let $U$ be a contractible open set, then we can identify $\mathcal{O}^{\times}(U) / \exp \left(\mathcal{O}^{\times}(U)\right)=1$.


Any $f \in \mathcal{O}^{\times}(U)$ has a logarithm, say by taking a branch cut, since $\pi_{1}(U)=0 \Longrightarrow \log f$ has an analytic continuation. Consider the annulus $U$ and the function $z \in \mathcal{O}^{\times}(U)$, then $z \notin \exp (\mathcal{O}(U))-$ if $z=e^{f}$ then $f=\log (z)$, but $\log (z)$ has monodromy on $U$ :


Thus on any sufficiently small open set, $\operatorname{coker}(\exp )=1$. This is only a presheaf: there exists an open cover of the annulus for which $\left.z\right|_{U_{i}}$, and so the naive cokernel doesn't define a sheaf. This is because we have a locally trivial section which glues to $z$, which is nontrivial.

Exercise 5.1.4 (Fixing the sheaf cokernel)
Redefine the cokernel so that it is a sheaf. Hint: look at sheafification, which has the defining property

$$
\underset{\substack{\mathrm{Sh} \\ \mathrm{pre}}}{\operatorname{Hom}}\left(\mathcal{G}, \mathcal{F}^{\mathrm{Sh}}\right)=\underset{\mathrm{Sh}}{\operatorname{Hom}}\left(\mathcal{G}, \mathcal{F}^{\mathrm{Sh}}\right)
$$

for any sheaf $\mathcal{G}$.

### 5.2 Global Sections

Definition 5.2.1 (Global Sections Sheaf)
The global sections sheaf of $\mathcal{F}$ on $X$ is given by $H^{0}(X ; \mathcal{F})=\mathcal{F}(X)$.

## Example 5.2.2(?):

- $C^{\infty}(X)=H^{0}\left(X, C^{\infty}\right)$ are the smooth functions on $X$
- $V F(X)=H^{0}(X ; T)$ are the smooth vector fields on $X$ for $T$ the tangent bundle
- If $X$ is a complex manifold then $\mathcal{O}(X)=H^{0}(X ; \mathcal{O})$ are the globally holomorphic functions on $X$.
- $H^{0}(X ; \mathbb{Z})=\underline{\mathbb{Z}}(X)$ are ??

Remark 5.2.3: Given vector bundles $V, W$, we have constructions $V \oplus W, V \otimes W, V^{\vee}, \operatorname{Hom}(V, W)=$ $V^{\vee} \otimes W, \operatorname{Sym}^{n} V, \bigwedge^{p} V$, and so on. Some of these work directly for sheaves:

- $\mathcal{F} \oplus \mathcal{G}(U):=\mathcal{F}(U) \oplus \mathcal{G}(U)$
- For tensors, duals, and homs $\mathscr{H} \mathrm{Om}(V, W)$ we only get presheaves, so we need to sheafify.


## § Warning 5.2.4

$\operatorname{Hom}(V, W)$ will denote the global homomorphisms $\mathscr{H} \mathrm{Om}(V, W)(X)$, which is a sheaf.
Example 5.2.5(?): Let $X^{n} \in \mathrm{Mfd}_{\mathrm{sm}}$ and let $\Omega^{p}$ be the sheaf of smooth $p$-forms, i.e $\bigwedge^{p} T^{\vee}$, i.e. $\Omega^{p}(U)$ are the smooth $p$ forms on $U$, which are locally of the form $\sum f_{i_{1}, \cdots, i_{p}}\left(x_{1}, \cdots, x_{n}\right) d x_{i_{1}} \wedge d x_{i_{2}} \wedge \cdots d x_{i_{p}}$ where the $f_{i_{1}, \cdots, i_{p}}$ are smooth functions.

Example 5.2.6(Sub-example): Take $X=S^{1}$, writing this as $\mathbb{R} / \mathbb{Z}$, we have $\Omega^{1}(X) \ni d x$. There are two coordinate charts which differ by a translation on their overlaps, and $d x(x+c)=d x$ for $c$ a constant:


Exercise 5.2.7 (?)
Check that on a torus, $d x_{i}$ is a well-defined 1-form.

Remark 5.2.8: Note that there is a map $d: \Omega^{p} \rightarrow \Omega^{p+1}$ where $\omega \mapsto d \omega$.

## $\triangle$ Warning 5.2.9

$d$ is not a map of $\mathcal{O}$-modules: $d(f \cdot \omega)=f \cdot \omega+d f \wedge \omega$, where the latter is a correction term. In particular, it is not a map of vector bundles, but is a map of sheaves of abelian groups since $d\left(\omega_{1}+\omega_{2}\right)=d\left(\omega_{1}\right)+d\left(\omega_{2}\right)$, making $d$ a sheaf morphism.

Remark 5.2.10: Let $X \in \mathrm{Mfd}_{\mathbb{C}}$, we'll use the fact that $T X$ is complex-linear and thus a $\mathbb{C}$-vector bundle.


Remark 5.2.11(Subtlety 1): Note that $\Omega^{p}$ for complex manifolds is $\bigwedge^{p} T^{\vee}$, and so if we want to view $X \in \mathrm{Mfd}_{\mathbb{R}}$ we'll write $X_{\mathbb{R}} . T X_{\mathbb{R}}$ is then a real vector bundle of rank $2 n$.

Remark 5.2.12(Subtlety 2): $\Omega^{p}$ will denote holomorphic p-forms, i.e. local expressions of the form

$$
\sum f_{I}\left(z_{1}, \cdots, z_{n}\right) \bigwedge d z_{I}
$$

For example, $e^{z} d z \in \Omega^{1}(\mathbb{C})$ but $z \bar{z} d z$ is not, where $d z=d x+i d y$. We'll use a different notation when we allow the $f_{I}$ to just be smooth: $A^{p, 0}$, the sheaf of $(p, 0)$-forms. Then $z \bar{z} d z \in A^{1,0}$.

Remark 5.2.13: Note that $T^{\vee} X_{\mathbb{R}} \otimes_{\mathbb{C}}=A^{1,0} \oplus A^{0,1}$ since there is a unique decomposition $\omega=$ $f d z+g d \bar{z}$ where $f, g$ are smooth. Then $\Omega^{d} X_{\mathbb{R}} \otimes_{\mathbb{R}} \mathbb{C}=\bigoplus_{p+q=d} A^{p, q}$. Note that $\Omega_{\mathrm{sm}}^{p} \neq A^{p, q}$ and these are really quite different: the former are more like holomorphic bundles, and the latter smooth. Moreover $\operatorname{dim} \Omega^{p}(X)<\infty$, whereas $\Omega_{\mathrm{sm}}^{1}$ is infinite-dimensional.

## 6 Principal $G$-Bundles and Connections (Monday, January 25)

Definition 6.0.1 (Principal Bundles)
Let $G$ be a (possibly disconnected) Lie group. Then a principal $G$-bundle $\pi: P \rightarrow X$ is a space admitting local trivializations $h_{u}: \pi^{-1}(U) \rightarrow G \times U$ such that the transition functions are given by left multiplication by a continuous function $t_{U V}: U \cap V \rightarrow G$.


Remark 6.0.2: Setup: we'll consider $T X$ for $X \in \mathrm{Mfd}_{\mathrm{Sm}}$, and let $g$ be a metric on the tangent bundle given by

$$
g_{p}: T_{p} X^{\otimes 2} \rightarrow \mathbb{R}
$$

a symmetric bilinear form with $g_{p}(u, v) \geq 0$ with equality if and only if $v=0$.

Definition 6.0.3 (The Frame Bundle)
Define $\underset{p}{\operatorname{Frame}}(X):=\left\{\right.$ bases of $\left.T_{p} X\right\}$, and $\operatorname{Frame}(X):=\bigcup_{p \in X} \underset{p}{\operatorname{Frame}}(X)$.

Remark 6.0.4: More generally, $\operatorname{Frame}(\mathcal{E})$ can be defined for any vector bundle $\mathcal{E}$, so $\operatorname{Frame}(X):=$ $\operatorname{Frame}(T X)$. Note that $\operatorname{Frame}(X)$ is a principal $\mathrm{GL}_{n}(\mathbb{R})$-bundle where $n:=\operatorname{rank}(\mathcal{E})$. This follows from the fact that the transition functions are fiberwise in $\mathrm{GL}_{n}(\mathbb{R})$, so the transition functions are given by left-multiplication by matrices.

Remark 6.0.5(Important): A principal $G$-bundle admits a $G$-action where $G$ acts by right multiplication:

$$
\begin{aligned}
P & \times G \rightarrow P \\
((g, x), h) & \mapsto(g h, x) .
\end{aligned}
$$

This is necessary for compatibility on overlaps. Key point: the actions of left and right multiplication commute.

Definition 6.0.6 (Orthogonal Frame Bundle)
The orthogonal frame bundle of a vector bundle $\mathcal{E}$ equipped with a metric $g$ is defined as $\underset{p}{\operatorname{OFrame}}(\mathcal{E}):=\left\{\right.$ orthonormal bases of $\left.\mathcal{E}_{p}\right\}$, also written $O_{r}(\mathbb{R})$ where $r:=\operatorname{rank}(\mathcal{E})$.

Remark 6.0.7: The fibers $P_{x} \rightarrow\{x\}$ of a principal $G$-bundle are naturally torsors over $G$, i.e. a set with a free transitive $G$-action.

Definition 6.0.8 (Hermitian metric)
Let $\mathcal{E} \rightarrow X$ be a complex vector bundle. Then a Hermitian metric is a hermitian form on every fiber, i.e.

$$
h_{p}: \mathcal{E}_{p} \times \overline{\mathcal{E}_{p}} \rightarrow \mathbb{C}
$$

where $h_{p}(v, \bar{v}) \geq 0$ with equality if and only if $v=0$. Here we define $\overline{\mathcal{E}_{p}}$ as the fiber of the complex vector bundle $\overline{\mathcal{E}}$ whose transition functions are given by the complex conjugates of those from $\mathcal{E}$.

Remark 6.0.9: Note that $\mathcal{E}, \overline{\mathcal{E}}$ are genuinely different as complex bundles. There is a conjugatelinear map given by conjugation, i.e. $L(c v)=\bar{c} L(v)$, where the canonical example is

$$
\begin{aligned}
\mathbb{C}^{n} & \rightarrow \mathbb{C}^{n} \\
\left(z_{1}, \cdots, z_{n}\right) & \mapsto\left(\overline{z_{1}}, \cdots, \overline{z_{n}}\right)
\end{aligned}
$$

Definition 6.0.10 (Unitary Frame Bundle)
We define the unitary frame bundle $\operatorname{UFrame}(\mathcal{E}):=\bigcup_{p} \operatorname{UFrame}(\mathcal{E})_{p}$, where at each point this is given by the set of orthogonal frames of $\mathcal{E}_{p}$ given by $\left(e_{1}, \cdots, e_{n}\right)$ where $h\left(e_{i}, \overline{e_{j}}\right)=\delta_{i j}$.

Remark 6.0.11: This is a principal $G$-bundle for $G=U_{r}(\mathbb{C})$, the invertible matrices $A_{/ \mathbb{C}}$ satisfy $A \bar{A}^{t}=\mathrm{id}$.

Example 6.0.12 (of more principal bundles): For $G=\mathbb{Z} / 2 \mathbb{Z}$ and $X=S^{1}$, the Möbius band is a principal $G$-bundle:


Example 6.0.13(more principal bundles): For $G=\mathbb{Z} / 2 \mathbb{Z}$, for any (possibly non-oriented) manifold $X$ there is an orientation principal bundle $P$ which is locally a set of orientations on $U$, i.e.

$$
P:=\left\{(x, O) \mid x \in X, O \text { is an orientation of } T_{p} X\right\} .
$$

Note that $P$ is an oriented manifold, $P \rightarrow X$ is a local isomorphism, and has a canonical orientation. (?) This can also be written as $P=\operatorname{Frame}(X) / \mathrm{GL}_{n}^{+}(\mathbb{R})$, since an orientation can be specified by a choice of $n$ linearly independent vectors where we identify any two sets that differ by a matrix of positive determinant.

Definition 6.0.14 (Associated Bundles)
Let $P \rightarrow X$ be a principal $G$-bundle and let $G \rightarrow \mathrm{GL}(V)$ be a continuous representation. The associated bundle is defined as

$$
P \times_{G} V=\{(p, v) \mid p \in P, v \in V\} / \sim \quad \text { where }(p, v) \sim\left(p g, g^{-1} v\right)
$$

which is well-defined since there is a right action on the first component and a left action on the second.

Example 6.0.15(?): Note that $\operatorname{Frame}(\mathcal{E})$ is a $\mathrm{GL}_{r}(\mathbb{R})$-bundle and the map $\mathrm{GL}_{r}(\mathbb{R}) \xrightarrow{\text { id }} \mathrm{GL}\left(\mathbb{R}^{r}\right)$ is
a representation. At every fiber, we have $G \times{ }_{G} V=(p, v) / \sim$ where there is a unique representative of this equivalence class given by $(e, p v)$. So $P \times_{G} V_{p} \rightarrow\{p\} \cong V_{x}$.

Exercise 6.0.16(?)
Show that $\operatorname{Frame}(\mathcal{E}) \times{ }_{\mathrm{GL}_{r}(\mathbb{R})} \mathbb{R}^{r} \cong \mathcal{E}$. This follows from the fact that the transition functions of $P \times_{G} V$ are given by left multiplication of $t_{U V}: U \cap V \rightarrow G$, and so by the equivalence relation, $\operatorname{im} t_{U V} \in \mathrm{GL}(V)$.

Remark 6.0.17: Suppose that $M^{3}$ is an oriented Riemannian 3-manifold. Them $T M \rightarrow \operatorname{Frame}(M)$ which is a principal $\mathrm{SO}(3)$-bundle. The universal cover is the double cover $\mathrm{SU}(2) \rightarrow \mathrm{SO}(3)$, so can the transition functions be lifted? This shows up for spin structures, and we can get a $\mathbb{C}^{2}$ bundle out of this.

## 7 Wednesday, January 27

### 7.1 Bundles and Connections

Definition 7.1.1 (Connections)
Let $\mathcal{E} \rightarrow X$ be a vector bundle, then a connection on $\mathcal{E}$ is a map of sheaves of abelian groups

$$
\nabla: \mathcal{E} \rightarrow \mathcal{E} \otimes \Omega_{X}^{1}
$$

satisfying the Leibniz rule:

$$
\nabla(f s)=f \nabla s+s \otimes d s
$$

for all opens $U$ with $f \in \mathcal{O}(U)$ and $s \in \mathcal{E}(U)$. Note that this works in the category of complex manifolds, in which case $\nabla$ is referred to as a holomorphic connection.

Remark 7.1.2: A connection $\nabla$ induces a map

$$
\begin{aligned}
\tilde{\nabla}: \mathcal{E} \otimes \Omega^{p} & \rightarrow \mathcal{E} \otimes \Omega^{p+1} \\
s \otimes \omega & \mapsto \nabla s \wedge w+s \otimes d \omega .
\end{aligned}
$$

where $\wedge: \Omega^{p} \otimes \Omega^{1} \rightarrow \Omega^{p+1}$. The standard example is

$$
\begin{aligned}
d: \mathcal{O} & \rightarrow \Omega^{1} \\
f & \mapsto d f .
\end{aligned}
$$

where the induced map is the usual de Rham differential.
Exercise 7.1.3 (?)

Prove that the curvature of $\nabla$, i.e. the map

$$
F_{\nabla}:=\nabla \circ \nabla: \mathcal{E} \rightarrow \mathcal{E} \otimes \Omega^{2}
$$

is $\mathcal{O}$-linear, so $F_{\nabla}(f s)=f \nabla \circ \nabla(s)$. Use the fact that $\nabla s \in \mathcal{E} \otimes \Omega^{1}$ and $\omega \in \Omega^{p}$ and so $\nabla s \otimes \omega \in \mathcal{E} \Omega^{1} \otimes \Omega^{p}$ and thus reassociating the tensor product yields $\nabla s \wedge \omega \in \mathcal{E} \otimes \Omega^{p+1}$.

Remark 7.1.4: Why is this called a connection?


This gives us a way to transport $v \in \mathcal{E}_{p}$ over a path $\gamma$ in the base, and $\nabla$ provides a differential equation (a flow equation) to solve that lifts this path. Solving this is referred to as parallel transport. This works by pairing $\gamma^{\prime}(t) \in T_{\gamma(t)} X$ with $\Omega^{1}$, yielding $\nabla s=\left(\gamma^{\prime}(t)\right)=s(\gamma(t))$ which are sections of $\gamma$.

Note that taking a different path yields an endpoint in the same fiber but potentially at a different point, and $F_{\nabla}=0$ if and only if the parallel transport from $p$ to $q$ depends only on the homotopy class of $\gamma$.

Note: this works for any bundle, so can become confusing in Riemannian geometry when all of the bundles taken are tangent bundles!

Example 7.1.5 (A classic example): The Levi-Cevita connection $\nabla^{L C}$ on $T X$, which depends on a metric $g$. Taking $X=S^{2}$ and $g$ is the round metric, there is nonzero curvature:


In general, every such transport will be rotation by some vector, and the angle is given by the area of the enclosed region.

Definition 7.1.6 (Flat Connection and Flat Sections)
A connection is flat if $F_{\nabla}=0$. A section $s \in \mathcal{E}(U)$ is flat if it is given by

$$
L(U):=\{s \in \mathcal{E}(U) \mid \nabla s=0\}
$$

Exercise 7.1.7 (?)
Show that if $\nabla$ is flat then $L$ is a local system: a sheaf that assigns to any sufficiently small open set a vector space of fixed dimension. An example is the constant sheaf $\underline{\mathbb{C}^{d}}$. Furthermore $\operatorname{rank}(L)=\operatorname{rank}(\mathcal{E})$.

Remark 7.1.8: Given a local system, we can construct a vector bundle whose transition functions are the same as those of the local system, e.g. for vector bundles this is a fixed matrix, and in general these will be constant transition functions. Equivalently, we can take $L \otimes_{\mathbb{R}} \mathcal{O}$, and $L \otimes 1$ form flat sections of a connection.

### 7.2 Sheaf Cohomology

Definition 7.2.1 (Čech complex)
Let $\mathcal{F}$ be a sheaf of abelian groups on a topological space $X$, and let $\mathfrak{U}:=\left\{U_{i}\right\} \rightrightarrows X$ be an open cover of $X$. Let $U_{i_{1}, \cdots, i_{p}}:=U_{i_{1}} \cap U_{i_{2}} \cap \cdots \cap U_{i_{p}}$. Then the Čech Complex is defined as

$$
C_{\mathfrak{U}}^{p}(X, \mathcal{F}):=\prod_{i_{1}<\cdots<i_{p}} \mathcal{F}\left(U_{i_{1}, \cdots, i_{p}}\right)
$$

with a differential

$$
\begin{aligned}
\partial^{p}: C_{\mathfrak{U}}^{p}(X, \mathcal{F}) & \rightarrow C_{\mathfrak{U}}^{p+1}(X \mathcal{F}) \\
\sigma & \mapsto(\partial \sigma)_{i_{0}, \cdots, i_{p}}:=\left.\prod_{j}(-1)^{j} \sigma_{i_{0}, \cdots, \widehat{i_{j}}, \cdots, i_{p}}\right|_{U_{i_{0}}, \cdots, i_{p}}
\end{aligned}
$$

where we've defined this just on one given term in the product, i.e. a $p$-fold intersection.
Exercise 7.2.2 (?)
Check that $\partial^{2}=0$.

Remark 7.2.3: The Čech cohomology $H_{\mathfrak{U}}^{p}(X, \mathcal{F})$ with respect to the cover $\mathfrak{U}$ is defined as ker $\partial^{p} / \operatorname{im} \partial^{p-1}$. It is a difficult theorem, but we write $H^{p}(X, \mathcal{F})$ for the Čech cohomology for any sufficiently refined open cover when $X$ is assumed paracompact.

Example 7.2.4(?): Consider $S^{1}$ and the constant sheaf $\underline{\mathbb{Z}}$ :

ere we have

$$
C^{0}\left(S^{1}, \underline{\mathbb{Z}}\right)=\underline{\mathbb{Z}}\left(U_{1}\right) \oplus \underline{\mathbb{Z}}\left(U_{2}\right)=\underline{\mathbb{Z}} \oplus \underline{\mathbb{Z}}
$$

and

$$
C^{1}\left(S^{1}, \mathbb{Z}\right)=\bigoplus_{\substack{\text { double } \\ \text { intersections }}} \underline{\mathbb{Z}}\left(U_{i j}\right) \underline{\mathbb{Z}}\left(U_{12}\right)=\underline{\mathbb{Z}}\left(U_{1} \cap U_{2}\right)=\underline{\mathbb{Z}} \oplus \underline{\mathbb{Z}}
$$

We then get

$$
\begin{aligned}
C^{0}\left(S^{1}, \underline{\mathbb{Z}}\right) & \xrightarrow{\partial} C^{1}\left(S^{1}, \underline{\mathbb{Z}}\right) \\
\mathbb{Z} \oplus \mathbb{Z} & \rightarrow \mathbb{Z} \oplus \mathbb{Z} \\
(a, b) & \mapsto(a-b, a-b),
\end{aligned}
$$

Which yields $H^{*}\left(S^{1}, \underline{\mathbb{Z}}\right)=[\mathbb{Z}, \mathbb{Z}, 0, \cdots]$.

## 8 Sheaf Cohomology (Friday, January 29)

Last time: we defined the Čech complex $C_{\mathfrak{U}}^{p}(X, \mathcal{F}):=\prod_{i_{1}, \cdots, i_{p}} \mathcal{F}\left(U_{i_{1}} \cap \cdots \cap U_{i_{p}}\right)$ for $\mathfrak{U}:=\left\{U_{i}\right\}$ is an open cover of $X$ and $F$ is a sheaf of abelian groups.

## Fact 8.0.1

If $\mathfrak{U}$ is a sufficiently fine cover then $H_{\mathfrak{U}}^{p}(X, \mathcal{F})$ is independent of $\mathfrak{U}$, and we call this $H^{p}(X ; \mathcal{F})$.

Remark 8.0.2: Recall that we computed $H^{p}\left(S^{1}, \underline{\mathbb{Z}}=[\mathbb{Z}, \mathbb{Z}, 0, \cdots]\right.$.

Theorem 8.0.3(When sheaf cohomology is isomorphic to singular cohomology).
Let $X$ be a paracompact and locally contractible topological space. Then $H^{p}(X, \underline{Z}) \cong$ $H_{\text {Sing }}^{p}(X, \underline{\mathbb{Z}})$. This will also hold more generally with $\underline{\mathbb{Z}}$ replaced by $\underline{A}$ for any $A \in \mathrm{Ab}$.

Definition 8.0.4 (Acyclic Sheaves)
We say $\mathcal{F}$ is acyclic on $X$ if $H^{>0}(X ; \mathcal{F})=0$.

Remark 8.0.5: How to visualize when $H^{1}(X ; \mathcal{F})=0$ :


On the intersections, we have $\operatorname{im} \partial^{0}=\left\{\left(s_{i}-s_{j}\right)_{i j} \mid s_{i} \in \mathcal{F}\left(U_{i}\right)\right\}$, which are cocycles. We have $C^{1}(X ; \mathcal{F})$ are collections of sections of $\mathcal{F}$ on every double overlap. We can check that ker $\partial^{1}=$ $\left\{\left(s_{i j}\right) \mid s_{i j}-s_{i k}+s_{j k}=0\right\}$, which is the cocycle condition. From the exercise from last class, $\partial^{2}=0$.

Theorem 8.0.6((Important!)).

Let $X$ be a paracompact Hausdorff space and let

$$
0 \rightarrow \mathcal{F}_{1} \xrightarrow{\varphi} \mathcal{F}_{2} \rightarrow \mathcal{F}_{3} \rightarrow 0
$$

be a SES of sheaves of abelian groups, i.e. $\mathcal{F}_{3}=\operatorname{coker}(\varphi)$ and $\varphi$ is injective. Then there is a LES in cohomology:


Example 8.0.7(?): For $X$ a manifold, we can define a map and its cokernel sheaf:

$$
0 \rightarrow \underline{\mathbb{Z}} \stackrel{2}{\rightarrow} \underline{\mathbb{Z}} \rightarrow \underline{\mathbb{Z}} / 2 \mathbb{Z} \rightarrow 0 .
$$

Using that cohomology of constant sheaves reduces to singular cohomology, we obtain a LES in homology:


## Corollary 8.0.8 (of theorem).

Suppose $0 \rightarrow \mathcal{F} \rightarrow I_{0} \xrightarrow{d_{0}} I_{1} \xrightarrow{d_{1}} I_{2} \xrightarrow{d_{2}} \cdots$ is an exact sequence of sheaves, so on any sufficiently small set kernels equal images., and suppose $I_{n}$ is acyclic for all $n \geq 0$. This is referred to as an acyclic resolution. Then the homology can be computed at $H^{p}(X ; \mathcal{F})=\operatorname{ker}\left(I_{p}(X) \rightarrow\right.$ $\left.I_{p+1}(X)\right) / \mathrm{im}\left(I_{p-1}(X) \rightarrow I_{p}(X)\right)$.

Note that locally having kernels equal images is different than satisfying this globally!

## Proof (of corollary).

This is a formal consequence of the existence of the LES. We can split the LES into a collection of SESs of sheaves:

$$
\begin{aligned}
0 \rightarrow \mathcal{F} \rightarrow I_{0} \xrightarrow{d_{0}} \operatorname{im}\left(d_{0}\right) \rightarrow 0 & \operatorname{im}\left(d_{0}\right)=\operatorname{ker}\left(d_{1}\right) \\
0 \rightarrow \operatorname{ker}\left(d_{1}\right) \hookrightarrow I_{1} \rightarrow I_{1} / \operatorname{ker}\left(d_{1}\right)=\operatorname{im}\left(d_{1}\right) & \operatorname{im}\left(d_{1}\right)=\operatorname{ker}\left(d_{2}\right)
\end{aligned}
$$

Note that these are all exact sheaves, and thus only true on small sets. So take the associated LESs. For the SES involving $I_{0}$, we obtain:


The middle entries vanish since $I_{*}$ was assumed acyclic, and so we obtain $H^{p}(\mathcal{F}) \cong$ $H^{p-1}\left(\operatorname{im} d_{0}\right) \cong H^{p-1}\left(\operatorname{ker} d_{1}\right)$. Now taking the LES associated to $I_{1}$, we get $H^{p-1}\left(\operatorname{ker} d_{1}\right) \cong$ $H^{p-2}\left(\operatorname{im} d_{1}\right)$. Continuing this inductively, these are all isomorphic to $H^{p}(\mathcal{F}) \cong$ $H^{0}\left(\operatorname{ker} d_{p}\right) / d_{p-1}\left(H^{0}\left(I_{p-1}\right)\right)$ after the $p$ th step.

Corollary 8.0.9 (of the previous corollary).
Suppose $\mathfrak{U} \rightrightarrows X$, then if $\mathcal{F}$ is acyclic on each $U_{i_{1}, \cdots, i_{p}}$, then $\mathfrak{U}$ is sufficiently fine to compute Čech cohomology, and $H_{\mathfrak{U}}^{p}(X ; \mathcal{F}) \cong H^{p}(X ; \mathcal{F})$.

## Proof (?).

See notes.

## Corollary 8.0.10 (of corollary).

Let $X \in \mathrm{Mfd}_{\mathrm{sm}}$, then $H^{p}(X, \mathbb{R})=H_{\mathrm{dR}}^{p}(X ; R R)$.

## Proof (?).

Idea: construct an acyclic resolution of the sheaf $\mathbb{R}$ on $M$. The following exact sequence works:

$$
0 \rightarrow \mathbb{R} \rightarrow \mathcal{O} \xrightarrow{d} \Omega^{1} \xrightarrow{d} \Omega^{2} \rightarrow \cdots .
$$

So we start with locally constant functions, then smooth functions, then smooth 1-forms, and so on. This is an exact sequence of sheaves, but importantly, not exact on the total space. To check this, it suffices to show that $\operatorname{ker} d^{p}=\operatorname{im} d^{p-1}$ on any contractible coordinate chart. In other words, we want to show that if $d \omega=0$ for $\omega \in \Omega^{p}\left(\mathbb{R}^{n}\right)$ then $\omega=d \alpha$ for some $\alpha \in \Omega^{p-1}\left(\mathbb{R}^{n}\right)$. This is true by integration! Using the previous corollary, $H^{p}(X ; \mathbb{R})=$ $\operatorname{ker}\left(\Omega^{p}(X) \xrightarrow{d} \Omega^{p+1}(X)\right) / \operatorname{im}\left(\Omega^{p-1}(X) \xrightarrow{d} \Omega^{p}(X)\right)$.

Check Hartshorne to see how injective resolutions line up with derived functors!

## 9 Monday, February 01

Remark 9.0.1: Last time $\underline{\mathbb{R}}$ on a manifold $M$ has a resolution by vector bundles:

$$
0 \rightarrow \mathbb{R} \hookrightarrow \Omega^{1} \xrightarrow{d} \Omega^{2} \xrightarrow{d} \cdots .
$$

This is an exact sequence of sheaves of any smooth manifold, since locally $d \omega=0 \Longrightarrow \omega=d \alpha$ (by the Poincaré $d$-lemma). We also want to know that $\Omega^{k}$ is an acyclic sheaf on a smooth manifold.

## Exercise 9.0.2 (?)

Let $X \in T o p$ and $\mathcal{F} \in \operatorname{Sh}(\mathrm{Ab})_{/ X}$. We say $\mathcal{F}$ is flasque if and only if for all $U \supseteq V$ the map $\mathcal{F}(U) \xrightarrow{\rho_{U V}} \mathcal{F}(V)$ is surjective. Show that $\mathcal{F}$ is acyclic, i.e. $H^{i}(X ; \mathcal{F})=0$. This can also be generalized with a POU.

Example 9.0.3(?): The function $1 / x \in \mathcal{O}(\mathbb{R} \backslash\{0\})$, but doesn't extend to a continuous map on $\mathbb{R}$. So the restriction map is not surjective.

Remark 9.0.4: Any vector bundle on a smooth manifold is acyclic. Using the fact that $\Omega^{k}$ is acyclic and the above resolution of $\underline{\mathbb{R}}$, we can write $H^{k}(X ; \mathbb{R})=\operatorname{ker}\left(d_{k}\right) / \operatorname{im} d_{k-1}:=H_{d R}^{k}(X ; \mathbb{R})$.

Remark 9.0.5: Now letting $X \in \operatorname{Mfd}_{\mathbb{C}}$, recalling that $\Omega^{p}$ was the sheaf of holomorphic $p$-forms. Locally these are of the form $\sum_{|I|=p} f_{I}(\mathbf{z}) d z^{I}$ where $f_{I}(\mathbf{z})$ is holomorphic. There is a resolution

$$
0 \rightarrow \Omega^{p} \rightarrow A^{p, 0}
$$

where in $A^{p, 0}$ we allowed also $f_{I}$ are smooth. These are the same as bundles, but we view sections differently. The first allows only holomorphic sections, whereas the latter allows smooth sections. What can you apply to a smooth ( $p, 0$ ) form to check if it's holomorphic?

Example 9.0.6(?): For $p=0$, we have

$$
0 \rightarrow \mathcal{O} \rightarrow A^{0,0}
$$

where we have the sheaf of holomorphic functions mapping to the sheaf of smooth functions. We essentially want a version of checking the Cauchy-Riemann equations.

Definition 9.0.7 ( $\partial$ and $\bar{\partial}$ operators)
Let $\omega \in A^{p, q}(X)$ where

$$
d \omega=\sum \frac{\partial f_{I}}{\partial z_{j}} d z^{j} \wedge d z^{I} \wedge d \bar{z}^{J}+\sum_{j} \frac{\partial f_{I}}{\partial \bar{z}_{j}} d \bar{z}^{j} \wedge d z^{I} d \bar{z}^{J}:=\partial+\bar{\partial}
$$

with $|I|=p,|J|=q$.
Example 9.0.8(?): The function $f(z)=z \bar{z} \in A^{0,0}(\mathbb{C})$ is smooth, and $d f=\bar{z} d z+z d \bar{z}$. This can be checked by writing $z^{j}=x^{j}+i y^{j}$ and $\bar{z}^{j}=x^{j}-i y_{j}$, and $\frac{\partial}{\partial \bar{z}} g=0$ if and only if $g$ is holomorphic. Here we get $\partial \omega \in A^{p+1, q}(X)$ and $\bar{\partial} \in A^{p, q+1}(X)$, and we can write $d(z \bar{z})=\partial(z \bar{z})+\bar{\partial}(z \bar{z})$.

Definition 9.0.9 (Cauchy-Riemann Equations)
Recall the Cauchy-Riemann equations: $\omega$ is a holomorphic $(p, 0)$-form on $\mathbb{C}^{n}$ if and only if $\bar{\partial} \omega=0$.

Remark 9.0.10: Thus to extend the previous resolution, we should take

$$
0 \rightarrow \Omega^{p} \hookrightarrow A^{p, 0} \xrightarrow{\bar{\sigma}} A^{p, 1} \xrightarrow{\bar{\sigma}} A^{p, 2} \rightarrow \cdots .
$$

The fact that this is exact is called the Poincaré $\bar{\partial}$-lemma.
Remark 9.0.11: There are no bump functions in the holomorphic world, and since $\Omega^{p}$ is a holomorphic bundle, it may not be acyclic. However, the $A^{p, q}$ are acyclic (since they are smooth vector bundles and thus admit POUs), and we obtain

$$
H^{q}\left(X ; \Omega^{p}\right)=\operatorname{ker}\left(\bar{\partial}_{q}\right) / \operatorname{im}\left(\bar{\partial}_{q-1}\right) .
$$

Note the similarity to $H_{\mathrm{dR}}$, using $\bar{\partial}$ instead of $d$. This is called Dolbeault cohomology, and yields invariants of complex manifolds: the Hodge numbers $h^{p, q}(X):=\operatorname{dim}_{\mathbb{C}} H^{q}\left(X ; \Omega^{p}\right)$. These are analogies:

| Smooth | Complex |
| :--- | :--- |
| $\mathbb{R}$ | $\Omega^{p}$ |
| $\Omega^{k}$ | $A^{p, q}$ |
| Betti numbers $\beta_{k}$ | Hodge numbers $h^{p, q}$ |

Note the slight overloading of terminology here!

## Theorem 9.0.12 (Properties of Singular Cohomology).

Let $X \in \mathrm{Top}$, then $H_{\text {Sing }}^{i}(X ; \mathbb{Z})$ satisfies the following properties:

- Functoriality: given $f \in \underset{\text { Top }}{\operatorname{Hom}}(X, Y)$, there is a pullback $f^{*}: H^{i}(Y ; \mathbb{Z}) \rightarrow H^{i}(X ; \mathbb{Z})$.
- The cap product: a pairing

$$
\begin{aligned}
& H^{i}(X ; \mathbb{Z}) \otimes_{\mathbb{Z}} H_{j}(X ; \mathbb{Z}) \rightarrow H_{j-i}(X ; \mathbb{Z}) \\
&\left.\varphi \otimes \sigma \mapsto \varphi\left(\left.\sigma\right|_{\Delta_{0, \cdots, j}}\right) \sigma\right|_{\Delta_{i, \cdots, j}}
\end{aligned}
$$

This makes $H_{*}$ a module over $H^{*}$.

- There is a ring structure induced by the cup product:

$$
H^{i}(X ; \mathbb{R}) \times H^{j}(X ; \mathbb{R}) \rightarrow H^{i+j}(X ; \mathbb{R}) \quad \alpha \cup \beta=(-1)^{i j} \beta \cup \alpha
$$

- Poincaré Duality: If $X$ is an oriented manifold, there exists a fundamental class $[X] \in$ $H_{n}(X ; \mathbb{Z}) \cong \mathbb{Z}$ and $(-) \cap X: H^{i} \rightarrow H_{n-i}$ is an isomorphism.

Remark 9.0.13: Let $M \subset X$ be a submanifold where $X$ is a smooth oriented $n$-manifold. Then $M \hookrightarrow X$ induces a pushforward $H_{n}(M ; \mathbb{Z}) \xrightarrow{\iota_{*}} H_{n}(X ; \mathbb{Z})$ where $\sigma \mapsto \iota \circ \sigma$. Using Poincaré duality, we'll identify $H_{\operatorname{dim} M}(X ; \mathbb{Z}) \rightarrow H^{\operatorname{codim} M}(X ; \mathbb{Z})$ and identify $[M]=P D\left(\iota_{*}([M])\right)$. In this case, if $M \pitchfork N$ then $[M] \cap[N]=[M \cap N]$, i.e. the cap product is given by intersecting submanifolds.

## Warning 9.0.14

This can't always be done! There are counterexamples where homology classes can't be represented by submanifolds.

## 10 Wednesday, February 03

Consider an oriented surface, and take two oriented submanifolds


We can then take the fundamental classes of the submanifolds, say $[\alpha],[\beta] \in H^{1}(X ; \mathbb{Z}) \xrightarrow{P D} H^{1}(X, \mathbb{Z})$. Here $T_{p} \alpha \oplus T_{p} \beta=T_{p} X$, since the intersections are transverse. Since $\alpha, \beta$ are oriented, let $\{e\}$ be a basis of $T_{p} \alpha$ (up to $\mathbb{R}^{+}$) and similarly $\{f\}$ a basis of $T_{p} \beta$. We can then ask if $\{e, f\}$ constitutes an oriented basis of $T_{p} X$. If so, we write $\alpha \cdot{ }_{p} \beta:=+1$ and otherwise $\alpha \cdot{ }_{p} \beta=-1$. We thus have

$$
[\alpha] \smile[\beta] \in H^{2}(X ; \mathbb{Z}) \xrightarrow{P D} H_{0}(X ; \mathbb{Z})=\mathbb{Z}
$$

since $X$ is connected. We can thus define the intersection form $\alpha \cdot \beta:=[\alpha] \smile[\beta]$. In general if $A, B$ are oriented transverse submanifolds of $M$ which are themselves oriented, we'll have $[A] \smile$ $[B]=[A \cap B]$. We need to be careful: how do we orient the intersection? This is given by comparing the orientations on $A$ and $B$ as before.

Example 10.0.1(?): If $\operatorname{dim} M=\operatorname{dim} A+\operatorname{dim} B$, then any $p \in A \cap B$ is oriented by comparing $\left\{\right.$ or $_{A}$, or $\left._{B}\right\}$ to or ${ }_{M}$.


Here it suffices to check that $\left\{e, f_{1}, f_{2}\right\}$ is an oriented basis of $T_{p} M$.
Example 10.0.2(?): In this case, $[\alpha] \smile[\beta]=0$ and so $\alpha \cdot \beta=0$ :


Remark 10.0.3: Note that cohomology with $\mathbb{Z}$ coefficients can be defined for any topological space, and Poincaré duality still holds.

Remark 10.0.4: We'll be considering $M=M^{4}$, smooth 4-manifolds. How to visualize: take a 3 -manifold and cross it with time!


Figure 1: Picking one basis element in the time direction

Here ? is oriented in the "forward time" direction, and this is a surface at time $t=0$. Where $A \cdot B=+1$, since $\left\{e_{1}, e_{2}, f_{1}, f_{2}\right\}=\left\{e_{x}, e_{y}, e_{z}, e_{t}\right\}$ is a oriented basis for $\mathbb{R}^{4}$. For $?^{2}$, switching the order of $\alpha, \beta$ no longer yields an oriented basis, but in this case it is ? and $A \cdot B=B \cdot A$. This is because

$$
A:=\left[\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right] \Longrightarrow \operatorname{det}(A)=-1 \quad \operatorname{det}\left[\begin{array}{ll}
A & \\
& A
\end{array}\right]=1
$$

Remark 10.0.5: Let $M^{2 n}$ be an oriented manifold, then the cup product yields a bilinear map $H^{n}(M ; \mathbb{Z}) \otimes H^{n}(M ; \mathbb{Z}) \rightarrow \mathbb{Z}$ which is symmetric when $n$ is odd and antisymmetric (or symplectic) when $n$ is even. This is a perfect (or unimodular) pairing (potentially after modding out by torsion) which realizes an isomorphism:

$$
\begin{aligned}
\left(H^{n}(M ; \mathbb{Z}) / \text { tors }\right)^{\vee} & \xrightarrow{\sim} H^{n}(M ; \mathbb{Z}) / \text { tors } \\
\alpha \smile- & \leftrightarrow \alpha
\end{aligned}
$$

where the LHS are linear functionals on cohomology.

Remark 10.0.6: Recall the universal coefficients theorem:

$$
H^{i}(X ; \mathbb{Z}) / \text { tors } \cong\left(H_{i}(X ; \mathbb{Z}) / \text { tors }\right)^{\vee}
$$

The general theorem shows that $H^{i}(X ; \mathbb{Z})_{\text {tors }}=H_{i-1}(X ; \mathbb{Z})_{\text {tors }}$.

Remark 10.0.7: Note that if $M$ is an oriented 4-manifold, then

|  | tors | torsionfree |  | tors | torsionfree |
| :--- | :--- | :--- | :--- | :---: | :---: |
| $H^{0}$ | 0 | $\mathbb{Z}$ | $H_{0}$ | 0 | $\mathbb{Z}$ |
| $H^{1}$ | 0 | $\mathbb{Z}^{\beta_{1}}$ |  | $H_{1}$ | $A$ |
| $H^{2}$ | $A$ | $\mathbb{Z}^{\beta_{2}}$ | $\xrightarrow{P D}$ | $H_{2}$ | $A$ |
| $H^{3}$ | $A$ | $\mathbb{Z}^{\beta_{1}}$ |  | $H_{3}$ | $\mathbb{Z}^{\beta_{1}}$ |
| $H^{4}$ | 0 | $\mathbb{Z}$ | $H_{4}$ | 0 | $\mathbb{Z}^{\beta_{2}}$ |
|  |  |  |  |  | $\mathbb{Z}^{\beta_{1}}$ |
|  |  |  |  | $\mathbb{Z}$ |  |

In particular, if $M$ is simply connected, then $H_{1}(M)=\operatorname{Ab}\left(\pi_{1}(M)\right)=0$, which forces $A=0$ and $\beta_{1}=0$.

## Definition 10.0.8 (Lattice)

A lattice is a finite-dimensional free $\mathbb{Z}$-module $L$ together with a symmetric bilinear form

$$
\begin{aligned}
& \cdot: L^{\otimes 2} \rightarrow \mathbb{Z} \\
& \ell \otimes m \mapsto \ell \cdot m .
\end{aligned}
$$

The lattice $(L, \cdot)$ is unimodular if and only if the following map is an isomorphism:

$$
\begin{aligned}
L & \rightarrow L^{\vee} \\
\ell & \mapsto \ell \cdot(-) .
\end{aligned}
$$

Remark 10.0.9: How to determine if a lattice is unimodular: take a basis $\left\{e_{1}, \cdots, e_{n}\right\}$ of $L$ and form the Gram matrix $M_{i j}:=\left(e_{i} \cdot e_{j}\right) \in \operatorname{Mat}(n \times n, \mathbb{Z})^{\mathrm{Sym}}$. Then $(L, \cdot)$ is unimodular if and only if $\operatorname{det}(M)= \pm 1$ if and only if $M^{-1}$ is integral. In this case, the rows of $M^{-1}$ will form a basis of the dual basis.

Definition 10.0.10 (Index of a lattice)
The index of a lattice is $|\operatorname{det} M|$.

Exercise 10.0.11 (?)
Prove that $|\operatorname{det} M|=\left|L^{\vee} / L\right|$.

Remark 10.0.12: In general, for $M^{4 k}$, the $H^{2 k} /$ tors is unimodular. For $M^{4 k+2}$, the $H^{2 k+1} /$ tors is a unimodular symplectic lattice, which is obtained by replacing the word "symmetric" with "antisymmetric" everywhere above.

Example 10.0.13(?): For the torus, since the dimension is $2(\bmod 4)$, you get the skew-symmetric matrix

$$
\left[\begin{array}{cc}
0 & 1 \\
-1 & 0
\end{array}\right] .
$$

## Check!

Definition 10.0.14 (Nondegenerate lattices)
A lattice is nondegenerate if $\operatorname{det} M \neq 0$.

Definition 10.0.15 (Base change of lattices)
The tensor product $L \otimes_{\mathbb{Z}} \mathbb{R}$ is a vector space with an $\mathbb{R}$-valued symmetric bilinear form. This allows extending the lattice from $\mathbb{Z}^{n}$ to $\mathbb{R}^{n}$.

Remark 10.0.16: If $(L, \cdot)$ is nondegenerate, then Gram-Schmidt will yield an orthonormal basis $\left\{v_{i}\right\}$. The number of positive norm vectors is an invariant, so we obtain $\mathbb{R}^{p, q}$ where $p$ is the number of +1 s in the Gram matrix and $q$ is the number of -1 s . The signature of $(L,-)$ is $(p, q)$, or by abuse of notation $p-q$. This is an invariant of the 4-manifold, as is the lattice itself $H^{2}(X ; \mathbb{Z}) /$ tors equipped with the intersection form.

Remark 10.0.17: There is a perfect pairing called the linking pairing:

$$
H^{i}(X ; \mathbb{Q} / \mathbb{Z}) \otimes H^{n-i-1}(X ; \mathbb{Q} / \mathbb{Z}) \rightarrow \mathbb{Q} / \mathbb{Z}
$$



Remark 10.0.18: $A \cdot B:=\sum_{p \in A \cap B} \operatorname{sgn}_{p}(A, B)$, where $A \pitchfork B$ and this turns out to be equal to the cup product. This works for topological manifolds - but there are no tangent spaces there, so taking oriented bases doesn't work so well! You can also view

$$
[A] \smile[\omega]=\int_{A} \omega .
$$

## 11 Friday, February 05

Remark 11.0.1: Recall that a lattice is unimodular if the map $L \rightarrow L^{\vee}:=\operatorname{Hom}(L, \mathbb{Z})$ is an isomorphism, where $\ell \mapsto \ell \cdot(-)$. To check this, it suffices to check if the Gram matrix $M$ of a basis $\left\{e_{i}\right\}$ satisfies $|\operatorname{det} M|=1$.

Example 11.0.2(Determinant 1 Integer Matrices): The matrices [1] and [ -1 correspond to the lattice $\mathbb{Z} e$ where either $e^{2}:=e \cdot e=1$ or $e^{2}=-1$. If $M_{1}, M_{2}$ both have absolute determinant 1 ,
then so does

$$
\left[\begin{array}{cc}
M_{1} & 0 \\
0 & M_{2}
\end{array}\right]
$$

So if $L_{1}, L_{2}$ are unimodular, then taking an orthogonal sum $L_{1} \oplus L_{2}$ also yields a unimodular lattice. So this yields diagonal matrices with $p$ copies of +1 and $q$ copies of -1 . This is referred to as $r m 1_{p, q}$, and is an odd unimodular lattice of signature ( $p, q$ ) (after passing to $\mathbb{R}$ ). Here odd means that there exists a $v \in L$ such that $v^{2}$ is odd.

Example 11.0.3(Even unimodular lattices): An even lattice must have no vectors of odd norm, so all of the diagonal elements are in $2 \mathbb{Z}$. This is because $\left(\sum n_{i} e_{i}\right)^{2}=\sum_{i} n_{i}^{2} e_{i}^{2}+\sum_{i<j} 2 n_{i}, n_{j} e_{i} \cdot e_{j}$. Note that the matrix must be symmetric, and one example that works is

$$
\left[\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right]
$$

We'll refer to this lattice as $H$, sometimes referred to as the hyperbolic cell or hyperbolic plane.

Example 11.0.4 (A harder even unimodular lattice): This is built from the $E_{8}$ Dynkin diagram:


The rule here is

$$
e_{i} \cdot e_{j}= \begin{cases}-2 & i=j \\ 1 & e_{i} \rightarrow e_{j} \\ 0 & \text { if not connected }\end{cases}
$$

So for example, $e_{2} \cdot e_{6}=0, e_{1} \cdot e_{3}=1, e_{2}^{2}=-2$. You can check that $\operatorname{det}\left(e_{i} \cdot e_{j}\right)=1$, and this is referred to as the $E_{8}$ lattice. This is of signature $(0,8)$, and it's negative definite if and only if $v^{2}<0$ for all $v \neq 0$. One can also negate the intersection form to define $-E_{8}$. Note that any simply-laced Dynkin diagram yields some lattice. For example, $E_{10}$ is unimodular of signature $(1,9)$, and it turns out that $E_{10} \cong E_{8} \oplus H$.

Definition 11.0.5 (Unimodular lattice II)
Take

$$
\mathbf{I I}_{a, a+8 b}:=\bigoplus_{i=1}^{a} H \oplus \bigoplus_{j=1}^{b} E_{8}
$$

which is an even unimodular lattice since the diagonal entries are all -2 , and using the fact
that the signature is additive, is of signature $(a, a+8 b)$. Similarly,

$$
\mathbf{I I}_{a+8 b, a}:=\bigoplus_{i=1}^{a} H \oplus \bigoplus_{j=1}^{b}\left(-E_{8}\right)
$$

which is again even and unimodular.

## Remark 11.0.6: Thus

- $\mathbf{I}_{p, q}$ is odd, unimodular, of signature $(p, q)$.
- $\mathbf{I I}_{p, q}$ is even, unimodular, of signature $(p, q)$ only for $p \equiv q(\bmod 8)$.


## Theorem 11.0.7 (Serre).

Every unimodular lattice which is not positive or negative definite is isomorphic to either $\mathbf{I}_{p, q}$ or $\mathbf{I I}_{p, q}$ with $8 \mid p-q$.

Remark 11.0.8: So there are obstructions to the existence of even unimodular lattices. Other than that, the number of (say) positive definite even unimodular lattices is

| Dimension | Number of Lattices |
| :--- | :--- |
| 8 | $1: E_{8}$ |
| 16 | $2: E_{8}^{\oplus 2}, D_{16}^{+}$ |
| 24 | $24:$ The Neimeir lattices (e.g. the Leech lattice) |
| 32 | $>8 \times 10^{16}!!!!$ |

Note that the signature of a definite lattice must be divisible by 8 .

Remark 11.0.9: There is an isometry: $f: E_{8} \rightarrow E_{8}$ where $f \in O\left(E_{8}\right)$, the linear maps preserving the intersection form (i.e. the Weyl group $W\left(E_{8}\right)$, given by $v \mapsto v+\left(v, e_{i}\right) e_{i}$. The Leech lattice also shows up in the sphere packing problems for dimensions $2,4,8,24$. See Hale's theorem / Kepler conjecture for dimension 3 ! This uses an identification of $L$ as a subset of $\mathbb{R}^{n}$, namely $L \otimes_{\mathbb{Z}} \mathbb{R} \cong \mathbb{R}^{24}$ for example, and the map $L \hookrightarrow\left(\mathbb{R}^{24}, \cdot\right)$ is an isometric embedding into $\mathbb{R}^{n}$ with the standard form. Connection to classification of Lie groups: root lattices.

Remark 11.0.10: If $M^{4}$ is a compact oriented 4-manifold and if the intersection form on $H^{2}(M ; \mathbb{Z})$ is indefinite, then the only invariants we can extract from that associated lattice are

- Whether it's even or odd, and
- Its signature

If the lattice is even, then the signature satisfies $8 \mid p-q$. So Poincaré duality forces unimodularity, and then there are further number-theoretic restrictions. E.g. this prohibits $\beta_{2}=7$, since then the signature couldn't possibly be 8 if the intersection form is even.

### 11.1 Characteristic Classes

Definition 11.1.1 (Classifying space)
Let $G$ be a topological group, then a classifying space $E G$ is a contractible topological space admitting a free continuous $G$-action with a "nice" quotient.

Remark 11.1.2: Thus there is a map $E G \rightarrow B G:=E G / G$ which has the structure of a principal $G$-bundle.


Here we use a point $p$ depending on $U$ in an orbit to identify orbits $g \cdot p$ with $g$, and we want to take transverse slices to get local trivializations of $U \in B G$. It suffices to know where $\pi^{-1}(U) \cong U \times G$, and it suffices to consider $U \times\{e\}$. Moreover, $E G \rightarrow B G$ is a universal principal $G$-bundle in the sense that if $P \rightarrow X$ is a universal $G$-bundle, there is an $f: X \rightarrow B G$.


Link to Diagram

Here bundles will be classified by homotopy classes of $f$, so

$$
\{\text { Principal } G \text {-bundles } / X\} \rightleftharpoons[X, B G] \text {. }
$$

## § Warning 11.1.3

This only works for paracompact Hausdorff spaces! The line $\mathbb{R}$ with the doubled origin is a counterexample, consider complex line bundles.

## Revisit this last section, had to clarify a few things for myself!

## 12 Monday, February 08

Last time: $B G$ and $E G$. See Milnor and Stasheff.

Example 12.0.1(?): Let $G:=\mathrm{GL}_{n}(\mathbb{R})=\mathbb{R}^{\times}$, then we can take

$$
E G=\mathbb{R}^{\infty}:=\left\{\left(a_{1}, a_{2}, \cdots\right) \mid a_{i} \in \mathbb{R}, a_{i \gg 0}=0, a_{i} \text { not all zero }\right\}
$$

Then $\mathbb{R}^{\times}$acts on $E G$ by scaling, and we can take the quotient $\mathbb{R}^{\infty} \backslash\{0\} / \mathbb{R}^{\times}$, where $\mathbf{a} \sim \lambda$ a for all $\lambda \in \mathbb{R}^{\times}$. This yields $\mathbb{R} \mathbb{P}^{\infty}$ as the quotient. You can check that $E_{G}$ is contractible: it suffices to show that $S^{\infty}:=\left\{\sum\left|a_{i}\right|=1\right\}$ is contractible. This works by decreasing the last nonzero coordinate and increasing the first coordinate correspondingly. Moreover, local lifts exist, so we can identify $\mathbb{R} \mathbb{P}^{\infty} \cong B \mathbb{R}^{\times}=B G$. Similarly $B C^{\times} \cong \mathbb{C P}^{\infty}$ with $E \mathbb{C}^{\times}:=\mathbb{C}^{\infty} \backslash\{0\}$.

Example 12.0.2(?): Consider $G=\mathrm{GL}_{n}(\mathbb{R})$. It turns out that $B G=\operatorname{Gr}\left(d, \mathbb{R}^{\infty}\right)$, which is the set of linear subspaces of $\mathbb{R}^{\infty}$ of dimension $d$. This is spanned by $d$ vectors $\left\{e_{i}\right\}$ in some large enough $\mathbb{R}^{N} \subseteq \mathbb{R}^{\infty}$, since we can take $N$ to be the largest nonvanishing coordinate and include all of the vectors into $\mathbb{R}^{\infty}$ by setting $a_{>N}=0$. For any $L \in \operatorname{Gr}_{d}\left(\mathbb{R}^{\infty}\right)$, since $\mathbb{R}^{d}$ has a standard basis, there is a natural $\mathrm{GL}_{d}$ torsor: the set of ordered bases of linear subspaces. So define

$$
E G:=\left\{\text { bases of linear subspaces } L \in \operatorname{Gr}_{d}\left(\mathbb{R}^{\infty}\right)\right\}
$$

then any $A \in \mathrm{GL}_{d}(\mathbb{R})$ acts on $E G$ by sending $\left(L,\left\{e_{i}\right\}\right) \mapsto\left(L,\left\{L e_{i}\right\}\right)$. We can identify $E G$ as $d$-tuples of linearly independent elements of $\mathbb{R}^{\infty}$, and there is a map

$$
\begin{aligned}
E G & \rightarrow B G \\
\left\{e_{i}\right\} & \mapsto \operatorname{span}_{\mathbb{R}}\left\{e_{i}\right\}
\end{aligned}
$$

Thus there is a universal vector bundle over $B G L_{d}$ :


So $\mathcal{E} \subseteq B G L_{d} \times \mathbb{R}^{\infty}$, where we can define $\mathcal{E}:=\{(L, p) \mid p \in L\}$. In this case, $E G=\operatorname{Frame}(\mathcal{E})$ is the frame bundle of this universal bundle. The same setup applies for $G:=\mathrm{GL}_{d}(\mathbb{C})$, except we take $\mathrm{Gr}_{d}\left(\mathbb{C}^{\infty}\right)$.

Example 12.0.3(?): Consider $G=O_{d}$, the set of orthogonal transformations of $\mathbb{R}^{d}$ with the standard bilinear form, and $U_{d}$ the set of unitary such transformations. To be explicit:

$$
U_{d}:=\{A \in \operatorname{Mat}(d \times d, \mathbb{C}) \mid\langle A v, A v\rangle=\langle v, v\rangle\}
$$

where

$$
\left\langle\left[v_{1}, \cdots, v_{n}\right],\left[v_{1}, \cdots, v_{n}\right]\right\rangle=\sum\left|v_{i}\right|^{2}
$$

Alternatively, $A^{t} A=I$ for $O_{d}$ and $\overline{A^{t}} A=I$ for $U_{d}$. In this case, $B O_{d}=\operatorname{Gr}_{d}\left(\mathbb{R}^{\infty}\right)$ and $B U_{d}=$ $\operatorname{Gr}_{d}\left(\mathbb{C}^{\infty}\right)$, but we'll make the fibers smaller: set the fiber over $L$ to be

$$
\left(E O_{d}\right)_{L}:=\{\text { orthogonal frames of } L\}
$$

and similarly $\left(E U_{d}\right)_{L}$ the unitary frames of $L$. That there are related comes from the fact that $\mathrm{GL}_{d}$ retracts onto $O_{d}$ using the Gram-Schmidt procedure.

Remark 12.0.4: Recall that there is a bijective correspondence

$$
\left\{\begin{array}{c}
\text { Principal } G \text { - bundles } \\
\text { on } X
\end{array}\right\} \rightleftharpoons[X, B G]
$$

and there is also a correspondence

$$
\left\{\begin{array}{c}
\text { Principal GL } \\
\text { on } X
\end{array}\right\} \rightleftharpoons\left\{\begin{array}{c}
\text { Principal } \mathcal{O}_{d} \text {-bundles } \\
\text { on } X
\end{array}\right\}
$$

Using the associated bundle construction, on the LHS we obtain vector bundles $\mathcal{E} \rightarrow X$ of rank $d$, and on the RHS we have bundles with a metric. In local trivializations $U \times \mathbb{R}^{d} \rightarrow \mathbb{R}^{d}$, the metric is the standard one on $\mathbb{R}^{d}$. This is referred to as a reduction of structure group, i.e. a principal $\mathrm{GL}_{d}$ bundle admits possibly different trivializations for which the transition functions lie in the subgroup $O_{d}$.

Example 12.0.5(?): Given any trivial principal $G$-bundle, it has a reduction of structure group to the trivial group. But the fact that the bundle is trivial may not be obvious.


Remark 12.0.6: We want to compute $H^{*}\left(B U_{d} ; \mathbb{Z}\right)$. Why is this important? Given any complex vector bundle $\mathcal{E} \rightarrow X$ there is an associated principal $U_{d}$ bundle by choosing a metric, so we get a homotopy class $\left[X, B U_{d}\right]$. Given any $f \in\left[X, B U_{d}\right]$ and any $\alpha \in H^{k}\left(B U_{d} ; \mathbb{Z}\right)$, we can take the pullback $f^{*} \alpha \in H^{k}(X ; \mathbb{Z})$, which are Chern classes.

## Exercise 12.0.7 (?)

Show that $H^{*}\left(B U_{d} ; \mathbb{Z}\right)$ stabilizes as $d \rightarrow \infty$ to an infinitely generated polynomial ring $\mathbb{Z}\left[c_{1}, c_{2}, \cdots\right]$ with each $c_{i}$ in cohomological degree $2 i$, so $c_{i} \in H^{2 i}\left(B U_{d}, \mathbb{Z}\right)$.

Definition 12.0.8 (Chern class)
There is a map $B U_{d-1} \rightarrow B U_{d}$, which we can identify as

$$
\begin{aligned}
\operatorname{Gr}_{d-1}\left(C^{\infty}\right) & \rightarrow \operatorname{Gr}_{d}\left(\mathbb{C}^{\infty}\right) \\
\left\{v_{1}, \cdots, v_{d-1}\right\} & \mapsto \operatorname{span}\left\{(1,0,0, \cdots), s v_{1}, \cdots, s v_{d-1}\right\}
\end{aligned}
$$

This is defined by sending a basis where $s: \mathbb{C}^{\infty} \rightarrow \mathbb{C}^{\infty}$ is the map that shifts every coordinate to the right by one.

```
Question: does }\mp@subsup{\textrm{Gr}}{d}{}(\mp@subsup{\mathbb{C}}{}{\infty})\mathrm{ deformation retract onto the image of this map?
```

This will yield a fiber sequence

$$
S^{2 d-1} \rightarrow B U_{d-1} \rightarrow B U_{d}
$$

and using connectedness of the sphere and the LES in homotopy this will identify

$$
H^{*}\left(B U_{d}\right)=H^{*}\left(B U_{d-1}\right)\left[c_{d}\right] \quad \text { where } c_{d} \in H^{2 d}\left(B U_{d}\right)
$$

The Chern class of a vector bundle $\mathcal{E}$, denoted $c_{k}(\mathcal{E})$, will be defined as the pullback $f^{*} c_{k}$.

## 13 Wednesday, February 10

## Theorem 13.0.1(Stable cohomology of BOn).

As $n \rightarrow \infty$, we have

$$
H^{*}\left(B O_{n}, \mathbb{Z} / 2 \mathbb{Z}\right)=\mathbb{Z} / 2 \mathbb{Z}\left[w_{1}, w_{2}, \cdots\right] \quad w_{i} \in H^{i}
$$

Definition 13.0.2 (Stiefel-Whitney class)
Given any principal $O_{n}$-bundle $P \rightarrow X$, there is an induced map $X \xrightarrow{f} B O_{n}$, so we can pull back the above generators to define the Stiefel-Whitney classes $f^{*} w_{i}$.

Remark 13.0.3: If $P:=$ OFrame $T X$, then $f^{*} w_{1}$ measures whether $X$ has an orientation, i.e. $f^{*} w_{1}=$ $0 \Longleftrightarrow X$ can be oriented. We also have $f^{*} w_{i}(P)=w_{i}(\mathcal{E})$ where $P=\operatorname{OFrame}(\mathcal{E})$. In general, we'll just write $w_{i}$ for Stiefel-Whitney classes and $c_{i}$ for Chern classes.

Definition 13.0.4 (Pontryagin Classes)
The Pontryagin classes of a real vector bundle $\mathcal{E}$ are defined as

$$
p_{i}(\mathcal{E})=(-1)^{i} c_{2 i}\left(\mathcal{E} \otimes_{\mathbb{R}} \mathbb{C}\right)
$$

Note that the complexified bundle above is a complex vector bundle with the same transition functions as $\mathcal{E}$, but has a reduction of structure group from $\mathrm{GL}_{n}(\mathbb{C})$ to $\mathrm{GL}_{n}(\mathbb{R})$.

## Observation 13.0.5

$\mathbb{R} \mathbb{P}^{\infty}$ and $\mathbb{C} \mathbb{P}^{\infty}$ are examples of $K(\pi, n)$ spaces, which are the unique-up-to-homotopy spaces defined by

$$
\pi_{k} K(\pi, n)= \begin{cases}\pi & k=n \\ 0 & \text { else }\end{cases}
$$

Theorem 13.0.6(Brown Representability).

$$
H^{n}(X ; \pi) \cong[X, K(\pi, n)]
$$

Example 13.0.7(?):

$$
\begin{aligned}
& {\left[X, \mathbb{R P}^{\infty}\right] \cong H^{1}(X ; \mathbb{Z} / 2 \mathbb{Z})} \\
& {\left[X, \mathbb{C P}^{\infty}\right] \cong H^{2}(X ; \mathbb{Z})}
\end{aligned}
$$

Proposition 13.0.8(Classification of complex line bundles).
There is a correspondence

$$
\{\text { Complex line bundles }\} \rightleftharpoons\left[X, \mathbb{C P}^{\infty}\right]=\left[X, B C^{\times}\right] \rightleftharpoons H^{2}(X ; \mathbb{Z})
$$

Importantly, note that for $X \in \operatorname{Mfd}_{\mathbb{C}}, H^{2}(X ; \mathbb{Z})$ measures smooth complex line bundles and not holomorphic bundles.

Proof (of proposition).
We'll take an alternate direct proof. Consider the exponential exact sequence on $X$ :

$$
0 \rightarrow \underline{Z} \rightarrow \mathcal{O} \xrightarrow{\exp } \mathcal{O}^{\times}
$$

Note that $\underline{\mathbb{Z}}$ consists of locally constant $\mathbb{Z}$-valued functions, $\mathcal{O}$ consists of smooth functions, and $\mathcal{O}^{\times}$are ???.
Can't read screenshot! : (
This yields a LES in homology:


## Link to Diagram

Since $\mathcal{O}$ admits a partition of unity, $H^{>0}(X ; \mathcal{O})=0$ and all of the red terms vanish. For complex line bundles $L, H^{1}\left(X, \mathcal{O}^{\times}\right) \cong H^{2}(X ; \mathbb{Z})$. Taking a local trivialization $\left.L\right|_{U} \cong U \times \mathbb{C}$, we obtain transition functions

$$
t_{U V} \in C^{\infty}\left(U \cap V, \mathrm{GL}_{1}(\mathbb{C})\right)
$$

where we can identify $\mathrm{GL}_{1}(\mathbb{C}) \cong \mathbb{C}^{\times}$. We then have

$$
\left(t_{U_{i j}}\right) \in \prod_{i<j} \mathcal{O}^{\times}\left(U_{i} \cap U_{j}\right)=C^{1}\left(X ; \mathcal{O}^{\times}\right) .
$$

Moreover,

$$
\left(t_{U_{i j}} t_{U_{i k}}^{-1} t_{U_{j k}}\right)_{i, j, k}=\partial\left(t_{U_{i j}}\right)_{i, j}=0
$$

since transitions functions satisfy the cocycle condition. So in fact $\left(t_{U_{i j}}\right) \in Z^{1}\left(X ; \mathcal{O}^{\times}\right)=$ $\operatorname{ker} \partial^{1}$, and we can take its equivalence class $\left[\left(t_{U_{i j}}\right)\right] \in H^{1}\left(X ; \mathcal{O}^{\times}\right)=\operatorname{ker} \partial^{1} / \operatorname{im} \partial^{0}$. Changing trivializations by some $s_{i} \in \prod_{i} \mathcal{O}^{\times}\left(U_{i}\right)$ yields a composition which is a different trivialization of the same bundle:


Link to Diagram
So the $\left(t_{U_{i j}}\right.$ change exactly by an $\partial^{0}\left(s_{i}\right)$. Thus the following map is well-defined:

$$
L \mapsto\left[\left(t_{U_{i j}}\right)\right] \in H^{1}\left(X ; \mathcal{O}^{\times}\right)
$$

There is another construction of the map

$$
\begin{aligned}
\{L\} & \rightarrow H^{2}(X ; \mathbb{Z}) \\
L & \mapsto c_{1}(L)
\end{aligned}
$$

Take a smooth section of $L$ and $s \in H^{0}(X ; L)$ that intersects an $\mathcal{O}$-section of $L$ transversely. Then

$$
V(s):=\{x \in X \mid s(x)=0\}
$$

is a submanifold of real codimension 2 in $X$, and $c_{1}(L)=[V(s)] \in H^{2}(X ; \mathbb{Z})$.

Theorem 13.0.9(Splitting Principle for Complex Vector Bundles).

1. Suppose that $\mathcal{E}=\bigoplus_{i=1}^{r} L_{i}$ and let $c(\mathcal{E}):=\sum c_{i}(\mathcal{E}$. Then

$$
c(\mathcal{E})=\prod_{i=1}^{r}\left(1+c_{i}\left(L_{i}\right)\right)
$$

2. Given any vector bundle $\mathcal{E} \rightarrow X$, there exists some $Y$ and a map $Y \rightarrow X$ such that $f^{*}: H^{k}(X ; \mathbb{Z}) \hookrightarrow H^{k}(Y ; \mathbb{Z})$ is injective and $f^{*} \mathcal{E}=\bigoplus_{i=1}^{r} L_{i}$.

## Slogan 13.0.10

To verify any identities on characteristic classes, it suffices to prove them in the case where $\mathcal{E}$ splits into a direct sum of line bundles.

Example 13.0.11(?):

$$
c(\mathcal{E} \oplus \mathcal{F})=c(\mathcal{E}) c(\mathcal{F})
$$

To prove this, apply the splitting principle. Choose $Y, Y^{\prime}$ splitting $\mathcal{E}, \mathcal{E}^{\prime}$ respectively, this produces a space $Z$ and a map $f: Z \rightarrow X$ where both split. We can write

$$
\begin{array}{ll}
f^{*} \mathcal{E}=\bigoplus L_{i} & c\left(f^{*} \mathcal{E}\right)=\prod\left(1+c_{1}\left(L_{i}\right)\right) \\
f^{*} \mathcal{F}=\bigoplus M_{j} & c\left(f^{*} \mathcal{E}\right)=\prod\left(1+c_{1}\left(M_{j}\right)\right)
\end{array}
$$

We thus have

$$
\begin{aligned}
c\left(f^{*} \mathcal{E} \oplus f^{*} \mathcal{F}\right) & =\prod\left(1+c_{1}\left(L_{i}\right)\right)\left(1+c_{1}\left(M_{j}\right)\right) \\
& =c\left(f^{*} \mathcal{E}\right) c\left(f^{*} \mathcal{F}\right)
\end{aligned}
$$

and $f^{*}\left(c(\mathcal{E} \oplus \mathcal{F})=f^{*}(c(\mathcal{E}) c(\mathcal{F}))\right.$. Since $f^{*}$ is injective, this yields the desired identity.
Example 13.0.12(?): We can compute $c\left(\operatorname{Sym}^{2} \mathcal{E}\right)$, and really any tensorial combination involving $\mathcal{E}$, and it will always yield some formula in the $c_{i}(\mathcal{E})$.

## 14 Friday, February 12

Remark 14.0.1: Last time: the splitting principle. Suppose we have $\mathcal{E}=L_{1} \oplus \cdots \oplus L_{r}$ and let $x_{i}:=c_{i}\left(L_{i}\right)$. Then $c_{k}(\mathcal{E})$ is the degree $2 k$ part of $\prod_{i=1}^{r}\left(1+x_{i}\right)$ where each $x_{i}$ is in degree 2 . This is equal to $e_{k}\left(x_{1}, \cdots, x_{r}\right)$ where $e_{k}$ is the $k$ th elementary symmetric polynomial.

Example 14.0.2(?): For example,

- $e_{1}=x_{1}+\cdots x_{r}$.
- $e_{2}=x_{1} x_{2}+x_{1} x_{3}+\cdots=\sum_{i<j} x_{i} x_{j}$
- $e_{3}=\sum_{i<j<k} x_{i} x_{j} x_{k}$, etc.

Remark 14.0.3: The theorem is that any symmetric polynomial is a polynomial in the $e_{i}$. For example, $p_{2}=\sum x_{i}^{2}$ can be written as $e_{1}^{2}-2 e_{2}$. Similarly, $p_{3}=\sum x_{i}^{3}=e_{1}^{3}-3 e_{1} e_{2}-3 e_{3}$ Note that the coefficients of these polynomials are important for representations of $S_{n}$, see Schur polynomials.

Remark 14.0.4: Due to the splitting principle, we can pretend that $x_{i}=c_{i}\left(L_{i}\right)$ exists even when $\mathcal{E}$ doesn't split. If $\mathcal{E} \rightarrow X$, the individual symbols $x_{i}$ don't exist, but we can write '

$$
x_{1}^{3}+\cdots+x_{r}^{3}=e_{1}^{3}-3 e_{1} e_{2}-3 e_{3}:=c_{1}(\mathcal{E})^{3}+3 c_{1}(\mathcal{E}) c_{2}(\mathcal{E})+\cdots,
$$

which is a well-defined element of $H^{6}(X ; \mathbb{Z})$. So this polynomial defines a characteristic class of $\mathcal{E}$, and this can be done for any symmetric polynomial. We can change basis in the space of symmetric polynomials to now define different characteristic classes.

Definition 14.0.5 (Chern Character)
The Chern character is defined as

$$
\begin{aligned}
\operatorname{ch}(\mathcal{E}) & :=\sum_{i=1}^{r} e^{x_{i}} \in H^{*}(X ; \mathbb{Q}) \\
& :=\sum_{i=1}^{r} \sum_{k=0}^{\infty} \frac{x_{i}^{k}}{k!} \\
= & \sum_{k=0}^{\infty} \frac{p_{k}\left(x_{1}, \cdots, x_{r}\right)}{k!} \\
= & \operatorname{rank}(\mathcal{E})+c_{1}(\mathcal{E})+\frac{c_{1}(\mathcal{E})-c_{2}(\mathcal{E})}{2!}+\frac{c_{1}(\mathcal{E})^{3}-3 c_{1}(\mathcal{E}) c_{2}(\mathcal{E})-3 c_{3}(\mathcal{E})}{3!}+\cdots \\
\quad & \in H^{0}+H^{2}+H^{4}+H^{6} \\
= & \operatorname{ch}_{0}(\mathcal{E})+\operatorname{ch}_{1}(\mathcal{E})+\operatorname{ch}_{2}(\mathcal{E})+\cdots, \\
& \operatorname{ch}_{i}(\mathcal{E}) \in H^{2 i}(X ; \mathbb{Q}) .
\end{aligned}
$$

Definition 14.0.6 (Total Todd class)
The total Todd class

$$
\operatorname{td}(\mathcal{E}):=\prod_{i=1}^{r} \frac{x_{i}}{1-e^{-x_{i}}}
$$

Note that

$$
\frac{x_{i}}{1-e^{-x_{i}}}=1+\frac{x_{i}}{2}+\frac{x_{i}^{2}}{12}+\frac{x_{i}^{4}}{720}+\cdots=1+\frac{x_{i}}{2}+\sum_{i=1}^{\infty} \frac{(-1)^{i-1} B_{i}}{(2 i)!} x^{2 i} .
$$

where L'Hopital shows that the derivative at $x_{i}=0$ exists, so it's analytic at zero and the expansion makes sense, and the $B_{i}$ are Bernoulli numbers.

Remark 14.0.7(Very important and useful!!): $\operatorname{ch}(\mathcal{E} \oplus \mathcal{F})=\operatorname{ch}(\mathcal{E})+\operatorname{ch}(\mathcal{F})$ and $\operatorname{ch}(\mathcal{E} \otimes \mathcal{F})=$ $\sum_{i, j} e^{x_{i}+y_{j}}=\operatorname{ch}(\mathcal{E}) \operatorname{ch}(\mathcal{F})$ using the fact that $c_{1}\left(L_{1} \otimes L_{2}\right)=c_{1}\left(L_{1}\right) c_{1}\left(L_{2}\right)$. So ch is a "ring morphism" in the sense that it preserves multiplication $\otimes$ and addition $\oplus$, making the Chern character even better than the total Chern class.

Definition 14.0.8 (Todd Class)
Let $X \in \mathrm{Mfd}_{\mathbb{C}}$, then define the Todd class of $X$ as $\operatorname{td}_{\mathbb{C}}(X):=\operatorname{td}(T X)$ where $T X$ is viewed as a complex vector bundle. If $X \in \mathrm{Mfd}_{\mathbb{R}}$, define $\operatorname{td}_{\mathbb{R}}=\operatorname{td}\left(T X \otimes_{\mathbb{R}} \mathbb{C}\right)$.

### 14.1 Section 5: Riemann-Roch and Generalizations

Remark 14.1.1: Let $X \in$ Top and let $\mathcal{F}$ be a sheaf of vector spaces. Suppose $h^{i}(X ; \mathcal{F}):=$ $\operatorname{dim} H^{i}(X ; \mathcal{F})<\infty$ for all $i$ and is equal to 0 for $i \gg 0$.

Definition 14.1.2 (Euler Characteristic of a Sheaf)
The Euler characteristic of $\mathcal{F}$ is defined as

$$
\chi(X ; \mathcal{F}):=\chi(\mathcal{F}):=\sum_{i=0}^{\infty}(-1)^{i} h_{i}(X ; \mathcal{F}) .
$$

## Warning 14.1.3

This is not always well-defined!
Example 14.1.4(?): Let $X \in \mathrm{Mfd}_{\mathrm{cpt}}$ and take $\mathcal{F}:=\mathbb{R}$, we then have

$$
\chi(X ; \mathbb{R})=h^{0}(X ; \mathbb{R})-h^{1}(X ; \mathbb{R})+\cdots=b_{0}-b_{1}+b_{2}-\cdots:=\chi_{\text {Top }}(X) .
$$

Example 14.1.5(?): Let $X=\mathbb{C}$ and take $\mathcal{F}:=\mathcal{O}:=\mathcal{O}^{\text {holo }}$ the sheaf of holomorphic functions. We then have $h^{>0}(X ; \mathcal{O})=0$, but $H^{0}(X ; \mathcal{O})$ is the space of all holomorphic functions on $\mathbb{C}$, making $\operatorname{dim}_{\mathbb{C}} h^{0}(X ; \mathcal{O})$ infinite.

Example 14.1.6(?): Take $X=\mathbb{P}^{1}$ with $\mathcal{O}$ as above, $h^{0}\left(\mathbb{P}^{1} ; \mathcal{O}\right)=1$ since $\mathbb{P}^{1}$ is compact and the maximum modulus principle applies, so the only global holomorphic functions are constant. We can write $\mathbb{P}^{1}=\mathbb{C}_{1} \cup \mathbb{C}_{2}$ as a cover and $h^{i}(\mathbb{C}, \mathcal{O})=0$, so this is an acyclic cover and we can use it to compute $h^{1}\left(\mathbb{P}^{1} ; \mathcal{O}\right)$ using Čech cohomology. We have

- $C^{0}\left(\mathbb{P}^{1} ; \mathcal{O}\right)=\mathcal{O}\left(\mathbb{C}_{1}\right) \oplus \mathcal{O}\left(\mathbb{C}_{2}\right)$
- $C^{1}\left(\mathbb{P}^{1} ; \mathcal{O}\right)=\mathcal{O}\left(\mathbb{C}_{1} \cap \mathbb{C}_{2}\right)=\mathcal{O}\left(\mathbb{C}^{\times}\right)$.
- The boundary map is given by

$$
\begin{aligned}
\partial_{0}: C^{0} & \rightarrow C^{1} \\
(f(z), g(z)) & \mapsto g(1 / z)-f(z)
\end{aligned}
$$

and there are no triple intersections.
Is every holomorphic function on $\mathbb{C}^{\times}$of the form $g(1 / z)-f(z)$ with $f, g$ holomorphic on $\mathbb{C}$. The answer is yes, by Laurent expansion, and thus $h^{1}=0$. We can thus compute $\chi\left(\mathbb{P}^{1} ; \mathcal{O}\right)=1-0=1$.

## 15 Monday, February 15

Remark 15.0.1: Last time: we saw that $\chi\left(\mathbb{P}^{1}, \mathcal{O}\right)=1$, and we'd like to generalize to holomorphic line bundles on a Riemann surface. This will be the main ingredient for Riemann-Roch.

Theorem 15.0.2(Euler characteristic and homological vanishing for holomorphic vector bundles).
Let $X \in \mathrm{Mfd}_{\mathbb{C}}$ be compact and let $\mathcal{F}$ be a holomorphic vector bundle on $X{ }^{a}$ Then $\chi$ is well-defined and

$$
h^{>\operatorname{dim}_{\mathbb{C}} X}(X ; \mathcal{F})=0 .
$$

${ }^{a}$ Or more generally a finitely-generated $\mathcal{O}$-module, i.e. a coherent sheaf.
Remark 15.0.3: The locally constant sheaf $\mathbb{C}$ is not an $\mathcal{O}$-module, i.e. $\mathbb{C}(U) \notin \mathcal{O}(\mathbf{U})$-Mod. In fact, $h^{2 i}(X, \mathbb{C})=\mathbb{C}$ for all $i$.

## Proof (of theorem).

We'll can resolve $\mathcal{F}$ as a sheaf by first mapping to its smooth sections and continuing in the following way:

$$
0 \rightarrow \mathcal{F} \rightarrow C^{\infty} \mathcal{F} \xrightarrow{\bar{\sigma}} F \otimes A^{0,1} \rightarrow \cdots,
$$

where $\bar{\partial} f=\sum_{i} \frac{\partial f}{\partial \bar{z}_{i}} d \bar{z}_{i}$. Suppose we have a holomorphic trivialization of $\left.\mathcal{F}\right|_{U} \cong \mathcal{O}_{U}^{\oplus r}$ and we have sections ${ }^{2}\left(s_{1}, \cdots, s_{r}\right) \in C^{\infty} \mathcal{F}(U)$, which are smooth functions on $U$. In local coordinates we have

$$
\bar{\partial} s:=\left(\bar{\partial} s_{1}, \cdots, \bar{\partial} s_{r}\right),
$$

but is this well-defined globally? Given a different trivialization over $V \subseteq X$, the $s_{i}$ are related by transition functions, so the new sections are $t_{U V}\left(s_{1}, \cdots, s_{r}\right)$ where $t_{U V}: U \cap V \rightarrow \mathrm{GL}_{r}(\mathbb{C})$.

Since $t_{U V}$ are holomorphic, we have

$$
\bar{\partial}\left(t_{U V}\left(s_{1}, \cdots, s_{r}\right)\right)=t_{U V} \bar{\partial}\left(s_{1}, \cdots, s_{r}\right) .
$$

This makes $\bar{\partial}: C^{\infty} \mathcal{F} \rightarrow F \otimes A^{0,1}$ a well-defined (but not $\mathcal{O}$-linear) map. We can thus continue this resolution using the Leibniz rule:

$$
0 \rightarrow \mathcal{F} \rightarrow C^{\infty} \mathcal{F} \xrightarrow{\overline{\mathrm{o}}} F \otimes A^{0,1} \xrightarrow{\overline{\mathrm{o}}} \cdots F \otimes A^{0,2} \xrightarrow{\overline{\mathrm{~b}}} \cdots,
$$

which is an exact sequence of sheaves since $\left(A^{0,-}, \bar{\partial}\right)$ is exact.

## Why? Split into line bundles?

We can identify $C^{\infty} \mathcal{F}=\mathcal{F} \otimes A^{0,0}$, and $\mathcal{F} \otimes A^{0, q}$ is a smooth vector bundle on $X$. Using partitions of unity, we have that $\mathcal{F} \otimes A^{0, q}$ is acyclic, so its higher cohomology vanishes, and

$$
H^{i}(X ; \mathcal{F}) \cong \frac{\operatorname{ker}\left(\bar{\partial}: \mathcal{F} \otimes A^{0, i} \rightarrow \mathcal{F} \otimes A^{0, i+1}\right.}{\operatorname{im}\left(\bar{\partial}: \mathcal{F} \otimes A^{0, i-1} \rightarrow \mathcal{F} \otimes A^{0, i}\right.} .
$$

However, we know that $A^{0, p}=0$ for all $p>n:=\operatorname{dim}_{\mathbb{C}} X$, since any wedge of $p>n$ forms necessarily vanishes since there are only $n$ complex coordinates.

## Warning 15.0.4

This only applies to holomorphic vector bundles or $\mathcal{O}$-modules!

### 15.1 Riemann-Roch

Theorem 15.1.1(Riemann-Roch).
Let $C$ be a compact connected Riemann surface, i.e. $C \in \operatorname{Mfd}_{\mathbb{C}}$ with $\operatorname{dim}_{\mathbb{C}}(C)=1$, and let $\mathcal{L} \rightarrow C$ be a holomorphic line bundle. Then

$$
\chi(C, \mathcal{L})=\operatorname{deg}(L)+(1-g) \quad \text { where } \operatorname{deg}(L):=\int_{C} c_{1}(\mathcal{L})
$$

and $g$ is the genus of $C$.
Proof (of Riemann-Roch).
We'll introduce the notion of a "point bundle", which are particularly nice line bundles, denoted $\mathcal{O}(p)$ for $p \in \mathbb{C}$.


Taking $\mathbb{D}$ to be a disc of radius $1 / 2$ and $V$ to be its complement, we have $t_{u v}(z)=z^{-1} \in$ $\mathcal{O}^{*}(U \cap V)$. We can take a holomorphic section $s_{p} \in H^{0}(C, \mathcal{O}(p))$, where $\left.s_{p}\right|_{U}=z$ and $\left.s_{p}\right|_{V}=1$. Then $t_{u v}\left(\left.s_{p}\right|_{U}\right)=\left.s_{p}\right|_{V}$ on the overlaps. We have a function which precisely vanishes to first order at $p$. Recall that $c_{1}(\mathcal{O}(p))$ is represented by $[V(s)]=[p]$, and moreover $\int_{C} c_{1}(\mathcal{O}(p))=1$. We now want to generalize this to a divisor: a formal $\mathbb{Z}$-linear combination of points.
Example 15.1.2(?): Take $p, q, r \in C$, then a divisor can be defined as something like $D:=$ $2[p]-[q]+3[r]$.
Define $\mathcal{O}(D):=\bigotimes_{i} \mathcal{O}\left(p_{i}\right)^{\otimes n_{i}}$ for any $D=\sum n_{i}\left[p_{i}\right]$. Here tensoring by negatives means taking duals, i.e. $\mathcal{O}(-[p])^{i}:=\mathcal{O}^{\otimes-1}:=\mathcal{O}(p)^{\vee}$, the line bundle with inverted transition functions. $\mathcal{O}(D)$ has a meromorphic section given by

$$
s_{D}:=\prod s_{p_{i}}^{n_{i}} \in \operatorname{Mero}(C, \mathcal{O}(D))
$$

where we take the sections coming from point bundles. We can compute

$$
\int_{C} c_{1}(\mathcal{O}(D))=\sum n_{i}:=\operatorname{deg}(D)
$$

Example 15.1.3(?):

$$
\operatorname{deg}(2[p]-[q]+3[r])=4
$$

Remark 15.1.4: Assume our line bundle $L$ is $\mathcal{O}(D)$, we'll prove Riemann-Roch in this case by induction on $\sum\left|n_{i}\right|$. The base case is $\mathcal{O}$, which corresponds to taking an empty divisor. Then either

- Take $D=D_{0}+[p]$ with $\operatorname{deg}\left(D_{0}\right)<\sum\left|n_{i}\right|$ (for which we need some positive coefficient), or
- Take $D_{0}=D+[p]$.

Claim: There is an exact sequence

$$
\begin{gathered}
0 \rightarrow \mathcal{O}\left(D_{0}\right) \rightarrow \mathcal{O}(D) \rightarrow \mathbb{C}_{p} \rightarrow 0 \\
s \in \mathcal{O}\left(D_{0}\right)(U) \mapsto s \cdot s_{p} \in \mathcal{O}\left(D_{0}+[p]\right)(U)
\end{gathered}
$$

where the last term is the skyscraper sheaf at $p$.
Proof (of claim).
The given map is $\mathcal{O}$-linear and injective, since $s_{p} \neq 0$ and $s s_{p}=0$ forces $s=0$. Recall that we looked at $\mathcal{O} \stackrel{z}{\rightarrow} \mathcal{O}$ on $\mathbb{C}$, and this section only vanishes at $p$ (and to first order). The same situation is happening here.

Thus there is a LES


We also have $h^{1}\left(\mathbb{C}_{p}\right)=0$ by taking a sufficiently fine open cover where $p$ is only in one open set. So just checking Čech cocycles yields $C_{U}^{1}\left(C, \mathbb{C}_{p}\right):=\prod_{i<j} \mathbb{C}_{p}\left(U_{i} \cap U_{j}\right)=0$ since $p$ is in no intersection.


We obtain $\chi\left(\mathcal{O}(D)=\chi\left(\mathcal{O}\left(D_{0}\right)\right)+1\right.$, using that it is additive in SESs

$$
0 \rightarrow \mathcal{E}_{1} \rightarrow \mathcal{E}_{2} \rightarrow \mathcal{E}_{3} \rightarrow 0 \Longrightarrow \quad \chi\left(\mathcal{E}_{2}\right)=\chi\left(\mathcal{E}_{\infty}\right)+\chi\left(\mathcal{E}_{3}\right)
$$

and thus

$$
\int_{C} c_{1}(\mathcal{O}(D))=\sum n_{i}=\operatorname{deg}(D)=\operatorname{deg} D_{0}+1 .
$$

The last step is to show that $\chi(C, \mathcal{O})=1-g$, so just define $g$ so that this is true!

Remark 15.1.5: Why is every $L \cong \mathcal{O}(D)$ for some $D$ ? Easy to see if $L$ has meromorphic sections: if $s$ is a meromorphic section of $L$, then the following works:

$$
D=\operatorname{Div}(s)=\sum_{p} \operatorname{Ord}_{p}(s)[p] .
$$

Then $\mathcal{O} \cong L \otimes \mathcal{O}(-D)$ has a meromorphic section $s s_{-D}$, a global nonvanishing section with $\operatorname{Div}\left(s s_{-D}\right)=\emptyset$. Proving that every holomorphic line bundle has a meromorphic section is hard!

## 16 Friday, February 19

### 16.1 Applications of Riemann-Roch

Definition 16.1.1 (Curves)
A curve is a compact complex manifold of complex dimension 1.
Example 16.1.2 (?): Let $C$ be a curve, then $\Omega_{C}^{1}$ is the sheaf of holomorphic 1-forms, and $\Omega_{C}^{>1}=0$. We also have the sheaves $A^{1,0}, A^{0,1}, A^{1,1}$, the sheaves of smooth $(p, q)$-forms. Here the only nonzero combinations are $(0,0),(0,1),(1,0),(1,1)$ by dimensional considerations. Let $L$ be a holomorphic line bundle on $C$, then

$$
\chi(C, L)=h^{0}(L)-h^{1}(L)=\operatorname{deg}(L)+1-g .
$$

Remark 16.1.3: In general it can be hard to compute $h^{1}(L)$, since this is sheaf cohomology (sections over double overlaps, cocycle conditions, etc). On the other hand, $h^{0}$ is easy to understand, since $h^{0}\left(\Omega_{C}^{1}\right)$ is the dimension of the global holomorphic sections $H^{0}(C, L)=L(C)$. A key tool here is the following:

### 16.1.1 Serre Duality

## Proposition 16.1.4(Serre Duality).

$$
H^{1}(C, L) \cong H^{0}\left(C, L^{-1} \otimes \Omega_{C}^{1}\right)^{\vee}
$$

noting that these are both global sections of a line bundle.

## Proof (of Serre Duality).

Recall that we had a resolution of the sheaf $L$ given by byooth vector bundles:

$$
0 \rightarrow L \hookrightarrow L \otimes A^{0,0} \xrightarrow{\bar{\sigma}} L \otimes A^{0,1} \xrightarrow{\bar{\sigma}} 0 .
$$

So we know that

$$
H^{1}(C, L)=H^{0}\left(L \otimes A^{0,1}\right) / \bar{\partial} H^{0}\left(L \otimes A^{0,0}\right) .
$$

Choose a Hermitian metric $h$ on $L$, i.e. a map $h: L \otimes \bar{L} \rightarrow \mathcal{O}$. On fibers, we have $h_{p}$ : $L_{p} \otimes \overline{L_{p}} \rightarrow \mathbb{C}$. We'll also choose a metric on $C$, say $g$. Since $C$ is a Riemann surface, we have an associated volume form $\nu$ on $C$ (essentially the determinant), so we can define a pairing between sections of $L \otimes A^{0,0}$ :

$$
\langle s, t\rangle:=\int_{C} h(s, \bar{t}) d \nu
$$

Note that

$$
\langle s, s\rangle=\int_{C} h(s, \bar{s}) d \nu \geq 0 \quad \text { since } h(s, \bar{s})(p)=0 \Longleftrightarrow s_{p}=0,
$$

and moreover this integral is zero if and only if $s=0$. So we have an inner product on $H^{0}\left(L \otimes A^{0,0}\right)$. We can also define a pairing on sections of $L \otimes A^{0,1}$, say

$$
\langle s \otimes \alpha, t \otimes \beta\rangle=\int_{C} h(s, \bar{t}) \alpha \wedge \bar{\beta} .
$$

Note that $h$ is a smooth function and $\alpha \wedge \bar{\beta}$ is a (1,1)-form. Moreover, this is positive and nondegenerate. We want to understand the cokernel of the linear map

$$
H^{0}\left(L \otimes A^{0,0}\right) \xrightarrow{\bar{\sigma}} H^{0}\left(L \otimes A^{0,1}\right) .
$$

To compute $\operatorname{coker}(\bar{\partial})$, we can look at the kernel of the adjoint, and it suffices to find the orthogonal complement of $\operatorname{im}(\bar{\partial})$, i.e.

$$
\operatorname{coker}(\bar{\partial})=\left\{t \in H^{0}\left(L \otimes A^{0,1}\right) \mid\langle\bar{\partial} s, t\rangle=0 \forall s\right\}
$$



So we want to understand sections $t \in H^{0}\left(L \otimes A^{0,1}\right)$ such that

$$
\int_{C}(\bar{\partial} s) \bar{t}=0 \quad \forall s \in H^{0}\left(L \otimes A^{0,0}\right),
$$

where $\partial C=\emptyset$. We'll basically want to do integration by parts on this. Note that $h(s, t)=h s t$ here where we view $h$ as a certain section. Note that $\bar{t} \in H^{0}\left(\bar{L} \otimes A^{1,0}\right)$, so we can replace $\partial$ with $d=\bar{\partial}+\partial$ and apply Stokes' theorem:

$$
\begin{array}{rlr}
\int_{C} s d(h \bar{t}) & =0 & \forall s \in H^{0}\left(L \otimes A^{0,0}\right) \\
0 & =\int_{C} s \bar{\partial}(h \bar{t}) & \\
& =\int_{C} s \frac{\bar{\partial}(h \bar{t})}{d \nu} d \nu & \overline{\bar{\partial}(h \bar{t})} \\
& =\left\langle s, \frac{d \nu}{d \nu}\right.
\end{array}
$$

where $h \in C^{\infty}\left(L^{-1} \otimes \bar{L}^{-1}\right)$ and $h \bar{t} \in C^{\infty}\left(L^{-1} \otimes A^{1,0}\right)$. But the right-hand side is in $H^{0}\left(L \otimes A^{0,0}\right)$ and by nondegeneracy we can conclude

$$
\frac{\overline{\bar{\partial}(h \bar{t})}}{d \nu}=0 \Longleftrightarrow \bar{\partial}(h \bar{t})=0 .
$$

We thus have $h \bar{t} \in H^{0}\left(L^{-1} \otimes A^{1,0}\right.$ which is a holomorphic line bundle tensored with $A^{0,0}$. Thus $\operatorname{coker}(\bar{\partial}) \cong_{h} H^{0}\left(L^{-1} \otimes \Omega^{1}\right)$.

Remark 16.1.5: We showed $\langle\bar{\partial} s, t\rangle=\langle s, Y(t)\rangle$ where $Y$ is the adjoint given above. Then the kernel of $Y$ wound up being where $\bar{\partial}$ vanishes, i.e. holomorphic sections of a separate bundle. Here we had

- $t \in H^{0}\left(L \otimes A^{0,1}\right)$
- $\bar{t} \in H^{0}\left(\bar{L} \otimes A^{1,0}\right)$
- $h \in H^{0}\left(L^{-1} \otimes \overline{L^{-1}}\right)$


## 17 Monday, February 22

Remark 17.0.1: Last time: Serre duality, and we'll review Riemann-Roch. Recall that this depended on the statement that every holomorphic line bundle $L \rightarrow C$ for $C$ a complex curve is of the form $L=\mathcal{O}(D)$ for some divisor $D$. Then

$$
\chi(C, L)=h^{0}(L)-h^{1}(L)=\operatorname{deg} L+1-g, \quad \operatorname{deg} L=\int_{C} c_{1}(L),
$$

Serre duality said that the space of sections $H^{1}(C ; L)$ is naturally isomorphic to $H^{0}\left(C, L^{-1} \otimes \Omega_{C}^{1}\right)^{\vee}$. Notation: given $X \in \mathrm{Mfd}_{\mathbb{C}}^{n}$ of complex, dimension $n$, the canonical bundle is written $K_{X}:=\Omega_{X}^{n}$ and is the sheaf of holomorphic $n$-forms. Serre duality will generalize: if $\mathcal{E} \rightarrow X$ is a holomorphic vector bundle, then $H^{i}(X ; \mathcal{E}) \cong H^{n-i}\left(X ; \mathcal{E}^{\vee} \otimes K_{X}\right)^{\vee}$. Note that only $H^{0}, H^{1}$ are the only nontrivial degrees for a curve. For 4 -manifolds, we'll have an $H^{2}$ as well.

### 17.1 Applications of Riemann-Roch

Proposition 17.1.1(The 2-sphere has a unique complex structure).
There is a unique complex $X \in \operatorname{Mfd}_{\mathbb{C}}$ diffeomorphic to $S^{2}$.

Proof (of proposition).
Note existence is clear, since we can take $\mathbb{C P}^{1}:=\left(\mathbb{C}^{2} \backslash\{0\}\right) / \mathbf{x} \sim \lambda \mathbf{x}$ for $\lambda \in \mathbb{C}^{\times}$, which is identified as the set of complex lines through 0 in $\mathbb{C}^{2}$. This decomposes as $\mathbb{C} \cup \mathbb{C}=$
$\{[1, *]\} \cup\{[*, 1]\}$. We now want to show that any two such complex manifolds are biholomorphic. Let $X \in \mathrm{Mfd}_{\mathbb{C}}^{1}$ with $X \cong_{C^{\infty}} S^{2}$, and consider for $p \in X$ the point bundle $\mathcal{O}(p) \rightarrow X$. The defining property was that there exists a section $s_{p} \in H^{0}(X ; \mathcal{O}(p))$ which vanishes at first order at $p$ :


We have

$$
\chi(X ; \mathcal{O}(p))=\operatorname{deg} \mathcal{O}(p)+1-g(x)=1+1-0=2 .
$$

Exercise (?)
Check that $\operatorname{deg} \mathcal{O}(p)=1$.
On the other hand we have

$$
\chi(X ; \mathcal{O}(p))=h^{0}(\mathcal{O}(p))-h^{1}(\mathcal{O}(p)) .
$$

We have $h^{1}(\mathcal{O}(p))=H 60\left(K \otimes \mathcal{O}(-p)\right.$, and $K_{X}=\Omega_{X}^{1}=T^{\vee} X$, so the question is: what is the degree of $T X$ for $X \cong S^{2}$ ? We need to compute $\int_{X} c_{1}(T X)$. How many zeros does a vector field on the sphere have? You can take the gradient vector field for a height function to get 2, noting that the two zeros come in with a positive orientation


In coordinates on $\mathbb{C P}^{1}$, the coordinate is given by $z$ and $z \frac{\partial}{\partial z} \mapsto-2 \frac{\partial}{\partial w}$ for the coordinate $w=1 / z$. We get $\int_{X} c_{1}(T X)=2$ and thus deg $K_{X}=-2$ by dualizing.

## Fact

$\operatorname{deg} K_{X}=2 g-2$. Use the existence of a smooth vector field on $X$.

Lemma 17.1.4 (When h0 of a line bundle on a curve vanishes).
If $\operatorname{deg} L<0$ on $C$, thne $h^{0}(C, L)=0$.

## Proof (of lemma).

If $s \in H^{0}(C, L)$ is nonzero, then since $s$ is a holomorphic section,

$$
0 \leq \sum_{p \in C} \operatorname{Ord}_{P}(s)=\operatorname{deg} L
$$

By this lemma, $h^{1}(\mathcal{O}(p))=0$. We have $H^{0}(X ; \mathcal{O}(p))=\mathbb{C} s_{p} \oplus \mathbb{C} s$ for our specific section $s_{p}$ and some other section $s \neq \lambda s_{p}$. Note that $s / s_{p}$ is a meromorphic section of $\mathcal{O}(p) \times \mathcal{O}(-p)=\mathcal{O}$, so we have a map

$$
\varphi: \frac{s}{s_{p}}: X \rightarrow \mathbb{P}^{1}
$$

Note that $P \mapsto \infty \in \mathbb{P}^{1}$ under this $\varphi$, and it's only the ratio that is well-defined. We have $\varphi^{-1}(u)=\left\{s / s_{p}=u\right\}=\left\{s-u s_{p}=0\right\}$ which is a single point. So $\varphi$ is a degree 1 map, and $X$ is biholomorphic to $\mathbb{P}^{1}$ via $\varphi$.

Remark 17.1.5: So there is only one genus 0 Riemann surface. What about genus 1 ?


By Riemann-Roch we know

$$
\chi(C ; \mathcal{O})=\operatorname{deg} \mathcal{O}+l-1=0=h^{0}(\mathcal{O})-h^{1}(\mathcal{O})
$$

We know $h^{0}(\mathcal{O})=1$ by the maximum modulus principle and $h^{1}(C ; \mathcal{O})=1$. By Serre duality, $h^{0}(C, K)=1$, and since $\operatorname{deg} K=2 g-2=0$. So let $s \in H^{0}(C, K)$ by a nonzero section, which we know exists. We then get $\operatorname{Ord}_{p} s=0$ for all $p$, so $s$ vanishes nowhere. But then we get an isomorphism of sheaves, since $s$ everywhere nonvanishing implies trivial cokernel:

$$
\mathcal{O} \xrightarrow{\cdot s} K .
$$

So $K_{C}=\mathcal{O}_{C}$ if $g(C)=1$, and such a Riemann surface is an elliptic curve.

Example 17.1.6(?): Let $C:=\mathbb{C} / \Lambda$ for $\Lambda$ some lattice.


All transition functions are of the form $z \mapsto z+\lambda$ for some $\lambda \in \Lambda$. What is a nonvanishing section of $K_{C}$, i.e. a holomorphic one form $\omega:=f(z) d z$ on $\mathbb{C}$ that descends to $\mathbb{C} / \Lambda$. We would need $f(z) d z=f(z+\lambda) d(z+\lambda)$ for all $\lambda$. Something like $f=1$ works, so $\omega=d z$ descends. In fact, $f$ must be constant, since $H^{0}(\mathbb{C} / \Lambda, \mathcal{O})=\mathbb{C} d z$ by the maximum modulus principle. Now let $p, q \in C$
and apply Riemann-Roch to the line bundle $\mathcal{O}(p+q)$ yields

$$
\begin{aligned}
\chi(\mathcal{O}(p+q)) & =h^{0}(\mathcal{O}(p+q))-h^{1}(\mathcal{O}(-p-q)) \\
& =h^{0}(\mathcal{O}(p+q))-0 \\
& =\operatorname{deg} \mathcal{O}(p+q)+1-1 \\
& =2 .
\end{aligned}
$$

Thus there is a section $s_{p+q} \in H^{0}(\mathcal{O}(p+q)) \ni s$ that vanishes at $p+q$, and similarly a map

$$
\frac{s}{s_{p+q}}: C \xrightarrow{\varphi} \mathbb{P}^{1}
$$

We can check $\varphi^{-1}(\infty)=p+q$ and $\operatorname{deg} \varphi=2$. Thus genus 1 surfaces have a generically 2 -to- 1 map to $\mathbb{P}^{1}$.


Figure 2: image_2021-02-25-20-41-53

Note that homothetic lattices define an isomorphism between the elliptic curves, and lattices mod homothety are in correspondence of elliptic curves. By acting $\mathrm{PGL}_{2}(C) \curvearrowright \mathbb{P}^{1}$ since $\mathrm{GL}_{2}$ acts on lines since scaling an element fixes a line. This is dimension 3. So elliptic curves are also in correspondence with $\left\{4\right.$ points on $\left.\mathbb{P}^{1}\right\} / \mathrm{PGL}_{2}(\mathbb{C})$ since this is now dimension 1 . Note that by applying homothety, the two basis vectors for a lattice can be rescaled so one is length 1 and the other is a complex number $\tau$, and we can identify this space with $\mathbb{H} / \mathrm{SL}_{2}(\mathbb{Z})$.

Exercise 17.1.7 (?)
Show that any $g(C)=2$ curve has a degree 2 map to $\mathbb{P}^{1}$.

Remark 17.1.8: Similarly $g(C)=3$ are usually a curve of degree 4 in $\mathbb{C P}^{2}$. Severi proof in the 50 s: false! issues with building moduli space for $g \geq 23$. Need to use orbifold structure to take into account automorphisms.

## 18 Wednesday, February 24

Last time:

$$
\begin{aligned}
\chi(C, L) & =h^{0}(C, L)-h^{1}(C, L) \\
& =h^{0}(C, L)-h^{0}\left(C, L^{-1} \otimes K_{C}\right) \\
& =\operatorname{deg} L+1-g
\end{aligned}
$$

which is determined by purely topological information. We can generalize this to arbitrary ranks of the bundle and arbitrary dimensions of manifold:

Theorem 18.0.1(Hirzebruch-Riemann-Roch (HRR) Formula).
Let $X$ be a compact complex manifold and let $\mathcal{E} \rightarrow X$ be a holomorphic vector bundle. Then

$$
\chi(\mathcal{E})=\int_{C} \operatorname{ch}(\mathcal{E}) \operatorname{td}(X)
$$

The constituents here:

- The Chern character, summed over $R$ the Chern roots, which is in mixed cohomological degree.

$$
\operatorname{ch}(\mathcal{E}):=\sum_{x_{i} \in R} e^{x_{i}}=\operatorname{ch}_{0}(\mathcal{E})+\operatorname{ch}_{1}(\mathcal{E})+\cdots+\operatorname{ch}_{i}(\mathcal{E}) \in H^{2 i}(X ; \mathbb{Q})
$$

- The Todd class, defined as

$$
\operatorname{td}(F):=\prod_{x_{i} \in R} \frac{x_{i}}{1-e^{-x_{i}}}
$$

where $\operatorname{td}(X):=\operatorname{td}(T X)$ is viewed as a complex vector bundle, which is again in mixed cohomological degree.

Remark 18.0.2: Note that integrating over cohomology classes in mixed degree is just equal to the integral over the top degree terms. Applying this to $X=C$ a curve and $\mathcal{E}:=\mathcal{O}$, we obtain

$$
\chi(C, \mathcal{O})=\int_{C} \operatorname{ch}(\mathcal{O}) \operatorname{td}(C)
$$

We have

- $\operatorname{ch}(\mathcal{O})=e^{c_{1}(\mathcal{O})}=e^{0}=1$
- $\operatorname{td}(C):=\operatorname{td}(T C)=c_{1}(T C) /\left(1-e^{-c_{1}(T C)}\right)$, whose Taylor coefficients are the Bernoulli numbers. We can expand $x /\left(1-e^{-x}\right)=1+(x / 2)+\left(x^{2} / 12\right)-x^{4}(720)+\cdots$, and since terms above degree 2 vanish, we have

$$
\begin{array}{rlr}
\cdots & =\int_{C} 1+\left(1+\frac{c_{1}(T C)}{2}\right) \\
& =\int_{C}\left(\frac{c_{1}(T C)}{2}\right) \\
& =\frac{1}{2} \chi_{\operatorname{Top}}(C) \\
& =\frac{2-2 g}{2} \\
& =1-g
\end{array} \quad \text { Chern-Gauss-Bonnet }
$$

We thus obtain

$$
\begin{aligned}
\chi(C, L) & =\int_{C} \operatorname{ch}(L) \operatorname{td}(C) \\
& =\int_{C}\left(1+c_{1}(L)\right)\left(1+\frac{c_{1}(L)}{2}\right) \\
& =\int_{C} c_{1}(L)+\frac{c_{1}(T C)}{2} \\
& =\operatorname{deg} L+1-g
\end{aligned}
$$

Remark 18.0.3: Note that this is a better definition of genus than the previous one, which was just the correction term in Riemann-Roch. Here we can define it as $g:=h^{1} / 2$.

Exercise 18.0.4 (?)
Try to state and prove a Riemann-Roch formula for vector bundles on curves.

Proposition 18.0.5(Formula for Euler characteristic of a line bundle on a complex surface).
Let $S$ be a compact complex surface, i.e. $S \in \mathrm{Mfd}_{\mathbb{C}}^{2}$. An example might be $C \times D$ for $C, D$ two complex curves, or $\mathbb{C P}{ }^{2}$. Let $L \rightarrow S$ be a holomorphic vector bundle. Then

$$
\chi(L)=\chi\left(\mathcal{O}_{S}\right)+\frac{1}{2}\left(L^{2}-L \cdot K\right)
$$

Note that $L^{2}:=\int_{S} c_{1}(L) c_{1}(L)$ is just shorthand for taking the intersection of $L$ with itself. Recall that $K:=\Omega_{S}^{2}$ is the space of holomorphic top forms.

Proof (?).

Let $x_{1}, x_{2}$ be the Chern roots of $T S$. By HRR, we have

$$
\begin{aligned}
\chi(L) & =\int_{S} \operatorname{ch}(L) \operatorname{td}(S) \\
& =\int_{S}\left(1+c_{1}(L)+\frac{c_{1}(L)^{2}}{2!}\right)\left(\frac{x_{1}}{1-e^{-x_{1}}} \frac{x_{2}}{1-e^{-x_{2}}}\right) \\
& =\int_{S}\left(1+c_{1}(L)+\frac{c_{1}(L)^{2}}{2!}\right)\left(1+\frac{x_{1}}{2}+\frac{x_{1}^{2}}{12}\right)\left(1+\frac{x_{2}}{2}+\frac{x_{2}^{2}}{12}\right) \\
& =\int_{S}\left(1+c_{1}(L)+\frac{c_{1}(L)^{2}}{2!}\right)\left(1+\frac{x_{1}+x_{2}}{2}+\frac{x_{1}^{2}+x_{2}^{2}+3 x_{1} x_{2}}{12}\right) \\
& =\int_{S}\left(1+c_{1}(L)+\frac{c_{1}(L)^{2}}{2!}\right)\left(1+\frac{c_{1}\left(x_{1}, x_{2}\right)}{2}+\frac{c_{1}\left(x_{1}, x_{2}\right)^{2}+c_{2}\left(x_{1}, x_{2}\right)}{12}\right) \\
& =\int_{S}\left(1+c_{1}(L)+\frac{c_{1}(L)^{2}}{2!}\right)\left(1+\frac{c_{1}(T)}{2}+\frac{c_{1}(T)^{2}+c_{2}(T)}{2}\right) \\
& =\int_{S} \frac{c_{1}(L)^{2}}{2}+\frac{c_{1}(L) c_{1}(T)}{2}+\frac{c_{1}(T)^{2}}{2}+\frac{c_{2}(T)}{12} \text { Take deg 4} \\
& =\int_{S}\left(\frac{c_{1}(L)^{2}+c_{1}(L) c_{1}(T)}{2}\right)+\chi\left(\mathcal{O}_{S}\right) \quad \text { HRR on last two terms. }
\end{aligned}
$$

where we've applied $\operatorname{HRR}$ to $\mathcal{O}_{S}$. It remains to show that $c_{1}(T)=-c_{1}(K)$. We have

$$
K=\Omega_{S}^{2}=\bigwedge^{2} T^{\vee} .
$$

Note that $\bigwedge^{\text {top }} \mathcal{E}:=\operatorname{det}(\mathcal{E})$ for any bundle $\mathcal{E}$ since this is a 1 -dimensional bundle. We have $c_{1}(T)=-c_{1}\left(T^{\vee}\right)$ since the Chern roots of $T^{\vee}$ are $-x_{1},-x_{2}$. So it suffices to show $c_{1}\left(T^{\vee}\right)=c_{1}(K)$, but there is a general result that $c_{1}(\mathcal{E})=c_{1}(\operatorname{det} \mathcal{E})$. This uses the splitting principle $\mathcal{E}=\bigoplus_{i=1}^{r} L_{i}$ with $x_{i}=c_{1}\left(L_{i}\right)$. We have $c_{1}(\mathcal{E})=\sum x_{i}$ and $\operatorname{det} \mathcal{E}=\bigotimes_{i=1}^{r} L_{i}$, so $\sum x_{i}=c_{1}\left(L_{1} \otimes \cdots \otimes L_{r}\right)$.

Remark 18.0.6: We want to use the following formula:

$$
\chi(S, L)=\chi\left(\mathcal{O}_{S}\right)=\frac{1}{2}\left(L^{2}-L \cdot K\right) .
$$

This requires knowing $\chi\left(\mathcal{O}_{S}\right)$. Applying HRR yields

$$
\begin{aligned}
\chi\left(\mathcal{O}_{S}\right) & =\int_{S} \frac{c_{1}(T)^{2}+c_{2}(T)}{12} \\
& =\int_{S} \frac{\left(-c_{1}(K)\right)^{2}+c_{2}(T)}{12} \\
& =\frac{K^{2}+\int_{S} c_{2}(T)}{12},
\end{aligned}
$$

so we just need to understand $\int_{S} c_{2}(T)$. But for $n=\operatorname{rank} \mathcal{E}, c_{n}(\mathcal{E})$ (the top Chern class) is the fundamental class of a zero locus of a section of $\mathcal{E}$. Note that $S \in \operatorname{Mfd}_{\mathbb{R}}^{4}$ is oriented, so $\int_{S} c_{2}(T)$ is the signed number of zeros of a smooth vector field.


Figure 3: image_2021-02-25-20-42-49

## Check.

Looking at the tangent bundle of the surface, the local sign of an intersection will be the number of incoming directions $(\bmod 2)$, i.e. the index of the critical point. Then the signed number of zeros here yields $1-6+1=-4=\chi_{\text {Top }}(C)$. More generally, we have

$$
\chi_{\mathrm{Top}}\left(M^{n}\right)=\int_{C} c_{n}(T M),
$$

the Chern-Gauss-Bonnet formula. We can thus write

$$
\chi\left(\mathcal{O}_{S}\right)=\frac{K^{2}+\chi_{\text {Top }}(S)}{12} .
$$

## 19 Friday, February 26

Remark 19.0.1: Last time: Riemann-Roch for surfaces, today we'll discuss some examples. Recall that if $S \in \mathrm{Mfd}_{\mathbb{C}}^{2}$ is closed and compact (noting that $S \in \mathrm{Mfd}_{\mathbb{R}}^{4}$ ) and $L \rightarrow S$ is a holomorphic line bundle then

$$
\chi(S, L)=\chi\left(\mathcal{O}_{S}\right)+\frac{1}{2}\left(L^{2}-L \cdot K\right)
$$

where $K=c_{1}\left(K_{S}\right)$ for $K_{S}:=\Omega_{S}^{2}$ the canonical bundle and $L=c_{1}(L)$. We also saw

$$
\chi\left(\mathcal{O}_{S}\right)=\frac{1}{12}\left(K^{2}+\chi_{\text {Top }}(S)\right),
$$

where $\chi_{\text {Top }}$ is the Euler characteristic and is given by

$$
\chi_{\text {Top }}(S)=2 h^{0}(S ; \mathbb{C})-2 h^{1}(S, \mathbb{C})+h^{2}(S ; \mathbb{C}) .
$$

Example 19.0.2 (?): Let $S=\mathbb{C P}^{2}$, which can be given in local coordinates by

$$
\left\{\left[x_{0}: x_{1}: x_{2}\right] \mid\left(x_{0}, x_{1}, x_{2}\right) \in \mathbb{C}^{3} \backslash\{0\}\right\}
$$

where we only take equivalence classes of ratios $[x, y, z]=[\lambda x, \lambda y, \lambda z]$ for any $\lambda \in \mathbb{C}^{\times}$. This decomposes as

$$
\mathbb{C P}^{2} \cup \mathbb{C} \cup\{p t\}=\left\{\left[1: x_{1}: x_{2}\right]\right\} \cup\left\{\left[0: x_{1}: x_{2}\right]\right\} \cup\{[0: 0: 1]\},
$$

i.e. we take $x_{0} \neq 0$, then $x_{0}=0, x_{1} \neq 0$, then $x_{0}=x_{1}=0$. Note that

$$
h^{i}\left(\mathbb{C P}^{n} ; \mathbb{Z}\right)= \begin{cases}\mathbb{Z} & 0 \leq i \leq 2 n \text { even } \\ 0 & \text { else }\end{cases}
$$

We can use this to conclude that $\chi_{\text {Top }}\left(\mathbb{C P}^{n}\right)=n+1$ and $\chi_{\text {Top }}\left(\mathbb{C P}^{2}\right)=3$. Over $\mathbb{C P}^{n}$ we have a tautological line bundle $\mathcal{O}(-1)$ given by sending each point to the corresponding line in $\mathbb{C}^{n+1}$, i.e. $\mathcal{O}(-1) \rightarrow \mathbb{C P}^{n}$ given by

$$
\lambda\left(x_{0}, \cdots, x_{n}\right) \mapsto\left[x_{0}: \cdots: x_{n}\right] .
$$

Note that the total space is $\underset{0}{\mathrm{Bl}}\left(\mathbb{C}^{n+1}\right)$ is the blowup at zero, which separates the tangents at 0 .

Remark 19.0.3: Let $X$ be an algebraic variety, i.e. spaces cut out by polynomial equations, for example $\{x y=0\} \subseteq \mathbb{C}^{2}$ which has a singularity at the origin. A divisor is a $\mathbb{Z}$-linear combination of subvarieties of codimension 1 . Note that for a curve $X$, this recovers the definition involving points. For $D$ a divisor on $X$, we associated a bundle $\mathcal{O}_{X}(D)$ which had a meromorphic section with a zero/pole locus whose divisor was precisely $D$.

Recall the construction: we chose a point, then a trivializing neighborhood where the transition functions where $V$.

## On annulus:

$$
D=\mathrm{pt} \quad t_{U V}=z
$$



For a higher dimensional algebraic variety or complex manifold, for $D$ a complex submanifold, pick a chart around a point that the nearby portion of $D$ to a coordinate axis in $\mathbb{C}^{n}$, which e.g. can be given by $\left\{z_{1}=0\right\}$.


As before there's a distinguished section $s_{D} \in H^{0}\left(X ; \mathcal{O}_{X}(D)\right)$ vanishing along $D$. Note that a line bundle is a free rank $1 \mathcal{O}$-module, and analogously here the functions vanishing along $D$ are $\mathcal{O}$-modules generated by (here) $z_{1}$.

Definition 19.0.4 (Hyperplane)

A hyperplane in $\mathbb{C P}^{n}$ is any set of the form

$$
H=\left\{\left[x_{0}: \cdots: x_{1}\right] \mid \sum a_{i} x_{i}=0\right\} \cong \mathbb{C P}^{n-1}
$$

Example 19.0.5(?): Take $\mathbb{C P}^{n-1} \subseteq \mathbb{C P}^{n}$, e.g. $\left\{x_{0}=0\right\}$. This is an example of a divisor on $\mathbb{C P}^{n}$, i.e. a complex codimension 1 "submanifold". We can take the line bundle constructed above to get $\mathcal{O}_{\mathbb{C P}^{n}}\left(\mathbb{C P}^{n-1}\right)$ which vanishes along $\mathbb{C P}^{n-1}$. More generally, for any hyperplane $H$ we can take $\mathcal{O}_{\mathbb{C P}^{n}}(H)$, and these are all isomorphic, so we'll denote them all by $\mathcal{O}_{\mathbb{C P}^{n}}(1)$. The implicit claim is that is the inverse line bundle of the tautological bundle, so $\mathcal{O}(1) \otimes \mathcal{O}(-1)$ is the trivial bundle since the transition functions are given by reciprocals and multiplying them yields 1 . We can classify complex line bundles on $\mathbb{C P}^{n}$ using the SES

$$
0 \rightarrow \underline{\mathbb{Z}} \rightarrow \mathcal{O} \xrightarrow{\exp } \mathcal{O}^{\times} \rightarrow 1
$$

We know that $H^{1}\left(X ; \mathcal{O}^{\times}\right)$were precisely holomorphic line bundles, since they were functions agreeing on double overlaps with a cocycle condition. We have a LES coming from sheaf cohomology:


## Link to Diagram

Applying this to $X:=\mathbb{C P}^{n}$, we have $H^{1}(\mathcal{O})=H^{2}(\mathcal{O})=0$. This can be computed directly using that $\mathbb{C} \mathbb{P}^{n}=\cup_{n \geq 1} \mathbb{C}^{n}$ by taking charts $x_{i} \neq 0$, and this yields an acyclic cover. Thus $c_{1}$ is an isomorphism above, and $\operatorname{Pic}\left(\mathbb{C} \mathbb{P}^{n}\right) \cong \mathbb{Z}$, where Pic denotes isomorphism classes of line bundles. We can identify $\operatorname{Pic}\left(\mathbb{C P}^{n}\right)=\left\{\mathcal{O}_{\mathbb{C P}^{n}}(k) \mid k \in \mathbb{Z}\right\}$.

## 20 Monday, March 01

Remark 20.0.1: Last time: we defined $\operatorname{Pic}\left(\mathbb{C P}^{n}\right)$ as the set of line bundles on $\mathbb{C} \mathbb{P}^{n}$.

Definition 20.0.2 (Picard Group of a Manifold)
Given any $X \in \mathrm{Mfd}_{\mathbb{C}}$, define $\operatorname{Pic}(X)$ as the set of isomorphism classes of holomorphic line bundles on $X$. This is an abelian group given by $L \otimes L^{\prime}$ and inversion $L \rightarrow L^{-1}$.

Remark 20.0.3: We saw that $\operatorname{Pic}(X) \cong H^{1}\left(X ; \mathcal{O}^{\times}\right)$as groups, noting that $H^{1}$ has a natural group structure here. We defined a tautological bundle on $\mathbb{C P}^{n}$ and saw it was isomorphic to $\mathcal{O}(-1)$, and moreover $\mathcal{O}(H) \cong \mathcal{O}(1)$ for $H$ a hyperplane. The fiber was given by

$$
\begin{aligned}
\text { Taut } & \rightarrow \mathbb{C P}^{n} \\
\left\{\lambda\left(x_{0}, \cdots, x_{n}\right) \mid \lambda \in \mathbb{C}\right\} & \mapsto\left[x_{0}: \cdots: x_{n}\right]
\end{aligned}
$$

i.e. the entire line corresponding to the given projective point. We also have $\mathcal{O}(H)(U)$ is the sect of rational homogeneous functions $\varphi$ on $U$ of degree 1 such that $\operatorname{Div} \varphi+H \geq 0$ where $H:=\left\{x_{0}=0\right\}$. We want $\varphi / x_{0}$ to be a well-defined function, so $\varphi$ should scale like $x_{0}$ in the sense that

$$
\varphi\left(\lambda x_{0}, \cdots, \lambda x_{n}\right)=\lambda \varphi\left(x_{0}, \cdots, x_{n}\right)
$$

Note that there is a natural map

$$
\text { Taut } \otimes \mathcal{O}(H) \rightarrow \mathcal{O}
$$

given by taking the line over a point and evaluating the homogeneous function on that line. Thus Taut is the inverse of $\mathcal{O}(H)$.

Remark 20.0.4: We want to understand what Noether's formula says for $\mathbb{C P}^{2}$, which requires understanding the canonical bundle $K_{\mathbb{C P}^{n}}$. We'll do this by writing down a meromorphic section $\omega$ (since it's a meromorphic volume form) which will yield $K_{\mathbb{C P}^{n}}=\mathcal{O}(\operatorname{Div} \omega)$. So take

$$
\omega:=x_{1}^{-1} d x_{1} \wedge \cdots \wedge x_{n}^{-1} d x_{n}
$$

noting that we leave out the first coordinate $x_{0}$ and divide by coordinates to make this scaleinvariant. Here we work in a $\mathbb{C}^{n}$ chart of points of the form $\left[1: x_{1}: \cdots: x_{n}\right]$. Where does $\omega$ have poles? Along $x_{i}=0$ for any $1 \leq i \leq n$, and similarly in any other coordinate chart. We also have a 1 st order pole along $x_{0}=0$. We then get

$$
K_{\mathbb{C P}^{n}}=\mathcal{O}(\operatorname{Div} \omega)=\mathcal{O}\left(-H_{0}-H_{1}-\cdots-H_{n}\right)=\mathcal{O}(-n-1)
$$

where $H_{i}=\left\{x_{i}=0\right\}$.

Note that $\mathbb{C P}^{n}$ is like a simplex:


## $x_{1}=0$

Applying this to $\mathbb{C P}^{2}$, we obtain

$$
K_{\mathbb{C P}^{2}}=\mathcal{O}(-3) .
$$

What is the intersection form? We know $H^{2}\left(\mathbb{C P}^{2} ; \mathbb{Z}\right) \cong \mathbb{Z}$ and the intersection form is unimodular. So write $\mathbb{Z}:=\mathbb{Z} \alpha$ for $\alpha$ some generator. Then $\alpha \cdot \alpha= \pm 1$ since $\operatorname{det} G= \pm 1$ for the Gram matrix for this to be unimodular. Note that $(-\alpha) \cdot(-\alpha)= \pm 1$ with the same sign.

Claim: $\mathcal{O}(1)=\mathcal{O}(H)$ generates $\operatorname{Pic}\left(\mathbb{C P}^{2}\right)=H^{2}\left(\mathbb{C P}^{2} ; \mathbb{Z}\right)$.
This is because $c_{1} \mathcal{O}(H) \cdot c_{1} \mathcal{O}(H)=H \cdot H=\left\{x_{0}=0\right\} \pitchfork\left\{x_{1}=0\right\}=\{[0: 0: 1]\}$ here we note that the two hyperplanes can be oriented transversely and intersected. This is an oriented intersection.

Recall Noether's formula, which was HRR applied to $\mathcal{O}$ and the Chern-Gauss-Bonet theorem:

$$
\begin{aligned}
\chi(\mathcal{O}) & =\frac{1}{12}\left(K^{2}+\chi_{\text {Top }}\right) \\
& =h^{0}(\mathcal{O})-h^{1}(\mathcal{O})+h^{2}(\mathcal{O}) \\
& =1-1+1 \\
& =1
\end{aligned}
$$

The right-hand side can be written as

$$
\frac{1}{12}((-3 H) \cdot(-3 H)+3)=\frac{1}{12}(9+3)=1
$$

## Proposition 20.0.5(The 4-sphere has no complex structure).

$S^{4}$ has no complex structure.

Proof (?).
We know that $\chi_{\text {Top }}\left(S^{4}\right)=2$. If $S^{4}$ had a complex structure, then $c_{1}\left(K_{S^{4}}\right) \in H^{2}\left(S^{4} ; \mathbb{Z}\right)=0$. Thus would make $K_{S^{4}}^{2}=0$, and so

$$
\chi\left(\mathcal{O}_{S^{4}}\right)=\frac{1}{12}(0+2)=\frac{1}{6} \notin \mathbb{Z}
$$

which is a contradiction. $\{$

Example 20.0.6(?): Consider $\overline{\mathbb{C P}}^{2}$, a 4-manifold diffeomorphic to $\mathbb{C P}^{2}$ with the opposite orientation. What is the intersection form? Taking $H \cdot H=-1$ since the orientations aren't compatible, and more generally the Gram matrix is negated when the orientation is reversed.

Proposition 20.0.7(Barred projective 2-space is not orientably diffeomorphic to a complex surface).
$\overline{\mathbb{C P}}^{2}$ is not diffeomorphic to a complex surface by an orientation-preserving diffeomorphism (or any homeomorphism).

Proof (?).
We have $\chi_{\text {Top }}=3$, and $K_{\overline{\mathbb{C P}}^{2}}=-c_{1}\left(T \overline{\mathbb{C P}}^{2}\right)= \pm 3 H$. Then

$$
\chi(\mathcal{O})=\frac{1}{12}\left(K_{\overline{\mathbb{C P}}^{2}}^{2}+\chi_{\text {Top }}\right)=\frac{1}{12}(-9+3) \notin \mathbb{Z}
$$

Remark 20.0.8: Consider $\mathcal{O}_{\mathbb{C P}^{n}}(d)$, what are its global sections $H^{0}\left(\mathbb{C P}^{n}, \mathcal{O}_{\mathbb{C P}^{n}}(d)\right)$. Locally we have $\mathcal{O}_{\mathbb{C P}^{n}}(d)(U)$ given by holomorphic functions in $\left(x_{0}, \cdots, x_{n}\right) \in \pi^{-1}(U)$ where $\pi: \mathbb{C}^{n+1} \rightarrow \mathbb{C P}^{n}$ and the functions satisfy $f(\lambda \mathbf{x})=\lambda^{d} f(\mathbf{x})$. The global sections will be the homogeneous degree $d$ polynomials in the coordinates of $\mathbf{x}$.

Remark 20.0.9: Why does a holomorphic function $f: \mathbb{C}^{n+1} \rightarrow \mathbb{C}$ such that $f(\lambda \mathbf{x})=\lambda^{d} f(\mathbf{x})$ necessarily a polynomial? Use the result that any such function with at most polynomial growth is itself a polynomial. If $\left.f\right|_{S^{2 d+1}}$ is bounded by $C$, we have $\|f\|_{L^{2}} \leq C|x|^{2 d}$. Since $\left(\partial_{x_{1}} \cdots \partial_{x_{k}}\right)^{d} f$ is globally bounded $k \geq 2 d$, applying Liouville's theorem makes it constant, and so a finite number of derivatives kill $f$ and this forces it to be polynomial.

Remark 20.0.10: So how many homogeneous degree $d$ functions are there? Here $h^{0}\left(\mathbb{C P}^{n}, \mathcal{O}(d)\right)=$ will be the number of linearly independent degree $d$ polynomials in the variables $x_{0}, \cdots, x_{n}$, which is $\left(\binom{n+1}{d}\right)=\binom{n+d}{n}$, using the fact that monomials span this space.

Exercise 20.0.11 (?)
Using that $h^{0}\left(\mathbb{C P}^{2} ; \mathcal{O}(k)\right)=h^{2}\left(\mathbb{C P}^{2} ; \mathcal{O}(-3-k)\right)$ by Serre duality and Riemann-Roch, compute $h^{i}\left(\mathbb{C P}^{2} ; \mathcal{O}(k)\right)$ for all $i, k$.

## Fact 20.0.12

$h^{i}\left(\mathbb{C P}^{n} ; \mathcal{O}(k)\right)=0$ unless $i=0, n$.

## 21 Wednesday, March 03

Find first 5m.

Remark 21.0.1: When we considered $\overline{\mathbb{C P}}^{2}$, we implicitly assumed $T \overline{\mathbb{C P}}^{2}$ was a complex rank 2 vector bundle with some purported complex structure.

## Claim:

$$
c_{1}\left(T \overline{\mathbb{C P}}^{2}\right)= \pm 3 H
$$

although it's not clear that $c_{1}(K) \in H^{2}\left(\overline{\mathbb{C P}}^{2} ; \mathbb{Z}\right) \cong(\mathbb{Z},[-1])$.
Remark 21.0.2: We had $\chi(\mathcal{O})=\frac{1}{12}\left(K^{2}+\chi_{\text {Top }}\right)=\frac{1}{12}\left(3-n^{2}\right)$, and since $3-n^{2} \in 12 \mathbb{Z}$, we have $n^{2} \in 3+12 \mathbb{Z} \subset 3+4 \mathbb{Z}$ and this forces $n^{2} \equiv 3(\bmod 4)$.

Definition 21.0.3 (Differential Complex)
Let

$$
0 \rightarrow \mathcal{E}^{0} \xrightarrow{d_{0}} \mathcal{E}^{1} \xrightarrow{d_{1}} \cdots \rightarrow \mathcal{E}^{n} \rightarrow 0
$$

be a complex (so $d^{2}=0$ ) of smooth vector bundles on a smooth manifold $X \operatorname{im} \mathrm{Mfd}_{\mathbb{R}}^{C^{\infty}}$. Suppose that the $d_{i}$ are differential operators, i.e. in local trivializing charts over $U$ we have

$$
\mathcal{E}^{i} \cong \mathcal{O}^{\oplus r_{i}} \mathcal{O}^{\oplus r_{i+1}} \cong \mathcal{E}^{i+1}
$$

where in every matrix coordinate, $d_{i}$ is of the form $\sum_{|I|<N} g_{I} \partial_{I}$ where $\partial_{I}:=\partial_{i_{1}} \cdots \partial_{i_{N}}$ is a partial derived and the $g_{I}$ are smooth functions.

Example 21.0.4(?): For $X \in \operatorname{Mfd}_{\mathbb{R}}^{C^{\infty}}$, we can take

$$
0 \rightarrow \mathcal{O} \xrightarrow{d} \Omega^{1} \xrightarrow{d} \Omega^{2} \xrightarrow{d} \cdots .
$$

In local coordinates,

- $\Omega^{1}$ is spanned over $\mathcal{O}$ by $d x_{1}, \cdots, d x_{n}$ where $n=\operatorname{dim}_{\mathbb{R}}(X)$
- $\Omega^{2}$ is spanned over $\mathcal{O}$ by $d x_{i} \wedge d x_{j}$ for $1 \leq i, j \leq n$.

Then the component of $d$ sending $d x_{i} \rightarrow d x_{i} \wedge d x_{j}$ is of the form

$$
f d x_{i} \mapsto-\frac{\partial f}{\partial x_{j}} d x_{i} \wedge d x_{j} .
$$

Example 21.0.5(?): For $X \in \operatorname{Mfd}_{\mathbb{C}}$ and $\mathcal{E} \rightarrow X$ a holomorphic vector bundle, take

$$
\mathcal{E} \otimes A^{0,0} \xrightarrow{\bar{\delta}} \mathcal{E} \otimes A^{0,1} \xrightarrow{\overline{\mathrm{~g}}} \mathcal{E} \otimes A^{0,2} \rightarrow \cdots .
$$

This is because for $s_{i}$ local holomorphic sections and $\omega$ a smooth form we have

$$
\bar{\partial}\left(\left(s_{1}, \cdots, s_{r}\right) \otimes \omega\right)=\left(s_{1}, \cdots, s_{r}\right) \otimes \bar{\partial} \omega .
$$

Definition 21.0.6 (Order of an operator)
The maximal $N$ that appears in $\sum_{|I| \leq N} g_{I} \partial_{I}$ is the order.
Definition 21.0.7 (Symbol Complex)
The symbol complex is a sequence of vector bundles on $T^{\vee} X$. Noting that we have $\pi$ : $T^{\vee} X \rightarrow X$, and using pullbacks we can obtain bundles over the cotangent bundle:

$$
0 \rightarrow \pi^{*} \mathcal{E}_{0} \xrightarrow{\sigma\left(d_{0}\right)} \pi^{*} \mathcal{E}_{1} \xrightarrow{\sigma\left(d_{1}\right)} \cdots \rightarrow \pi^{*} \mathcal{E}_{n} \rightarrow 0 .
$$

The symbol of the differential operator $d_{i}$ is $\sigma\left(d_{i}\right)$. It is defined by replacing $\partial_{i}$ in $\sum_{|I|=N} g_{I} \partial_{I}$ with $y_{i}$ where

$$
y_{i}: T^{\vee} U \rightarrow \mathbb{R}
$$

is the coordinate function on the second factor of $T^{\vee} U=U \times \mathbb{R}^{n}$ associated to the local coordinate $i$. Using that $T U=\left(T^{\vee}\right)^{\vee} U$, we can view $\partial_{i}$ as functions on the cotangent bundle, $\sigma\left(d_{i}\right)$ is given in local trivializations by multiplication by a smooth function $\sum_{|I|=N} g_{I} y^{I}$.

Example 21.0.8(?): Consider $\mathcal{O} \xrightarrow{d} \Omega^{1}$. In local coordinates, this is given by $d=\left(\partial_{1}, \cdots, \partial_{n}\right)$, i.e. coordinate-wise differentiation, since we can write a local trivialization $\Omega^{1}=\mathcal{O} d z_{1} \oplus \cdots \oplus \mathcal{O} d z_{n}$. Then the symbol of $d$ is given by

$$
\begin{aligned}
\sigma(d): \pi^{*} \mathcal{O} & \rightarrow \pi^{*} \Omega^{1} \\
1 & \mapsto\left(y_{1}, \cdots, y_{n}\right)
\end{aligned}
$$

thought of as vector bundles over $T^{\vee} X$, and this is projection onto to cotangent factor. Locally, the image of 1 is given by $y_{1} d x_{1}+\cdots y_{n} d x_{n}$, which is a point in $T_{p}{ }^{\vee} X$ for all $(p, \alpha) \in T^{\vee} X$ which is an assignment to every point $(p, \alpha) \in T_{p}{ }^{\vee} X$ a point in $\left(\pi^{*} \Omega^{1}\right)_{p, \alpha} \cong T_{p}{ }^{\vee} X$. There is a tautological section $(p, \alpha) \rightarrow \alpha \in T_{p}{ }^{\vee} X \in\left(\pi^{*} \Omega^{1}\right)_{p, \alpha}$, or really $(p, \alpha) \mapsto((p, \alpha), \alpha)$.

Remark 21.0.9: See similarly to the canonical symplectic structure of the cotangent bundle.

Remark 21.0.10: More generally, for $d: \Omega^{p} \rightarrow \Omega^{p+1}, \sigma(d)$ acts on the frame $d x_{i_{1}} \wedge \cdots d x_{i_{p}}$ in the following way:

$$
\sigma(d)\left(d x_{i_{1}} \wedge \cdots \wedge d x_{i_{p}}\right)=\sum_{y} y_{y} d x_{j} \wedge d x_{i_{1}} \wedge \cdots d x_{i_{p}}
$$

where

$$
d: f d x_{i_{1}} \wedge \cdots \wedge d x_{i_{p}} \mapsto \sum_{j} \frac{\partial f}{\partial x_{j}} d x_{j} \wedge\left(d x_{i_{1}} \wedge \cdots \wedge d x_{i_{p}}\right)
$$

The symbol complex is

$$
\pi^{*} \mathcal{O} \xrightarrow{\sigma(d)} \pi^{*} \Omega^{1} \xrightarrow{\sigma(d)} \pi^{*} \Omega^{2} \rightarrow \cdots \rightarrow \pi^{*} \Omega^{n} \rightarrow 0
$$

for $n$ the dimension. In this case, $\sigma(d)$ has the same formula everywhere, since it's $C^{\infty}$-linear:

$$
\sigma(d)=\sum_{j} y_{j} d x_{j} \wedge(\cdots)
$$

Definition 21.0.11 (Elliptic Complex)
A differential complex $\left(\mathcal{E}_{*}, d\right)$ is elliptic if the symbol complex $\left(\pi^{*} \mathcal{E}_{*}, \sigma(d)\right)$ is an exact sequence of sheaves (importantly) on $T^{\vee} X \backslash\left\{s_{z}\right\}$ for $s_{z}$ the zero section.

Claim: $\left(\Omega_{*}, d\right)$ is elliptic. To check exactness of a sequence of vector bundles, it suffices to check exactness on every fiber. Fix $(p, \alpha) \in T^{\vee} X \backslash\left\{s_{z}\right\}$, then

$$
0 \rightarrow \mathbb{C} \xrightarrow{\wedge \alpha} T_{p}^{\vee} X \xrightarrow{\wedge \alpha} \bigwedge_{\Lambda}^{2} T_{p}{ }^{\vee} X \xrightarrow{\wedge \alpha} \bigwedge^{3} T_{p}{ }^{\vee} X \rightarrow \cdots
$$

Moreover, if $\alpha \wedge \beta=0$ implies that $\beta=\alpha \wedge \gamma$ for some $\gamma$, which implies that this sequence is exact.

## 22 Friday, March 05

Remark 22.0.1: Recall that we set up a differential complex, whose objects were vector bundles and differentials were differential operators (i.e. linear combinations of partial derivatives) in local trivializations. We pulled back to tangent bundles (?) and defined the symbol of an operator, and saw that when taking the symbol complex of the deRham complex. the sequence of maps was given by wedging against a tautological one-form. This was an elliptic complex because the maps became wedging with a covector.

Example 22.0.2(of an elliptic complex): Let $X \in \operatorname{Mfd}_{\mathbb{C}}$ and $\mathcal{E} \rightarrow X \in \operatorname{Bun}_{\mathrm{GL}_{r} \mathbb{C}}$ be holomorphic. There is a resolution

$$
0 \rightarrow \mathcal{E} \xrightarrow{i} \mathcal{E} \otimes A^{0,0} \xrightarrow{\bar{\partial}} \mathcal{E} \otimes A^{0,1} \xrightarrow{\bar{\partial}} \cdots
$$

What is the symbol complex? Consider the projection $\pi: T^{\vee} X \rightarrow X$, and use pullbacks to get a sequence

$$
0 \rightarrow \pi^{*} \mathcal{E} \otimes A^{0,0} \xrightarrow{\sigma(\bar{\partial})} \pi^{*} \mathcal{E} \otimes A^{0,1} \xrightarrow{\sigma(\bar{\partial})} \cdots
$$

Here the symbol $\sigma(\bar{\partial})$ replace $\frac{\partial}{\partial t \bar{z}_{i}}$ with the corresponding function on $T^{\vee} X$, say $\bar{y}_{i}$. Then $\sigma(\bar{\partial})=$ $\sum_{i} \bar{y}_{i} d \bar{z}_{i} \wedge(-)=\bar{\alpha} \wedge(-)$. As before, at a point $(p, \alpha)$ where $\alpha \neq 0$ in $T^{\vee} X$, we get

$$
0 \rightarrow \mathcal{E}_{p} \xrightarrow{\bar{\alpha} \wedge(-)} \mathcal{E}_{p} \otimes \bigwedge_{p}^{0,1} X \xrightarrow{\bar{\alpha} \wedge(-)} \mathcal{E}_{p} \otimes \bigwedge^{0,2} X \rightarrow \cdots
$$

which is an exact sequence of vector spaces. So $\left(\mathcal{E} \otimes A^{0, p}, \bar{\partial}\right)$ is an elliptic complex.

## Slogan 22.0.3

The symbol being exact is approximately the top-order part being nowhere-vanishing.

Remark 22.0.4: The next theorem computes the cohomology of an elliptic complex using Chern and Todd classes.

Theorem 22.0.5(Atiyah-Singer Index Theorem).
If $\left(\mathcal{E}_{*}, d\right)$ is an elliptic complex of smooth vector bundles on a compact oriented $X \in \mathrm{Mfd}_{\mathbb{R}}^{n}$, then

$$
\chi\left(\mathcal{E}_{*}, d\right)=\sum(-1)^{i} \operatorname{dim}\left(\frac{\operatorname{ker} d^{i}}{\operatorname{im} d^{i-1}}\right)=(-1)^{(\underset{2}{\operatorname{dim}(X)})} \int_{X} \frac{\operatorname{ch}}{\operatorname{eul}}\left(\mathcal{E}_{*}\right) \operatorname{td}\left(T X \otimes_{\mathbb{R}} \mathbb{C}\right)
$$

Remark 22.0.6: Here we define $\operatorname{ch}\left(\mathcal{E}_{*}\right):=\sum_{i}(-1)^{i} \operatorname{ch}\left(\mathcal{E}^{i}\right)$. What does it mean to divide by the Euler class? Let $\left\{x_{i},-x_{i}\right\}$ be the Chern roots of the complexified tangent bundle $T X \otimes \mathbb{C}$, then
$\operatorname{eul}(X):=\prod x_{i}$ is the product where we pick one of each of the Chern roots from each of the pairs. The preferred sign to choose is the one for which $\int_{X} \prod x_{i}=\chi_{\text {Top }}(X)$. Dividing just means to take the Chern character, then if it's divisible by $\prod x_{i}$, we do so. We have

$$
\operatorname{td}(T X \otimes \mathbb{C})=\prod_{i}\left(\frac{x_{i}}{1-e^{-x_{i}}}\right)\left(\frac{-x_{i}}{1-e^{-x_{i}}}\right)
$$

Thus

$$
\frac{\operatorname{td}(T X \otimes \mathbb{C})}{\operatorname{eul}(X)}=\prod_{i} \frac{1}{x_{i}}\left(\frac{x_{i}}{1-e^{-x_{i}}}\right)\left(\frac{-x_{i}}{1-e^{-x_{i}}}\right)
$$

but note that this doesn't necessarily make sense. However, all all computations we'll see, there will be enough cancellation to make this well-defined.

Exercise 22.0.7 (Chern character of the de Rham complex)
$\operatorname{ch}\left(\Omega_{*} X \otimes \mathbb{C}\right)=\prod_{i}\left(1-e^{x_{i}}\right)\left(1-e^{-x_{i}}\right)$ for $X \in \mathrm{Mfd}_{\mathbb{R}}^{2 n}$ even dimensional.

Example 22.0.8(?): Supposing $X \in \operatorname{Mfd}_{\mathbb{R}}^{2}$ is a genus $g$ surface, we have

$$
\mathcal{O} \rightarrow \Omega^{1} \otimes \mathbb{C} \rightarrow \Omega^{2} \otimes \mathbb{C}
$$

and $\operatorname{ch}\left(\Omega_{*}\right)=\operatorname{ch}(\mathcal{O})-\operatorname{ch}\left(\Omega^{1} \otimes \mathbb{C}\right)+\operatorname{ch}\left(\Omega^{2} \otimes \mathbb{C}\right)$. The Chern roots of $T X \otimes \mathbb{C}$ are $\left\{x_{i},-x_{i}\right\}$, which come in pairs. So

$$
\operatorname{ch}\left(\Omega_{*}\right)=1-e^{x_{i}}-e^{x_{i}}+e^{-x_{i}+x_{i}}=\left(1-e^{-x_{i}}\right)\left(1-e^{x_{i}}\right)
$$

From the theorem, we're supposed to have

$$
\begin{aligned}
\chi\left(\Omega_{*}, d\right) & =(-1)^{\frac{n(n-1)}{2}} \int_{X} \frac{\prod_{i}\left(1-e^{-x_{i}}\right)\left(1-e^{x_{i}}\right)}{\prod_{i=1}^{n} x_{i}} \prod_{i}\left(\frac{x_{i}}{1-e^{-x_{i}}}\right)\left(\frac{-x_{i}}{1-e^{-x_{i}}}\right) \\
& =(-1)^{\frac{n(n-1)}{2}} \int_{X} \prod_{i=1}^{n}\left(-x_{i}\right) \\
& =\int_{X} \prod_{i} x_{i} \\
& =\chi_{\operatorname{Top}}(X)
\end{aligned}
$$

C-G-B.
Letting $d=\operatorname{dim} X=2 n$, we have

$$
(-1)^{n}(-1)^{\frac{d(d-1)}{2}}=(-1)^{n}(-1)^{n(2 n-1)}=(-1)^{2} n=1
$$

Example 22.0.9(?): We can prove HRR using this theorem: we have

$$
\chi(X, \mathcal{E})=\chi\left(\mathcal{E} \otimes A^{0,-}, \bar{\partial}\right) \stackrel{\operatorname{ASIT}}{=} \int_{X} \frac{\operatorname{ch}\left(\mathcal{E} \otimes A^{0,-}\right)}{\operatorname{eul}(X)} \operatorname{td}\left(T X \otimes_{R} \mathbb{C}\right)
$$

We have $\operatorname{ch}\left(\mathcal{E} \otimes A^{0,-}\right)=\operatorname{ch}(\mathcal{E}) \operatorname{ch}\left(A^{0,-}\right)$ where $\operatorname{ch}\left(A^{0,1}\right)=\sum_{I}(-1)^{i} \operatorname{ch}\left(\bigwedge^{i} A^{0,1}\right)$. The Chern roots of

- $T X$ are $\left\{x_{i}\right\}$
- $A^{1,0}=T^{\vee} X$ are $\left\{-x_{i}\right\}$
- $A^{0,1}$ are $\left\{-x_{i}\right\}$

So we obtain

$$
\begin{aligned}
\chi(\mathcal{E}) & =(-1)^{n} \int_{X} \frac{\prod\left(1-e^{x_{i}}\right)}{\prod x_{i}} \prod_{i}\left(\frac{x_{i}}{1-e^{-x_{i}}}\right)\left(\frac{-x_{i}}{1-e^{-x_{i}}}\right) \\
& =\int_{X} \operatorname{ch}(\mathcal{E}) \prod_{i} \frac{x_{i}}{1-e^{-x_{i}}} \\
& =\int_{X} \operatorname{ch}(\mathcal{E}) \operatorname{td}(T X),
\end{aligned}
$$

which is HRR.

## 23 Monday, March 08

Remark 23.0.1: Recall that given a differential complex $\left(\mathcal{E}_{*}, d\right)$ we had a symbol complex $\left(\pi^{*} \mathcal{E}_{*}, \sigma(d)\right)$ where $\pi: T^{\vee} X \rightarrow X$ and

$$
\sigma\left(\sum_{|I| \leq N} f_{I} \partial_{I}\right):=\sum_{|I|=N} f_{I} y^{I}
$$

where we take the top-order differentials, $\frac{\partial}{\partial x_{j}} \mapsto y_{j}$ and

$$
\begin{aligned}
T^{\vee} X & \rightarrow \mathbb{R} \\
\alpha & \mapsto \alpha\left(\frac{\partial}{\partial x_{j}}\right) .
\end{aligned}
$$

We say that $\left(\mathcal{E}_{*}, d\right)$ is elliptic if the symbol complex is exact on $T^{\vee} X \backslash\{0\}$ where we delete the zero section. The Atiyah-Singer index theorem stated

$$
\chi\left(\mathcal{E}_{*}, d\right)=\int_{X} \frac{\operatorname{ch}\left(\mathcal{E}_{*}\right)}{\operatorname{eul}(X)} \operatorname{td}\left(T X \otimes_{\mathbb{R}} \mathbb{C}\right)
$$

What's the connection to elliptic operators? Given a 2-term complex

$$
0 \rightarrow \mathcal{E}^{0} \xrightarrow{D} \mathcal{E}^{1} \rightarrow 0
$$

then $D$ is an elliptic operator if this is an elliptic complex. This means the symbol complex is an isomorphism, i.e.

$$
0 \rightarrow \pi^{*} \mathcal{E}^{0} \xrightarrow{\sigma(D)} \pi^{*} \mathcal{E}^{1} \rightarrow 0
$$

where $\sigma(D)$ is an isomorphism away from the zero section.

Remark 23.0.2: Every elliptic complex can be converted into a 2-term complex using a hermitian metric. Given

$$
\mathcal{E}^{0} \xrightarrow{d^{0}} \mathcal{E}^{1} \xrightarrow{d^{1}} \mathcal{E}^{2} \rightarrow \cdots,
$$

we map this to

$$
0 \rightarrow \mathcal{E}^{\text {even }}:=\bigoplus_{i \text { even }} \mathcal{E}^{i} \underset{D^{\text {odd }}}{D^{\text {even }}} \mathcal{E}^{\text {odd }}:=\bigoplus_{i \text { odd }} \rightarrow 0
$$

where

$$
D:=\left(\left(d^{2 i-1}\right)^{\dagger}, d^{2 i}\right): \mathcal{E}^{2 i} \rightarrow \mathcal{E}^{2 i-1} \oplus \mathcal{E}^{2 i+2}
$$

and $\left(d^{2 i-1}\right)^{\dagger}$ is defined by the following property: for $\alpha \in \mathcal{E}^{2 i-1}$ and $\beta \in \mathcal{E}^{2 i}(X)$,

$$
\left\langle d^{2 i-1} \alpha, \beta\right\rangle_{h}=\left\langle\alpha,\left(\left(d^{2 i-1}\right)^{\dagger} \beta\right\rangle_{h}\right.
$$

Here this pairing depends on a hermitian metric $h$, which is a hermitian form on each fiber:

$$
h_{i}: \mathcal{E}^{i} \otimes \overline{\mathcal{E}^{i}} \rightarrow \mathbb{C}
$$

Using this, we can fix a volume form $d V$ on $X$ and define

$$
\langle u, v\rangle_{h}:=\int_{X} h_{i}(u, \bar{v}) d V \quad u, v \in \mathcal{E}^{i}(X)
$$

This yields the desired two-term complex, and $\left(\mathcal{E}_{*}, d\right)$ is elliptic if and only if $D^{e} \circ D^{o}: \mathcal{E}^{o} \circlearrowleft$ and $D^{o} \circ D^{e}: \mathcal{E}^{e} \circlearrowleft$ are elliptic operators.

Example 23.0.3(?): Taking the de Rham complex

$$
0 \rightarrow \mathcal{O} \xrightarrow{d} \Omega^{1} \xrightarrow{d} \Omega^{2} \rightarrow \cdots,
$$

one can define

$$
\Omega^{\text {even }} \underset{d+d^{\dagger}}{\stackrel{d+d^{\dagger}}{\rightleftharpoons}} \Omega^{\text {odd }}
$$

Then using adjoint properties, we have

$$
\left\langle\alpha, d^{\dagger} d^{\dagger} \beta\right\rangle=\left\langle d \alpha, d^{\dagger} \beta\right\rangle=\left\langle d^{2} \alpha, \beta\right\rangle=0
$$

using that $d^{2}=0$, and since this is true for all $\alpha, \beta$ we have $\left(d^{\dagger}\right)^{2} \beta=0$ for all $\beta$. Noting that $d d^{\dagger}+d^{\dagger} d: \Omega^{i}(X) \circlearrowleft$, and this operator is the Laplacian. Moreover $\operatorname{ker}\left(d d^{\dagger}+d^{\dagger} d\right)$ is the space of harmonic $i$-forms.

Remark 23.0.4: Note that this space of harmonic forms depended on the Hermitian metrics on $\mathcal{E}^{i}$ and the volume form $d V$. In the case $\mathcal{E}^{i}:=\Omega^{i}$, there is a natural metric determined by any Riemannian metric on $X$. Recall that this is given by a metric

$$
g: T X \otimes T X \rightarrow \mathbb{R}
$$

This determines an isomorphism

$$
\begin{aligned}
T_{p} X & \xrightarrow{\sim} T_{p}{ }^{\vee} X \\
v & \mapsto g(v,-),
\end{aligned}
$$

which we can invert to get a metric on the cotangent bundle $T^{\vee} X$. This induces a metric on $i$-forms using the identification $\Omega^{i}:=\bigwedge^{i} T^{\vee} X$ and induces a volume form

$$
d V:=\sqrt{\operatorname{det} g}: \bigwedge^{\mathrm{top}} T X \rightarrow \mathbb{R} .
$$

In this case, $d d^{\dagger}+d^{\dagger} d$ on $\Omega^{i}(X)$ is called the metric Laplacian.
Remark 23.0.5: Let $(X, g)$ be a Riemannian manifold. We thus have a symmetric bilinear form on $\Omega^{p}(X)$ given by pairing sections:

$$
\langle\alpha, \beta\rangle:=\int_{X} g(\alpha, \beta) .
$$

Note that we have orthonormal frames on $\Omega^{p}(X)$ of the form $e_{i_{1}} \wedge \cdots \wedge e_{i_{p}}$ where the $\left\{e_{i}\right\}$ are orthonormal frames on $T^{\vee} X$.

Definition 23.0.6 (Hodge Star Operator)
Let $n:=\operatorname{dim}(X)$. The Hodge star operator is a map

$$
\star: \Omega^{p} \rightarrow \Omega^{n-p} .
$$

defined by the property

$$
\alpha \wedge \star \beta=g(\alpha, \beta) d V .
$$

Concretely, we have

$$
\begin{aligned}
\star\left(\sum f_{I} d x_{i_{1}} \wedge \cdots \wedge d x_{i_{p}}\right) & =\star\left(\sum f_{I} e_{i_{1}} \wedge \cdots \wedge e_{i_{p}}\right) \\
& =(-1)^{\ell} \sum_{j_{k} \in\{1, \cdots, n\} \backslash I} f_{I} e_{j_{1}} \wedge \cdots \wedge e_{j_{n-p}}
\end{aligned}
$$

for some sign $\ell$.
Example 23.0.7(?): Let $X:=\mathbb{R}^{4}$ and $g$ the standard metric, i.e. $d=d x_{1}^{2}+\cdots+d x_{4}^{2}$. Take an orthonormal basis of $T^{\vee} \mathbb{R}^{4}$, say $\left\{e_{1}, e_{2}, e_{3}, e_{4}\right\}$ where $e_{i}:=d x_{i}$. Then the induced volume form is $d V:=e_{1} \wedge e_{2} \wedge e_{3} \wedge e_{4}$. We can then compute $\star\left(e_{1} \wedge e_{2}\right)$ which is defined by the property

$$
\alpha \wedge \star\left(e_{1} \wedge e_{2}\right)=g\left(\alpha, e_{1} \wedge e_{2}\right) d V .
$$

On the right-hand side, $g\left(\alpha, e_{1} \wedge e_{2}\right)=c_{12}(\alpha) e_{1} \wedge e_{2} \wedge e_{3} \wedge e_{4}$ where $c_{12}$ is the coefficient of $e_{1} \wedge e_{2}$. To extract that coefficient, we can take $\alpha\left(e_{3} \wedge e_{4}\right.$, writing $\alpha=\sum c_{i j} e_{i} \wedge e_{j}$. Similarly, *) $\left.e_{1} \wedge e_{3}\right)=-e_{2} \wedge e_{4}$. This follows from writing

$$
\alpha \wedge \star\left(e_{1} \wedge e_{3}\right)=c_{13}(\alpha) e_{1} \wedge e_{2} \wedge e_{3} \wedge e_{4}=(-1) c_{13}(\alpha) e_{1} \wedge e_{3} \wedge e_{2} \wedge e_{4} .
$$

From this, $\star: \Omega^{p} \rightarrow \Omega^{n-p}$ is defined fiber-wise as

$$
\langle\alpha, \beta\rangle=\int_{X} \alpha \wedge \star \beta
$$

Exercise 23.0.8 (?)
Show that $\star^{2}=(-1)^{p(n-p)}$.

## Proposition 23.0.9(Formula for the adjoint of the Hodge star).

Let $d^{\dagger}:=(-1)^{n(p-1)+1} \star d \star$. Then

$$
\langle\alpha, d \beta\rangle=\left\langle d^{\dagger} \alpha, \beta\right\rangle \quad \alpha \in \Omega^{p}(X), \beta \in \Omega^{p-1}(X)
$$

Proof (?).
A slick application of Stokes' theorem! Using that $\star$ is an isometry, we have

$$
\begin{aligned}
\langle\alpha, d \beta\rangle & =\int_{X} \alpha \wedge \star d \beta & & \\
& =\int_{X} \star \alpha \wedge d \beta(-1)^{p(n-p)} & & \text { applying } \star \text { to both } \\
& =-\int_{X} d(\star \alpha) \wedge \beta(-1)^{p(n-p)} & & \text { Stokes/IBP } \\
& =(-1)^{p(n-p)+1} \int_{X} \star d \star \alpha \wedge \star \beta & & \text { isometry } \\
& =(-1)^{p(n-p)+1}\langle\star d \star \alpha, \beta\rangle, & &
\end{aligned}
$$

which shows that the term in the left-hand side of the inner product above is the adjoint of $d^{\dagger}$.

## 24 Wednesday, March 10

## Warning 24.0.1

Missing some stuff from the first few minutes here!
Remark 24.0.2: Can we always get a Hermitian metric? Let $X \in \mathrm{Mfd}_{C^{\infty}(\mathbb{R})}$ and $\mathcal{E} \rightarrow X \in \mathrm{Bun}_{\mathrm{GL}_{r} \mathbb{C}}$ a smooth complex vector bundle. Then any section $h \in \mathcal{E}^{\vee} \otimes \overline{\mathcal{E}}^{\vee}(X)$, we have

$$
\begin{array}{r}
h: \mathcal{E} \otimes \overline{\mathcal{E}} \rightarrow \mathcal{O} \\
h(e \otimes f) .
\end{array}
$$

for $e, f \in \mathcal{E}_{p}$ is a Hermitian form for all $p$. In local trivializations, $\left.\mathcal{E}\right|_{U} \cong \mathcal{O}_{U}^{\oplus r}$, and one can take the standard Hermitian form here. Then for $\left(f_{1}, \cdots, f_{r}\right) \in \mathcal{O}^{\oplus r}(U)$, we have $\sum f_{i} \bar{f}_{i} \in \mathcal{O}(U)$. This can be extended to all of $X$ using a partition of unity subordinate to the coordinate charts.

The thing to check here is that on $\mathbb{C}^{r}$, for any collection $h_{1}, \cdots, h_{n}$, any positive linear combination $\sum a_{i} h_{i}$ is again a Hermitian metric for any $a_{i} \in \mathbb{R}^{+}$. One can regard these as skew-symmetric matrices, which are closed under addition, and the positive-definite property ensures it's still a metric since $h(v, v)=\sum a_{i} h_{i}(v, v)>0$ for $v \neq 0$.

Remark 24.0.3: Recall that we start with a Riemannian manifold $(X, g)$ where $g: T X^{\otimes 2} \rightarrow \mathcal{O}$ is a metric on the tangent bundle. Locally choose $f_{1}, \cdots, f_{n}$ an orthogonal frame of $T X$, then setting $e_{i}:=f_{i}^{\vee}$ yields an orthogonal frame of $T^{\vee} X$ and thus an orthogonal frame $e_{i_{1}} \wedge \cdots e_{i_{p}}$ of $\bigwedge^{p} T^{\vee} X:=\Omega^{p} X$. So we get a metric on the smooth $p$-forms $\Omega^{p} X$. We defined the Hodge star operator

$$
\begin{aligned}
\star: \Omega^{p} & \rightarrow \Omega^{n-p} \\
e_{i_{1}} \wedge \cdots e_{i_{p}} & \mapsto \pm e_{j_{1}} \wedge \cdots \wedge e_{j_{n-p}} .
\end{aligned}
$$

where $\left\{i_{1}, \cdots, i_{p}, j_{1}, \cdots, j_{n-p}\right\}=\left\{e_{1}, \cdots, e_{n}\right\}$. We saw that

$$
\begin{aligned}
e_{i_{1}} \wedge \cdots \wedge e_{i_{p}} \star\left(e_{1} \wedge \cdots e_{i_{p}}\right) & =e_{1} \wedge \cdots \wedge e_{n} \\
\star\left(\sum_{|I|=p} f_{I} e_{I}\right) & =\sum_{|I|=p} e_{I^{c}}(-1)^{\operatorname{sign}(I)} .
\end{aligned}
$$

## Moreover,

$$
\langle\alpha, \beta\rangle=\int_{X} g(\alpha, \beta) d V=\int_{X} \alpha \wedge(\star \beta)
$$

and we showed that

$$
\langle\alpha, d \beta\rangle= \pm\left\langle d^{\dagger} \alpha, \beta\right\rangle \quad d^{\dagger}:=\star d \star, \beta \in \Omega^{p-1}(X), \alpha \in \Omega^{p}(X),
$$

yielding an adjoint operator

$$
d^{\dagger}: \Omega^{p}(X) \rightarrow \Omega^{p-1}(X) .
$$

Definition 24.0.4 (Laplacian)
The Laplacian is the differential operator

$$
\Delta:=d d^{\dagger}+d^{\dagger} d: \Omega^{p}(X) \rightarrow \Omega^{p}(X) .
$$

Definition 24.0.5 (Harmonic Forms)
A $p$-form $\omega$ is harmonic if and only if $\Delta \omega=0$. We define $\mathcal{H}^{p}(X)$ as the space of harmonic $p$-forms.

Remark 24.0.6: This operator is $\mathbb{R}$-linear, so $\mathcal{H}^{p}(X) \in \operatorname{Vect}_{\mathbb{R}}$. Note that this whole construction can be made to work over $\mathbb{C}$ by adding conjugates in appropriate places.

Proposition 24.0.7(Characterization of when a smooth p-form is harmonic).
A smooth $p$-form $\omega$ is harmonic if and only if $d \omega=d^{\dagger} \omega=0$.

## Proof (?).

$\Longleftarrow:$ This direct is easy, since $\Delta \omega:=\left(d d^{\dagger}+d^{\dagger} d\right) \omega=d(0)+d^{\dagger} 0=0$.
$\Longrightarrow$ : A nice trick! Using the adjunction $d, d^{\dagger}$ we have

$$
\begin{aligned}
\langle\Delta \omega, \omega\rangle & =\left\langle d d^{\dagger} \omega, \omega\right\rangle+\left\langle d^{\dagger} \omega, \omega\right\rangle \\
& =\left\langle d^{\dagger} \omega, d^{\dagger} \omega\right\rangle+\langle d \omega, d \omega\rangle
\end{aligned}
$$

We now use that since $g$ is positive definite, it is a non-negative smooth function, and

$$
\langle\alpha, \alpha\rangle:=\int_{X} g(\alpha, \alpha) d V \geq 0 \text { with equality } \Longleftrightarrow \alpha \equiv 0 \text { on } X .
$$

So we can conclude that $d^{\dagger} \omega=d \omega=0$.

## § Warning 24.0.8

Note that we've used that the inner product is symmetric over $\mathbb{R}$. Over $\mathbb{C}$, there are bars introduced from conjugation when swapping the variables.

## Proposition 24.0.9(Orthogonal decomposition of p-forms).

The following three subspaces of $\Omega^{p}(X)$ are mutually orthogonal:

$$
d \Omega^{p-1}(X), \mathcal{H}^{p}(X), d^{\dagger} \Omega^{p+1}(X)
$$

Proof (?).
We can write

$$
\left\langle d \alpha, d^{\dagger}\right\rangle=\left\langle d^{2} \alpha, \beta\right\rangle=\langle 0, \beta\rangle
$$

showing that the 1 st and 3 rd spaces are orthogonal. If $\alpha \in \mathcal{H}^{p}(X)$ then by the above proposition, $d \alpha=d^{\dagger} \alpha=0$, and so

$$
\begin{gathered}
\langle\alpha, d \beta\rangle=\left\langle d^{\dagger} \alpha, \beta\right\rangle=0 \\
\left\langle\alpha, d^{\dagger} \beta\right\rangle=\langle d \alpha, \beta\rangle=0
\end{gathered}
$$

Thus the 2 nd space is orthogonal to the 1st and 3rd.

## Observation 24.0.10

Suppose something false ( $\widehat{\varrho})$ : that $\Omega^{p}(X)$ is a complete vector space with respect to the inner product. Remember that it is not! But if it were, there would be a decomposition

$$
\Omega^{p}(X)=d \Omega^{p-1}(X) \oplus \mathcal{H}^{p}(X) \oplus d^{\dagger} \Omega^{p+1}(X)
$$

Let $\alpha \in\left(d \Omega^{p-1}(X) \oplus d^{\dagger} \Omega^{p+1}(X)\right)^{\perp}$ where we take the orthogonal complement with respect to the inner product. Then

$$
\begin{gathered}
\langle\alpha, d \beta\rangle=0 \forall \beta \\
\left\langle\alpha, d^{\dagger} \gamma\right\rangle=0 \forall \gamma \\
\Longrightarrow\left\langle d^{\dagger} \alpha, \beta\right\rangle=0 \forall \beta
\end{gathered}
$$

$$
\Longrightarrow d^{\dagger} \alpha \equiv 0 \quad \text { setting } \beta:=d^{\dagger} \alpha
$$

Similarly, $d \alpha=0$ and so $\alpha \in \mathcal{H}^{p}(X)$.

The conclusion (which is true without the false assumption) is that

$$
\left(d \Omega^{p-1}(X) \oplus d^{\dagger} \Omega^{p+1}(X)\right)^{\perp}=\mathcal{H}^{p}
$$

However, this doesn't yield the full direct sum decomposition: if $W \subseteq V$, then it's not necessarily true that $V \cong W \oplus W^{\perp}$, which only holds if

- $V$ is complete,
- $W$ is closed.


## Fact 24.0.11

For smooth $p$-forms, this decomposition does hold despite the false assumption:

$$
\Omega^{p}(X)=d \Omega^{p-1}(X) \oplus \mathcal{H}^{p}(X) \oplus d^{\dagger} \Omega^{p+1}(X)
$$

Corollary 24.0.12 (p-forms have harmonic representatives).
Thus $\mathcal{H}^{p}(X)$ represents $H^{p}(X ; \mathbb{R})$.

Remark 24.0.13: We have

$$
\begin{aligned}
H^{p}(X ; \mathbb{R}) & =\frac{\operatorname{ker} d}{\operatorname{im} d} \\
& =\frac{d \Omega^{p-1}(X) \oplus \mathcal{H}^{p}(X)}{d \Omega^{p-1}(X)} \\
& =\mathcal{H}^{p}(X)
\end{aligned}
$$

Note that there is a map

$$
\mathcal{H}^{p}(X) \rightarrow H^{p}(X ; \mathbb{R})
$$

since $\alpha \in \mathcal{H}^{p}(X)$ satisfies $d \alpha=0$ in addition to $d^{\dagger} \alpha=0$.

Remark 24.0.14: Note that one can complete these spaces using Sobolev spaces, but there are issues. Take $S^{1}$, then

$$
L_{2}\left(S^{1}\right):=\left\{\left.\sum a_{n} e^{2 \pi i n z}\left|\sum\right| a\right|_{i}<\infty\right\}
$$

but for $f \in L_{2}\left(S^{1}\right)$ we have $d f=\sum 2 \pi i n a_{n} e^{2 \pi i n z}$ which may not converge.

## 25 Review (Monday, March 15)

Remark 25.0.1: Recall that a sheaf of rings $\mathcal{F}$ on $X \in$ Top is an assignment of a $\operatorname{ring} \mathcal{F}(U)$ to each open set $U \subseteq X$ and restriction maps $\mathcal{F}(U) \xrightarrow{\rho_{U V}} \mathcal{F}(V)$ for $V \subseteq U$ that is a presheaf, so

1. This diagram commutes:


> Link to Diagram
2. $\varphi_{U U}=\mathbb{1}_{\mathcal{F}(U)}$ and $\mathcal{F}(\emptyset)=0$.

That additionally satisfies unique gluing on double overlaps.

Example 25.0.2(?): Any reasonable class of functions whose behavior is only locally restricted. Examples are being smooth or continuous, but e.g. being constant is a global condition. Other examples include $X \in \operatorname{Mfd}^{n}\left(C^{\infty}(-, \mathbb{R})\right)$, denoting $\mathcal{O}$ the sheaf of smooth functions. This also carries a sheaf of abelian groups $\Omega^{p}$. In the special case where $U$ is a coordinate chart, we have functions $\varphi_{U}: U \rightarrow \mathbb{R}^{n}$. Writing $S:=\varphi_{U}(U)$, we can define

$$
\Omega^{p}(U) \cong \Omega^{p}(S):=\left\{\sum f_{I}(\mathbf{x}) d x_{I} \mid f_{I} \in C^{\infty}\left(\mathbb{R}^{n}, \mathbb{R}\right)\right\}
$$

:::\{.remark\} More generally, for an arbitrary open $U$, cover it by coordinate charts $\left\{U_{i}\right\} \rightrightarrows U$. Then we want $\omega_{i} \in \Omega^{p}\left(U_{i}\right)$ which are compatible on double overlaps, so such a collection defines a section $\left\{\omega_{i} \mid i \in I\right\} \in \Gamma\left(\Omega^{p}(U)\right)$. The compatibility is given by taking coordinate charts $\varphi_{i}: U_{i} \rightarrow \mathbb{R}^{n}$ with $\omega_{i} \in \Omega^{p}\left(U_{i}\right)$, we consider

$$
t_{i j}: \varphi_{i} \circ \varphi_{2}^{-1}: \varphi_{j}\left(U_{i} \cap U_{j}\right) \rightarrow \varphi_{i}\left(U_{i} \cap U_{j}\right)
$$

and we require that the pullback satisfies $t_{i j}^{*}\left(\omega_{1}\right)=\omega_{2}$ This pullback can be thought of as a coordinate change for the forms. Writing $x_{I}$ as coordinates on $U_{i}$ and $y_{J}$ on $U_{j}$, we can write

$$
\begin{aligned}
& x_{1}=h_{1}\left(y_{J}\right) \\
& x_{2}=h_{2}\left(y_{J}\right) \\
& \vdots \\
& x_{n}=h_{n}\left(y_{J}\right)
\end{aligned}
$$

which expresses $t_{i j}$ in coordinates. This allows us to give meaning to the formal symbols $d x_{I}$ :

$$
\begin{aligned}
d x_{1} & :=\sum_{i=1}^{n} \frac{\partial h_{1}}{\partial y_{i}} d y_{i} \\
d x_{2} & :=\sum_{i=1}^{n} \frac{\partial h_{2}}{\partial y_{i}} d y_{i} \\
\vdots & \\
d x_{k} & :=\sum_{i=1}^{n} \frac{\partial h_{k}}{\partial y_{i}} d y_{i}
\end{aligned}
$$

and under these substitutions in the original expression we obtain

$$
\omega_{1}=\sum_{|I|=p} f_{I}(\mathbf{x}) d x_{I} \mapsto \omega_{2} .
$$

Remark 25.0.3: For $X \in \operatorname{Mfd}(\operatorname{Hol}(-, \mathbb{C}))$ such that $\varphi_{V} \circ \varphi_{U}^{-1}: \varphi_{U}(U \cap V) \rightarrow \varphi_{V}(U \cap V)$ is holomorphic, so $\bar{\partial} z_{i}=0$. Then $\Omega^{p}(U)=\left\{\sum_{|I|=p} f_{I}(\mathbf{z}) d z_{I}\right\}$, and the key difference is that the $f_{I}$ be holomorphic. This matters since POUs exist in the smooth setting but not the complex setting. Note that $\mathcal{O}, \Omega^{p}$ denote smooth/holomorphic functions and smooth/holomorphic $p$-forms in the smooth/complex settings. So we need a new notation for smooth holomorphic $p$-forms in the complex setting. We defined $A^{p, 0}$ to be the smooth $p$-forms, and $A^{p, q}$ the smooth $(p, q)$-forms. In local coordinates, these look like

$$
A^{p, q}(U)=\left\{\sum_{|I|=p,|J|=q} f_{I, J}(\mathbf{z}) d z_{I} \wedge d \bar{z}_{J}\right\} .
$$

## Example 25.0.4(?):

- $\Re(z) d z \in A^{1,0}(\mathbb{C})$ is a smooth ( 1,0 )-form.
- $z d w-w d z \in \Omega^{1}\left(\mathbb{C}^{2}\right)$ is a holomorphic 1 -form.
- On $\mathbb{C}^{3}, z_{1} d z_{2} \wedge d \bar{z}_{3}-\Re\left(z_{3}\right) d z_{1} d \bar{z}_{1} \in A^{1,1}\left(\mathbb{C}^{3}\right)$.

Remark 25.0.5: Why are these $A^{p, q}$ useful? They give a resolution of $\Omega^{p}$ on a complex manifold. There are maps of sheaves

$$
0 \rightarrow \Omega^{p} \xrightarrow{i} A^{p, 0}
$$

where being a map of sheaves means there are maps $\Omega^{p}(U) \rightarrow A^{p, 0}(U)$ for all opens $U$ which are compatible with restriction:


Link to Diagram

It's clear that this works for $i$, since any holomorphic function simply is smooth. We could continue this resolution:

$$
0 \rightarrow \Omega^{p} \xrightarrow{i} A^{p, 0} \xrightarrow{\bar{\sigma}} A^{p, 1}
$$

where

$$
\bar{\partial}\left(\sum_{I, J} f_{I, J} d z_{I} \wedge d \bar{z}_{J}\right):=\sum_{I, J, K} \frac{\partial f_{I, J}}{\partial z_{k}} d \bar{z}_{k} \wedge d z_{I} \wedge d \bar{z}_{J}
$$

We then defined Dolbeaut cohomology, $H^{q}\left(X, \Omega^{p}\right)=\operatorname{ker} \bar{\partial}_{p, q} / \operatorname{im} \bar{\partial}_{p, q-1}$.

## 26 Wednesday, March 17

### 26.1 Inverting Bundles

Remark 26.1.1: Continuing review: let $\mathcal{E} \rightarrow X \in \operatorname{Bun}\left(\mathbb{R}^{n}\right)$. A metric on $\mathcal{E}$ is a smoothly varying positive definite inner product on the fibers.


Fix this diagram! Need to remember what it was demonstrating.

For $v, w \in \mathcal{E}_{p}$, we want a pairing $g_{p}(v, w): \mathcal{E}_{p}^{\otimes 2} \rightarrow \mathbb{R}$. To think about this globally, this should be a map

$$
g: \mathcal{E}^{\otimes 2} \rightarrow \mathcal{O}
$$

where $g_{p}: \mathcal{E}_{p}^{\otimes 2} \rightarrow \mathbb{R}$. Note that this map is $\mathcal{O}$-linear, which follows from the fact that it's $\mathbb{R}$-linear on each fiber, or equivalently it is a map of vector bundles. We should also have that $g(s \otimes s) \in \mathcal{O}(X)$ is a smooth function, and we require $g(s \otimes s) \geq 0$. We also require $g(s \otimes s)(p)=0 \Longleftrightarrow s_{0}=0$ and $g(s \otimes t)=g(t \otimes s)$. This implies that $g \in\left(\mathcal{E}^{\otimes 2}\right)^{\vee} \otimes \mathcal{O}=\left(\mathcal{E}^{\vee}\right)^{\otimes 2}(X)$. The symmetric condition means that $g \in \operatorname{Sym}^{2} \mathcal{E}^{\vee}(X)$.

Remark 26.1.2: For Hermitian forms, we take

$$
h:\left(\mathbb{C}^{n}\right)^{\otimes 2} \rightarrow \mathbb{C}
$$

where $h$ is conjugate linear, so $h\left(c v, c^{\prime} w\right)=\bar{c} c^{\prime} h(v, w)$. Note that we can write $h(v, w)=\bar{v}^{t} H w$ where $H$ is Hermitian, so $\bar{H}^{t}=H$. This implies that $h(v, v) \in \mathbb{R}^{\geq 0}$ and $h(v, v)=0 \Longleftrightarrow v=0$ with $h(v, w)=\overline{h(v, w)}$ The great thing about metrics: we can identify zero sections by self-pairing, multiplying by a volume form, and integrating. For $\mathcal{E} \rightarrow X \in \operatorname{Bun}(\mathbb{C})$, there is another bundle $\overline{\mathcal{E}} \rightarrow X \in \operatorname{Bun}(\mathbb{C})$. Supposing that $\left.\mathcal{E}\right|_{U} \xrightarrow{\varphi_{U}} \mathcal{O}_{U}^{\oplus n}$ in a local trivialization, conjugating all of the
transition functions gives the transition functions $\left.\overline{\mathcal{E}}\right|_{U} \xrightarrow{\operatorname{conjo\varphi _{U}}} \mathcal{O}_{U}^{\oplus n}$. This yields a map

$$
h: \overline{\mathcal{E}} \otimes_{\mathbb{C}} \mathcal{E} \rightarrow \mathcal{O} \in(\overline{\mathcal{E}} \otimes \mathcal{E})^{\vee}
$$

In local trivializations we have $\left.\mathcal{E}\right|_{U}=\mathcal{O}_{U}^{\oplus n}=\mathbb{C}^{n} \times U$, and $h$ is described by $h_{U} \in\left(\overline{\mathcal{O}}^{\oplus n} \otimes \mathcal{O}^{\oplus n}\right)(U)$.

Remark 26.1.3: When $\operatorname{rank} \mathcal{E}=1$ we abuse notation! For $h \in\left(\overline{\mathcal{E}}^{\vee} \otimes \mathcal{E}^{\vee}\right)(X)$, this is locally a $1 \times 1$ Hermitian matrix, thus of the form $[a]$ for $a \in \mathbb{R}^{\geq 0}$. So we write

$$
h(s, t)=h s \bar{t}:=h \otimes s \otimes \bar{t} \in\left(\overline{\mathcal{E}}^{\vee} \otimes \mathcal{E}^{\vee}\right) \otimes \mathcal{E} \otimes \overline{\mathcal{E}}=\mathcal{O}
$$

if $\mathcal{E}$ is a line bundle. Why is $V \otimes V^{\vee}=\mathcal{O}$ in this case? There is a pairing $v \otimes \lambda \mapsto \lambda(v)$, or more generally a trace pairing.

### 26.2 Serre Duality Revisited

Remark 26.2.1: Let $X$ be a Riemann surface, so $X \in \operatorname{Mfd}^{1}(\mathbb{C})$. Let $L \rightarrow X \in \operatorname{Bun}{ }^{1}(\operatorname{Hol})$, then we have a resolution

$$
0 \rightarrow L \hookrightarrow L \otimes A^{0,0} \xrightarrow{\bar{\partial}} L \otimes A^{0,1} \rightarrow 0
$$

where the first map is inclusion of smooth holomorphic sections into smooth sections. What is this cut out by? We had $s \mapsto \bar{\partial} s$ and thus $f \mapsto \frac{\partial f}{\partial \bar{z}} d \bar{z}$. Note that $H_{1}(L)=$ coker $\bar{\partial}$.

Remark 26.2.2: Serre duality said that

$$
h^{1}(L)=\operatorname{dim} H^{1}(L)=h^{0}\left(L^{\vee} \otimes K\right) \quad K=\Omega^{1}
$$

where $\Omega^{1}$ is the sheaf of holomorphic 1-forms. Choose a metric to identify $H^{1}(L)$ and $H^{0}\left(L^{\vee} \otimes K\right)$. Choose a hermitian metric on $L$ and take $s, t \in H^{0}\left(L \otimes A^{0,0}\right)=C^{\infty}(L ; \mathbb{C})$, then we get $h(s, t) \in$ $C^{\infty}(X ; \mathbb{C})$ a smooth complex function. We abuse notation by writing this as $h(s, t)=h s \bar{t}$, viewing $h \in C^{\infty}\left(L^{\vee} \otimes \bar{L}^{\vee}\right)$ locally. Note that we can't integrate a function on a manifold without a form, so choosing a volume for $d V$ we can define a pairing on sections

$$
\langle s, t\rangle:=\int_{X} h s \bar{t} d V
$$

Now for two sections $\alpha, \beta \in H^{0}\left(L \otimes A^{0,1}\right)$ we can write

$$
\int_{X} h \alpha \bar{\beta}=\int_{X} \omega
$$

where $\omega$ is a smooth ( 1,1 )-form since $h \in \bar{L}^{\vee} \otimes L^{\vee}, \alpha \in L \otimes A^{0,1}$, and $\bar{\beta} \in \bar{L} \otimes A^{1,0}$. We now have metric on both the source and target spaces here:

$$
H^{0}\left(L \otimes A^{0,0}\right) \xrightarrow{\bar{b}} H^{0}\left(L \otimes A^{0,1}\right)
$$

where on the left-hand side we take $(s, t) \mapsto \int_{X} h s \bar{t} d V$ and on the right-hand side we have $(\alpha, \beta) \mapsto$ $\int_{X} h \alpha \bar{\beta}$.

Remark 26.2.3: Given a map of metric vector spaces $V \xrightarrow{\varphi} W$, the adjoint $\varphi^{\dagger}$ satisfies

$$
\langle\varphi(v), w\rangle=\left\langle v, \varphi^{\dagger}(w)\right\rangle
$$

and $\operatorname{coker}(\varphi)=\operatorname{ker}\left(\varphi^{\dagger}\right)$. So $H^{1}(L)=\operatorname{coker} \bar{\partial}=\operatorname{ker} \bar{\partial}^{\dagger}$, and after integrating by parts we have

$$
\begin{aligned}
\langle\alpha, \bar{\partial} s\rangle & :=\int_{X} \alpha \overline{\bar{\partial} s} h \\
& =\int_{X} \alpha \partial(\bar{s}) h \\
& =-\int_{X} \bar{s} \partial(\alpha h) \quad \mathrm{IBP} \\
& =-\int_{X} \bar{s} \frac{\partial(\alpha h)}{d V} d V \\
& =\left\langle-\frac{\partial(\alpha h)}{d V}, s\right\rangle
\end{aligned}
$$

So we could define

$$
\bar{\partial}^{\dagger} \alpha=\frac{\overline{-\bar{\partial}(\bar{\alpha} h)}}{d V}
$$

Note that $\alpha \mapsto \bar{\alpha} h$, so $\alpha \in \operatorname{ker} \bar{\partial}^{\dagger} \Longleftrightarrow \bar{\alpha} h \in \operatorname{ker} \bar{\partial}$. Then $\operatorname{ker}\left(\bar{\partial}^{\dagger}\right)=H^{0}\left(L^{\vee} \otimes K\right)$.

## 27 Friday, March 19

Remark 27.0.1: Recall Serre duality: let $C \in \operatorname{Mfd}_{\mathbb{C}}$ (compact, oriented) and $L \rightarrow C \in \operatorname{Bun}(\mathrm{Hol})$. Then

$$
h^{1}(L)=h^{0}\left(L^{\vee} \otimes K_{C}\right)
$$

We also have Riemann-Roch, a very important tool:

$$
h^{0}(L)-h^{1}(L)=\operatorname{deg} L+1-g(C)
$$

where $\operatorname{deg} L=\int_{C} c_{1}(L)$, which is also equal to $\operatorname{deg}[\{s=0\}]=\operatorname{deg}(\operatorname{Div} s)$. Note that $c_{1}$ is the most important Chern class to know, thanks to the splitting principle. How was it defined? There are several definitions:

1. $L$ defines an element of

$$
\begin{aligned}
H^{1}\left(C, \mathcal{O}^{\times}\right) & =\left\{t_{U V}: U \cap V \rightarrow \mathbb{C}^{\times} \mid t_{U V} t_{U W}^{-1} t_{V W}=1\right\} / \partial\left\{h_{u}: U \rightarrow \mathbb{C}^{\times}\right\} \\
& =\operatorname{ker} \partial^{1} / \operatorname{im} \partial^{0}
\end{aligned}
$$

in Čech cohomology. By definition $\partial\left\{h_{U} \mid U \in \mathcal{U}\right\}=\left\{h_{u} h_{v}^{-1} \mid U, V \in \mathcal{U}\right\}$, where $\partial^{2}=1$ since

$$
\left(h_{U} h_{V}\right)^{-1}\left(h_{U} h_{W}^{-1}\right)^{-1}\left(h_{V} h_{W}^{-1}\right)=1 \quad \text { on } U \cap V \cap W
$$

By assigning $L$ to its transition functions, we get a map $L \rightarrow H^{1}$. We have the exponential exact sequence:

$$
0 \rightarrow \underline{\mathbb{Z}} \rightarrow \mathcal{O} \xrightarrow{\exp } \mathcal{O}^{\times} \rightarrow 1
$$

which induces a map

$$
\begin{aligned}
H^{1}\left(C, \mathcal{O}^{\times}\right) & \rightarrow H^{2}(C, \mathbb{Z}) \\
L & \mapsto c_{1}(L)
\end{aligned}
$$

2. $L$ defines an element $\operatorname{Fr} L \in \operatorname{Bun}^{\text {prin }}\left(\mathbb{C}^{\times}\right)$(which only works for line bundles), which is defined by $\operatorname{Fr} L=L \backslash s_{0}$ where $s_{0}$ is the zero section of $L$. By topology, we get a classifying map

$$
C \xrightarrow{\varphi_{L}} B \mathbb{C}^{\times}=\mathbb{C P} \mathbb{P}^{\infty}=\left(\mathbb{C}^{\infty} \backslash\{0\}\right) / \mathbb{C}^{\times}
$$

There is a universal $c_{1} \in H^{2}\left(\mathbb{C P}{ }^{\infty} ; \mathbb{Z}\right)$, so we take the pullback to define $c_{1}(L):=\varphi_{L}^{*}\left(c_{1}\right)$. We can use that there is a cell decomposition $\mathbb{C P}=\mathbb{C}^{0} \cup \mathbb{C}^{1} \cup \mathbb{C}^{2} \cup \cdots$, and so there is a unique generator in its $H^{2}$.
3. Consider a smooth section $s \in C^{\infty}(L)$, then we can define $c_{1}(L):=[\{s=0\}]$ by taking the fundamental class, assuming that $s$ is transverse to the zero section $s_{z}$ of $L$. Here we view the zero set as an oriented submanifold. See picture: in this case $[\{s=0\}]=[p]-[q]+[r]$.

## Add picture.

Remark 27.0.2: Applying Serre duality to the left-hand side in Riemann-Roch yields the dimension of the space of holomorphic sections of some other bundle, $L^{\vee} \otimes K$.

Example 27.0.3(The structure sheaf): Applying Riemann-Roch to $L:=\mathcal{O}$, we get

$$
\chi(\mathcal{O})=h^{0}(\mathcal{O})-h^{1}(\mathcal{O})=0+1-g
$$

which is equal to $h^{0}(\mathcal{O})-h^{0}(K)$. But the only holomorphic functions on $\mathbb{C}$ are constant, so $h^{0}(\mathcal{O})=1$. In particular, $h^{0}(K)=g$, so any Riemann surface of genus $g$ has a $g$-dimensional space of holomorphic 1-forms.

Example 27.0.4(The Canonical Bundle): Applying Riemann-Roch to $L:=K$, we get

$$
\chi(K)=h^{0}(K)-h^{0}\left(K^{\vee} \otimes K\right)=\operatorname{deg}(K)+1-g
$$

Since $K^{\vee} \otimes K=\mathcal{O}$, we obtain $g-1=\operatorname{deg}(K)+1-g$, so $\operatorname{deg}(K)=2 g-2$.
We also proved this using that $K$ was the dual of holomorphic vector fields, i.e. $\int_{C} c_{1}(K)=$ $-\int_{C} c_{1}(T)$, which by Gauss-Bonnet equals $-\chi_{\operatorname{Top}}(C)=-(2-2 g)=2 g-2$.

Example 27.0.5(Genus 2 Riemann Surfaces): Taking $C$ of genus 2, we have $h^{0}\left(K_{C}\right)=g=2$, so $\operatorname{deg} K_{C}=2(2)-2=2$. Thus there exist linearly independent sections $s, t \in H^{0}\left(K_{C}\right)$, i.e. two linearly independent holomorphic 1 -forms. We can take the ratio $s / t$, which defines a map

$$
\frac{s}{t}: C \rightarrow \mathbb{P}^{1}
$$

Locally we have $s=f(z) d z$ for $z$ a local holomorphic coordinate on $C$ and $f \in \operatorname{Hol}(C, \mathbb{C})$, and similarly $t=g(z) d z$. So $s / t=f(z) / g(z)$ is meromorphic in this chart. Choosing a new coordinate chart $w$, this yields a transition function $z(w)$ - not of $L$, but from the atlas on $C$. We can write $s=f(z(w)) d(z(w))=f(z(w)) z^{\prime}(w) d w$ by the chain rule. Thus

$$
\frac{s}{t}(z)=\frac{f(z(w)) z^{\prime}(w) d w}{g(z(w)) z^{\prime}(w) d w}=\frac{s}{t}(w)
$$

So although $s / t$ was only defined in a coordinate chart, it winds up being independent of coordinates. This works in general for any holomorphic line bundle: for $s, t \in H^{0}(L)$, there is a map $\frac{s}{t}: C \rightarrow \mathbb{P}^{1}$ since writing $s_{V}=\varphi_{U V} s_{U}, t_{V}=\varphi_{U V} t_{U}$ where $\varphi_{U V}$ is the transition function for $L$.

## Fact 27.0.6

Important fact: we can take these ratios to get maps to $\mathbb{P}^{1}$.

## Slogan 27.0.7

The canonical bundle is the line bundle whose transition functions are the Jacobians of the change of variables for the atlas.

## Question 27.0.8

What is the degree of this map generically? I.e. given $\left[x_{0}: x_{1}\right] \in \mathbb{P}^{1}$ fixed, what is the size of the inverse image $\left(\frac{s}{t}\right)^{-1}\left(\left[x_{0}: x_{1}\right]\right) ?$

## Answer 27.0.9

Writing $s / t=x_{1} / x_{0}$, we have $x_{0} s-x_{1} t=0$. This is in $H^{0}\left(K_{C}\right)$, and we computed $\operatorname{deg} K_{C}=2$, meaning there are two zeros of this function. Thus is $g(C)=2$, there is a generically 2-to-1 map $C \rightarrow \mathbb{P}^{1}$, a degree 2 meromorphic function. Note that this section could have a double zero.

Example 27.0.10(?): Consider the curve $y^{2}=(z-1)(z-2) \cdots(z-5)$, where we think of $z, y \in \mathbb{P}^{1}$. This has roots $z=1, \cdots, 5$, and is equal to $\infty$ if $z=\infty$. These are the only points of $\mathbb{P}^{1}$ with just one square root, all other points have two square roots.



## 28 Monday, March 22

Remark 28.0.1: Last time: we reviewed Riemann-Roch, Serre duality, sheaves of $p$-forms. Recall a theorem from a few weeks ago:

## Theorem 28.0.2(The Hodge Theorem).

If $(X, g)$ is a compact oriented Riemannian manifold, then there is a decomposition of the smooth $p$-forms on $X$ :

$$
\Omega^{p}(X)=d \Omega^{p-1}(X) \oplus \mathcal{H}^{p}(X)+d^{\dagger} \Omega^{p+1}(X)
$$

Remark 28.0.3: Note that $\mathcal{H}$ was the space of harmonic $p$-forms, and $d^{\dagger}::=(-1)^{?} \star d \star$ where

$$
\begin{aligned}
& \star: \Omega^{p}(X) \\
& e_{i_{1}} \wedge \cdots \wedge \Omega^{n-p}(X) \\
& e_{i_{p}} \mapsto \pm e_{j_{1}} \wedge \cdots e_{j_{n-p}}
\end{aligned}
$$

where $\left\{e_{i}\right\}$ is an orthonormal basis of basis of $T^{\vee} X$. Note that this formula is replacing the $e_{i}$ that do appear with the $e_{i}$ that don't appear, up to a sign. The harmonic forms were defined as $\mathcal{H}^{p}(X)=\operatorname{ker}\left(d d^{\dagger}+d^{\dagger} d\right)=\operatorname{ker}(d) \cap \operatorname{ker}\left(d^{\dagger}\right)$. We proved that assuming this decomposition, there is an isomorphism

$$
\mathcal{H}^{p}(X) \cong H_{\mathrm{dR}}^{p}(X ; \mathbb{R})
$$

Example 28.0.4 (The circle $S^{1}$ ): There's a standard flat metric $g_{\text {std }}$ on $S^{1}$ where $g_{\text {std }}=d x^{2}$ with $x$ the coordinate on $\mathbb{R}$ which is the universal cover of $S^{1}$. We can write

$$
\Omega^{1}\left(S^{1}\right)=\left\{f(x) d x \mid f \in C^{\infty}\left(S^{1}, \mathbb{R}\right)\right\}
$$

since every 1-form $\omega$ looks like this. Then $d \omega=0$ since this is a 2 -form on $S^{1}$. On the other hand, what is $d^{\dagger}$ ? We know that $\star \omega$ is a 0 -form, so a function. The volume form is given by $\sqrt{\operatorname{det} g_{\mathrm{std}}}=\sqrt{\left[d x^{2}\right]}$, and you can wedge $1 \wedge d x=d x$, so $\star \omega=f(x)$. Then $d \star \omega=f^{\prime}(x) d x$ and $d^{\dagger} x \omega=f^{\prime}(x)$. If this is zero, $f^{\prime}(x)=0$ and $f$ is a constant function. So in this metric, $\mathcal{H}^{1}\left(S^{1}\right)=\mathbb{R}\langle d x\rangle \cong H^{1}\left(S^{1} ; \mathbb{R}\right)$.

Remark 28.0.5(Important): The harmonic forms $\mathcal{H}^{p}(X)$ depend on the metric $g$, despite mapping isomorphically to de Rham cohomology.

Remark 28.0.6: This was just in the case of a real smooth Riemannian manifold. What extra structure to we have for $X \in \operatorname{Mfd}(\operatorname{Hol}(-, \mathbb{C}))$ ?

Definition 28.0.7 (Kähler Forms (Important!))
Let $X \in \operatorname{Mfd}(\operatorname{Hol}(-, \mathbb{C}))$ be a complex manifold. A Kähler form $\omega \in \Omega^{2}\left(X_{\mathbb{R}}\right)$ is a closed real (possibly needed: $J$-invariant) 2-form on the underlying real manifold of $X$ for which $\omega(v, J w):=g(v, w)$ is a metric on $T X_{\mathbb{R}}$ where $J$ is an almost complex structure. The associated hermitian metric is $h:=g+i \omega$, which defines a hermitian form on $T X \in \operatorname{Vect}_{\mathbb{C}}$.

Example 28.0.8(?): Take $X:=\mathbb{C}^{n}$ and $J(v):=i \cdot v$. Note that $X_{\mathbb{R}}=\mathbb{R}^{2 n}$, so write its coordinates as $x_{k}, y_{k}$ for $k=1, \cdots, n$ where $z_{k}=x_{k}+i y_{k}$ are the complex coordinates. Consider $g=g_{\text {std }}$ on $\mathbb{R}^{2 n}$ - does this come from a closed 2-form $g_{\text {std }}=\sum\left(d x_{k}\right)^{2}+\left(d y_{k}\right)^{2}$ ? Using $\omega(v, J w)=g(v, w)$, we have $\omega\left(v, J^{2} w\right)=g(v, J w)$. The left-hand side is equal to $-\omega(v, w)$ and the right-hand side is
$\omega(v, w)=-g(v, J w)$. What 2-form does this give? We have

$$
\begin{aligned}
\omega\left(\frac{\partial}{\partial x_{k}}, \frac{\partial}{\partial x_{\ell}}\right) & =-g\left(\frac{\partial}{\partial x_{k}}, \frac{\partial}{\partial y_{\ell}}\right)=0 \\
\omega\left(\frac{\partial}{\partial y_{k}}, \frac{\partial}{\partial x_{\ell}}\right) & =-g\left(\frac{\partial}{\partial y_{k}}, \frac{\partial}{\partial y_{\ell}}\right)=0 \\
\omega\left(\frac{\partial}{\partial x_{k}}, \frac{\partial}{\partial y_{\ell}}\right) & =-g\left(\frac{\partial}{\partial x_{k}}, \frac{\partial}{\partial y_{\ell}}\right)=0 \quad \forall k \neq \ell \\
\omega\left(\frac{\partial}{\partial x_{k}}, \frac{\partial}{\partial y_{k}}\right) & =-g\left(\frac{\partial}{\partial x_{k}}, \frac{\partial}{\partial y_{k}}\right) \\
& =(-1)^{2} g\left(\frac{\partial}{\partial x_{k}}, \frac{\partial}{\partial x_{k}}\right) \\
& =1 \\
\omega\left(\frac{\partial}{\partial y_{k}}, \frac{\partial}{\partial x_{k}}\right) & =-1 .
\end{aligned}
$$

So we can write this in block form using blocks

$$
M=\left[\begin{array}{cc}
0 & 1 \\
-1 & 0
\end{array}\right] \quad \omega=\left[\begin{array}{lll}
M & & \\
& M & \\
& & M
\end{array}\right]
$$

which is a closed $(d \omega=0)$ antisymmetric 2 -form, i.e. a symplectic form, and

$$
\omega_{\mathrm{std}}=d x_{1} \wedge d y_{1}+d x_{2} \wedge d y_{2}+\cdots+d x_{n} \wedge d y_{n}
$$

Remark 28.0.9: So the Kähler geometry is determined by the data ( $\mathbb{C}^{n}, g_{\text {std }}, J, \omega_{\text {std }}$ ), i.e. a metric, an almost complex structure, and a symplectic form. Note that the relation $\omega(x, y)=g(x, J y)$ can be used to determine the 3 rd piece of data from any 2 . This is the fiberwise/local model, i.e. every tangent space at a point looks like this.

## $\triangle$ Warning 28.0.10

But note that a form being closed is not a tensorial property! So this local data (looking at a single fiber) is not quite enough to determine the global geometry.

Remark 28.0.11: Given $g$ and $J, \omega$ is automatically a 2 -form. That it's antisymmetric follows from

$$
\begin{aligned}
-\omega(w, v) & =-g(w, J v) \\
& =-g(J v, w) \\
& =-g\left(J^{2} v, J w\right) \\
& =g(v, J w) \\
& =\omega(v, w) .
\end{aligned}
$$

Conversely, we can always define $g(v, w):=-\omega(v, J w)$, but a priori this may not be a metric. This will be symmetric, but potentially not positive-definite.

Definition 28.0.12 ( $\omega$-tame almost complex structures)
An almost complex structure $J$ is $\omega$-tame if $g(v, w)=-\omega(v, J w)$ is positive definite.

Remark 28.0.13: Next time: we'll see that if $X$ is Kähler, then

$$
\mathcal{H}^{k}(X)=\bigoplus_{p+q=k} \mathcal{H}^{p, q}(X),
$$

so this is compatible with the Hodge decomposition. This is what people usually call the Hodge decomposition theorem, and gives some invariants of complex manifolds. By a miracle, this decomposition only depends on $g$ and the complex structure.

Remark 28.0.14: Note that there is a notion of hyperkähler manifolds, which have 3 complex structures $I, J, K$ such that $I^{2}=J^{2}=K^{2}=I J K=-\mathbb{1}$, yielding 3 "parallel" 2-forms $\omega_{I}, \omega_{J}, \omega_{K}$ such that the covariant derivative vanishes, i.e. $\nabla_{g}\left\{\omega_{I}, \omega_{J}, \omega_{K}\right\}=0$. With respect to the complex structure $I, \omega_{J}+\omega_{K}$ is a holomorphic 2 -form. There is a sphere's worth of almost complex structures, and there is an action $\mathrm{SO}\left(4, b_{2}-4\right) \curvearrowright H^{*}(X)$. There's no known example where the hyperkähler metric has been explicitly written down.

## 29 Wednesday, March 24

Remark 29.0.1: Last time: we defined a Kähler manifold: $X \in \operatorname{Mfd}(\mathbb{C})_{\text {compact }}$ and $\omega \in \Omega^{2}\left(X_{\mathbb{R}}\right)$ a closed real 2 -form such that $g(x, y):=\omega(x, J y)$ is a metric. By the Hodge theorem, we have a space $\mathcal{H}^{k}(X)$ of harmonic $k$-forms for $(X, g)$ which represents $H_{\mathrm{dR}}^{k}(X ; \mathbb{R})$. We can consider the $\mathbb{C}$-valued harmonic forms $\mathcal{H}_{\mathbb{C}}^{k}:=\mathcal{H}^{k}(X) \otimes_{\mathbb{R}} \mathbb{C}$, which represents $H_{\mathrm{dR}}^{k}(X ; \mathbb{C})$

## Question 29.0.2

How does this interact with the decomposition of the smooth $k$-forms

$$
\Omega^{k}\left(X_{\mathbb{R}}\right) \otimes_{\mathbb{R}} \mathbb{C}=\bigoplus_{p+q=k}^{K} A^{p, q}(X),
$$

where $\mathcal{H}_{\mathbb{C}}^{k}(X)$ is contained in this. Note that this is a small finite dimensional space in an infinite dimensional space! The following miracle occurs:

Theorem 29.0.3(Kähler manifolds admit a Hodge decomposition?).
If $X \in \operatorname{Mfd}$ (Kähler),

$$
\mathcal{H}_{\mathbb{C}}^{k}=\bigoplus_{p+q=k} \mathcal{H}^{p, q}(X)
$$

where

$$
\mathcal{H}^{p, q}(X):=\left(\mathcal{H}^{K}(X) \otimes_{\mathbb{R}} \mathbb{C}\right) \cap A^{p, q}(X) \subseteq \Omega^{k}\left(X_{\mathbb{R}}\right)
$$

Example 29.0.4(?): Let $X=\mathbb{C} / \Lambda$ be an elliptic curve where $\Lambda$ is a lattice. The standard metric $d x^{2}+d y^{2}$ on $\mathbb{C}$ descends to a metric on $X$ since translation is an isometry on the metric space $\left(\mathbb{C}, d x^{2}+d y^{2}\right)$. Let $z=x+i y$ be a complex coordinate on $\mathbb{C}$ so $d z=d x+i d y$ and $d \bar{z}=d x-i d y$, then $d x^{2}+d y^{2}=d z d \bar{z} \in \operatorname{Sym}^{2}(\mathrm{~T} \mathbb{C})$. The symplectic form is given by

$$
\omega(v, w)= \pm g(v, J w)=i d z d \bar{z}(v, w)
$$

since $J$ is given by $i$ on $\mathbb{C}$. Then $\omega(v, w)=i d z(v) d \bar{z}(w)$, i.e. $\omega=i d z \wedge d \bar{z}$. So

$$
\bar{\omega}=\bar{i} d \bar{z} \wedge d z=-i d \bar{z} \wedge d z=i d z d \bar{z}=\omega
$$

and this determines the Kähler geometry on $X$. What are the harmonic 1-forms on $X, \mathcal{H}^{1}(X) \otimes_{\mathbb{R}} \mathbb{C}$ ? Note that $\omega=d V$ is the volume form. The smooth 1-forms are given by

$$
\Omega^{1}\left(X_{\mathbb{R}}\right) \otimes_{\mathbb{R}} \mathbb{C}=A^{1,0}(X) \oplus A^{0,1}(X)=\{f(z, \bar{z}) d z\} \oplus\{g(z, \bar{z}) d \bar{z}\}
$$

where $f, g$ are smooth and $\Lambda$-periodic on $\mathbb{C}$ to make them well-defined. We can find the Hodge star:

$$
\begin{aligned}
\star & : ? \\
d z & \rightarrow i d \bar{z} \\
d \bar{z} & \mapsto-i d z .
\end{aligned}
$$

Writing $\alpha:=f(z, \bar{z}) d z+g(z, \bar{z}) d \bar{z}$, this is harmonic if $d \alpha=0$ and $\star d \star \alpha=0$. The first implies $\partial_{\bar{z}} f-\partial_{z} g=0$. What does the second imply? We can compute

$$
\begin{aligned}
\star \alpha & =i f(z, \bar{z}) d \bar{z}-i g(z, \bar{z}) d z \\
\Longrightarrow \partial_{z} f+\partial_{\bar{z}} g & =0
\end{aligned}
$$

and so $\partial_{\bar{z}} f=\partial_{z} g$ and $\partial_{\bar{z}}^{2} f=\partial_{\bar{z}} \partial_{z} g=-\partial_{z}^{2} f$, so

$$
\begin{aligned}
& \left(\partial_{\bar{z}}^{2}+\partial_{z}^{2}\right) f=0 \\
& \left(\partial_{\bar{z}}^{2}+\partial_{z}^{2}\right) g=0 .
\end{aligned}
$$

Note that this recovers the usual notion of harmonic functions on $\mathbb{C}$, i.e. being in the kernel of the Laplacian. The only biperiodic functions that satisfy these equations are constants, since there is a maximum modulus principle for harmonic functions. Thus

$$
\mathcal{H}^{1}(X) \otimes_{\mathbb{R}} \mathbb{C}=\left\{c_{1} d z+c_{2} d \bar{z}\right\}=\mathbb{C} d z \oplus \mathbb{C} d \bar{z}=H^{1,0}(X) \oplus H^{0,1}(X)
$$

Remark 29.0.5: There is a generalization to higher genus curves. Recall the following theorem:

## Theorem 29.0.6(Uniformization).

Let $C \in \mathrm{Mfd}^{1}(\mathbb{C})_{\text {compact }}$ of genus $g \geq 2$. Then the universal cover admits a biholomorphism

$$
\tilde{C} \cong \mathbb{H}:=\{z \in \mathbb{C} \mid \Im(z)>0\}
$$

Remark 29.0.7: This essentially follows from the Riemann mapping principle.

Corollary 29.0.8(Every curve of genus $g>1$ is the plane mod a subgroup of biholomorphisms).
Any curve $C$ of genus $g \geq 2$ is of the form $C=\mathbb{H} / \Gamma$ where $\Gamma \leq \operatorname{BiHol}(\mathbb{H})$ is a subgroup that acts freely. By covering space theory, $\Gamma=\pi_{1}(C)$, and it's known that $\operatorname{BiHol}(\mathbb{H}) \cong \mathrm{PSL}_{2}(\mathbb{R})$ by the map

$$
\left[\begin{array}{cc}
a & b \\
c & d
\end{array}\right] z \mapsto \frac{a z+b}{c z+d}
$$

Proposition 29.0.9(The upper half-plane admits a PSL-invariant hyperbolic metric).
The upper half plane $\mathbb{H}$ admits a hyperbolic metric which is invariant under $\operatorname{PSL}_{2}(\mathbb{R})$ given by

$$
g_{\mathrm{hyp}}=\frac{d x^{2}+d y^{2}}{y^{2}}=\frac{d z d \bar{z}}{\Im(z)^{2}}
$$

## Proof (?).

This follows from a computation:

$$
\begin{aligned}
d\left(\frac{a z+b}{c z+d}\right) & =\frac{a d z}{c z+d}-\frac{c(a z+b) d z}{(d z+d)^{2}} \\
& =\frac{a(c z+d)-c(a z+b) d z}{(c z+d)^{2}} \\
& =\frac{(a d-b c) d z}{(c z+d)^{2}} \\
& =\frac{d z}{(c z+d)^{2}} \\
& =\frac{d\left(\frac{a z+b}{c z+d}\right) d\left(\frac{a z+b}{c z+d}\right)}{\Im\left(\frac{a z+b}{c z+d}\right)^{2}} \\
& =\frac{d z d \bar{z}}{(c z+d)^{2}(c \bar{z}+d)^{2} \Im\left(\frac{a z+b}{c z+d}\right)} \\
& =\frac{d z d \bar{z}}{\Im(z)^{2}}
\end{aligned}
$$

Remark 29.0.10: It's miraculous! The biholomorphisms of $\mathbb{H}$ preserve a metric. So $C$ has a canonical metric, $g_{\text {hyp }}$, which descends along the quotient map $\mathbb{H} \rightarrow \mathbb{H} / \Gamma \cong \mathbb{C}$.

## Question 29.0.11

What are the harmonic 1-forms on $\left(C, g_{\mathrm{hyp}}\right)$ ?

Remark 29.0.12: By lifting we can write

$$
\Omega^{1}\left(C_{\mathbb{R}}\right) \otimes_{\mathbb{R}} \mathbb{C}=A^{1,0}(C) \oplus A^{0,1}(C)=\left\{f(z, \bar{z}) d z+g(z, \bar{z}) d \bar{z} \mid z \in \mathbb{H}, f, g \in C^{\infty}(\mathbb{C}, \mathbb{R})\right\}
$$

But $d z$ is not invariant under the map $z \mapsto \frac{a z+b}{c z+d}$, since $d z \mapsto \frac{d z}{(c z+d)^{2}}$. In order to descend $f(z)$ to $C$, we need

$$
f\left(\frac{a z+b}{c z+d}\right)=(c z+d)^{2} f(z) \quad \text { for all }\left[\begin{array}{ll}
a & b \\
c & d
\end{array}\right] \in \Gamma
$$

This says that $f$ is a modular form of weight 2 .
Exercise 29.0.13 (?)
Check that this implies that $f$ must be holomorphic and $g$ must be antiholomorphic.

## Fact 29.0.14

There is a decomposition

$$
\mathcal{H}^{1}\left(C_{\mathbb{R}}\right) \otimes_{\mathbb{R}} \mathbb{C}=\mathcal{H}^{1,0}(C) \oplus \mathcal{H}^{0,1}(C),
$$

and the first space will be the space of holomorphic 1-forms $H^{0}\left(K_{C}\right)$, and the second term will be $\overline{H^{0}\left(K_{C}\right)}$. This shows the power of the Hodge decomposition theorem!

## $30 \mid$ Friday, March 26th

Remark 30.0.1: Recall the Hodge decomposition theorem. Let $(M, g) \in \operatorname{Mfd}_{\mathbb{R}}^{n}$ (Riem, compact), then choosing an orthonormal basis $\left\{v_{j}\right\}$ for $T_{p} M$ yields a corresponding orthonormal basis in $T_{p}{ }^{\vee} M:=\underset{\mathbb{R}}{\operatorname{Hom}}\left(T_{p} M, \mathbb{R}\right)$ given by taking $\left\{e_{i} \mid e_{i}\left(v_{j}\right)=\delta_{i j}\right\}$.


There is a map

$$
\begin{aligned}
\star & : \bigwedge^{k} T_{p}{ }^{\vee} M
\end{aligned} \rightarrow \bigwedge_{j=1}^{n-k} T_{p} \vee^{\vee} M .
$$

where the $e_{j}$ are defined such that $\bigwedge_{j=1}^{k} e_{i_{j}} \wedge \bigwedge_{\ell=1}^{n-k} e_{j_{\ell}}:=d V$, where $d V$ is the volume form on $M$ at $p$. Thus we have a map

$$
\begin{aligned}
\star: \Omega^{k} & \rightarrow \Omega^{n-k} \\
1 & \mapsto d V .
\end{aligned}
$$

We defined $d^{\dagger}:=\star c t$, and said a form $\omega$ was harmonic iff $\Delta \omega=0$, where $\Delta:=d d^{\dagger}+d^{\dagger} d$. The space of such forms was denoted $\mathcal{H}^{k}(M) \subseteq \Omega^{k}(M)$.

Theorem 30.0.2 (Hodge Theorem).

$$
\mathcal{H}^{k}(M) \cong H_{\mathrm{dR}}^{k}(M ; \mathbb{R})
$$

## Question 30.0.3

What kinds of extra structure can we put on a complex manifold?

Definition 30.0.4 (Kähler Form)
A Kähler form is a closed 2-form $\omega \in \Omega_{\mathbb{R}}^{2}$ such that the following equation defines a metric on $T_{p} M$ :

$$
g(u, v):=\omega(u, i v)
$$

I.e., this is a closed symplectic form that defines a metric.

Example 30.0.5(?): Consider $M=\mathbb{C}^{n}$ with holomorphic coordinates $z_{1}, z_{2}, \cdots, z_{n}$, where $z_{j}:=$ $x_{j}+i y_{j}$. Then take

$$
\omega:=\sum_{j=1}^{n} d x_{j} \wedge d y_{j}
$$

Note that multiplication by $i$ induces a map

$$
\begin{aligned}
\cdot i: T_{p} \mathbb{C}^{n} \circlearrowleft & \\
\frac{\partial}{\partial x_{j}} & \mapsto \frac{\partial}{\partial y_{j}} \\
\frac{\partial}{\partial y_{j}} & \mapsto-\frac{\partial}{\partial x_{j}}
\end{aligned}
$$

Moreover, $\omega(u, i v)$ recovers the standard metric on $\mathbb{C}^{n}$ given by

$$
g_{\mathrm{std}}=\sum\left(d x_{j}\right)^{2}+\left(d y_{j}\right)^{2} \in \operatorname{Sym}^{2} T^{\vee} \mathbb{C}^{n}
$$

which is incidentally positive-definite, where $(d x)^{2}(u, v):=\left(\frac{\partial}{\partial x_{j}}\right) u \cdot *\left(\frac{\partial}{\partial y_{j}}\right) v$. Is this closed? We need to check to see if $d \omega=0$, but this is true: applying $d$ to all of the coefficients yields the constant 1.

Remark 30.0.6: So for $M \in \operatorname{Mfd}(\mathbb{C})$ a complex manifold, we have a decomposition

$$
\begin{aligned}
\Omega^{k}(M) & =\bigoplus_{p+q=k} A^{p, q}(M) \\
A^{p, q} & :=\left\{\sum_{\substack{|I|=p \\
|J|=q}}\left(d z_{i_{1}} \wedge \cdots d z_{i_{p}}\right) \wedge\left(d z_{j_{1}} \wedge \cdots d z_{j_{q}}\right)\right\} .
\end{aligned}
$$

For $M$ a Kähler manifold, we have

$$
\begin{gathered}
\mathcal{H}^{k}(M)=\bigoplus_{p+q=k} \mathcal{H}^{p, q}(M) \\
\mathcal{H}^{p, q}(M)=\mathcal{H}^{k}(M) \cap A^{p, q}(M) .
\end{gathered}
$$



Remark 30.0.7: Why is this true? We have a map

$$
d: A^{p, q}(M) \rightarrow A^{p+1, q}(M) \oplus A^{p, q+1}(M)
$$

where for example if $f(z):=z \bar{z} \in A^{0,0}(\mathbb{C})$, we have $d f=\bar{z} d z+z d \bar{z}$ where the first is a $(1,0)$ form and the latter is a $(0,1)$ form. Write $d=\partial+\bar{\partial}$ where $\partial:=\sum d z_{j}$ and $\bar{\partial}=\sum d \bar{z}_{j}$, as well as

$$
d^{\dagger}: A^{p, q}(M) \rightarrow A^{p-1, q}(M) \oplus A^{p, q-1}(M)
$$

Now $\star$ of a $(p, q)$ form is an $(n-p, n-q)$ form, and so

$$
\star\left(d z_{i_{1}} \wedge \cdots \wedge d z_{i_{r}} \wedge d \bar{z}_{j_{1}} \wedge \cdots \wedge d \bar{z}_{q}\right):=\star\left(d z_{I} \wedge d \bar{z}_{J}\right)= \pm d z_{I^{c}} \wedge d \bar{z}_{J^{c}}
$$

and we have $d^{\dagger}=\partial^{\dagger}+\bar{\partial}^{\dagger}$. We can thus move around the bigraded group in several ways:


## Link to Diagram

## Theorem 30.0.8(Kähler Identities).

Let

$$
\begin{aligned}
& \Delta_{\bar{\partial}}:=\bar{\partial} \bar{\partial}^{\dagger}+\bar{\partial}^{\dagger} \bar{\partial} \\
& \Delta_{\partial}:=\partial \partial^{\dagger}+\partial^{\dagger} \partial \\
& \Delta_{d}:=d d^{\dagger}+d^{\dagger} d .
\end{aligned}
$$

Then

$$
\frac{1}{2} \Delta_{d}=\Delta_{\bar{\partial}}=\Delta_{\partial} .
$$

Remark 30.0.9: See Griffiths-Harris for details. Note that this is a local statement, i.e. it can be checked in coordinate charts.

Remark 30.0.10: The upshot:

$$
\mathcal{H}^{k}(M)=\operatorname{ker} \Delta_{d}=\operatorname{ker} \Delta_{\bar{\partial}},
$$

and moreover

$$
\Delta_{\bar{\partial}}: A^{p, q}(M) \circlearrowleft
$$

which implies that on $\Omega^{k}(M)$,

$$
\operatorname{ker} \Delta_{\bar{\partial}} \circ \bigoplus_{p+q=k} \operatorname{ker}\left(A^{p, q}(M) \xrightarrow{\Delta_{\bar{\rightharpoonup}}} A^{p, q}(M)\right)=\bigoplus_{p+q=k} \operatorname{ker} \Delta_{d},
$$

which yields the Hodge decomposition theorem

$$
\mathcal{H}^{k}(M)=\bigoplus_{p+q=k} \mathcal{H}^{p, q}(M)
$$

Remark 30.0.11: This is a strong restriction on what manifolds can admit a Kähler structure. Moreover, since $\Delta_{d}$ is a real operator, we obtain $\overline{\mathcal{H}^{p, q}(M)} \cong \mathcal{H}^{p, q}(M)$.

Remark 30.0.12: Some consequences:
For $M$ a Kähler manifold, the odd Betti numbers $\beta_{2 i+1}(M):=\operatorname{dim} H_{\mathrm{dR}}^{2 i+1}(M ; \mathbb{C})$ are even. This is because

$$
\bigoplus_{p+q=k} \mathcal{H}^{p, q} \cong \mathcal{H}^{2 i+1}(M) \cong H_{\mathrm{dR}}^{2 i+1}(M) .
$$

If we define $h^{p, q}(M):=\operatorname{dim}_{\mathbb{C}} \mathcal{H}^{p, q}(M)$, we clearly have

$$
\beta_{2 i+1}=\sum_{p+q=2 i+1} h^{p, q}(M) .
$$

Now using that $\overline{\mathcal{H}} \cong \mathcal{H}$, we can rewrite this as

$$
\begin{aligned}
\beta_{2 i+1} & =\sum_{p+q=2 i+1} h^{p, q}(M) \\
& =2 \sum_{\substack{p+q=2 i+1 \\
p<q}} h^{p, q}(M) .
\end{aligned}
$$

Remark 30.0.13: Is this just some fact about arbitrary complex manifolds, with no extra structure? The answer is no, and the counterexample is the Hopf surface

$$
X:=\left(\mathbb{C}^{2} \backslash\{\mathbf{0}\}\right) /(x, y) \sim(2 x, 2 y)
$$

which we can roughly identify as $\mathbb{R}^{4}$ "modulo doubling". We can take a fundamental domain $1 \leq|r| \leq 3$, this yields an annulus-like sphere with the inner shell glued to the outer:


This is homeomorphic to $S^{1} \times S^{3}$, but $\beta_{1}(M)=1$, so this won't yield a Kähler structure.

## 31 Monday, March 29

Remark 31.0.1: Last time: the Hodge decomposition theorem. Let $(X, g) \in \operatorname{Mfd}_{\mathbb{C}}^{\text {compact }}$ (Kähler), then the space of harmonic $k$-forms $\mathcal{H}^{k}(X) \otimes_{\mathbb{R}} \mathbb{C}$ decomposes as $\bigoplus_{p+q=k} \mathcal{H}^{p, q}(X)$. There is also a symmetry $\overline{\mathcal{H}^{p, q}(X)}=\mathcal{H}^{q, p}(X)$. We have an isomorphism to the de Rham cohomology $\mathcal{H}^{k}(X) \otimes_{\mathbb{R}} \mathbb{C} \cong$ $H_{\mathrm{dR}}^{k}(X ; \mathbb{C})$. We know the constituent pieces as well, as well as several relationships:

$$
\begin{aligned}
\mathcal{H}^{p, q}(X) & =\operatorname{ker}\left(\Delta_{d}: A^{p, q}(X) \circlearrowleft\right) \\
\Delta_{\bar{\partial}} & =\bar{\partial} \bar{\partial}^{\dagger}+\bar{\partial}^{\dagger} \bar{\partial} \\
\Delta_{d} & =2 \Delta_{\bar{\partial}}
\end{aligned}
$$

There was a proposition that $\operatorname{ker}\left(\Delta_{d}\right)=\operatorname{ker}(d) \cap \operatorname{ker}\left(d^{\dagger}\right)$, and the same proposition holds for $\Delta_{\bar{\partial}}$. In this case we have $\operatorname{ker}\left(\Delta_{\bar{\partial}}\right)=\operatorname{ker}(\bar{\partial}) \cap \operatorname{ker}\left(\bar{\partial}^{\dagger}\right)$ on $A^{p, q}(X)$, and this is isomorphic to $\operatorname{ker}(\bar{\partial}) / \operatorname{im}(\bar{\partial})$. Recall that we resolved the sheaf $\Omega^{p}$ of holomorphic $p$-forms by taking the Dolbeault resolution

$$
0 \rightarrow \Omega^{p} \rightarrow A^{p, 0} \xrightarrow{\overline{\mathrm{~b}}} A^{p, 1} \xrightarrow{\overline{\mathrm{~b}}} A^{p, 2} \rightarrow \cdots
$$

Thus we can identify $\operatorname{ker}(\bar{\partial}) / \operatorname{im}(\bar{\partial}) \cong \mathcal{H}\left(X ; \Omega^{p}\right)$ as sheaf cohomology. We defined $h^{p, q}(X):=$ $\operatorname{dim}_{\mathbb{C}} H^{p, q}(X)$.

## Corollary 31.0.2(Homology is independent of the choice of Kähler form).

$h^{p, q}(X)$ is independent of the Kähler form, noting that the isomorphism to sheaf cohomology doesn't involve taking adjoints, and $\operatorname{dim}_{\mathbb{C}} \mathcal{H}^{q}\left(X ; \Omega^{p}\right)$ doesn't depend on the complex structure.

Remark 31.0.3: A priori, one could vary the Kähler form and have some $h^{p, q}$ jump or drop dimension. It also turns out that varying the complex structure will also not change these dimensions.

Remark 31.0.4: Whenever the Hodge-de Rham spectral sequence degenerates, one generally gets $\sum_{p+q} h^{p, q}=h^{k}$. Note that there is a resolution:

$$
0 \rightarrow \mathbb{\mathbb { C }} \rightarrow \mathcal{O} \xrightarrow{d} \Omega^{1} \xrightarrow{d} \Omega^{2} \xrightarrow{d} \cdots
$$

which is not acyclic and thus has homology. In general, the spectral sequence is

$$
E_{p, q}^{1}=\mathcal{H}^{q}\left(X ; \Omega^{p}\right) \Rightarrow \mathcal{H}^{p+q}(X ; \mathbb{C})
$$

## Fact 31.0.5

A fact about the cohomology of vector bundles: given a family of Kähler manifolds $X_{t}$, one can consider $H^{q}\left(X_{t} ; \mathcal{E}_{t}\right.$ where $\mathcal{E}_{t}$ is a family of holomorphic vector bundles. This can only jump upward in dimension, i.e. $\operatorname{dim}_{\mathbb{C}} H^{q}\left(X_{t} ; \mathcal{E}_{t}\right)$ is lower semicontinuous.

Example 31.0.6(?): Consider

$$
X_{t}:=\left\{x^{3}+y^{3}+z^{3}+t x y z=0\right\} \subseteq \mathbb{C P}^{2}
$$

where $t$ varies in $\mathbb{C}$. These all admit a line bundle $\mathcal{L}_{t}:=\left.\mathcal{O}(1)\right|_{X_{t}}$, the anti-tautological line bundle on $\mathbb{P}^{2}$.


The real points of this vanishing locus form an elliptic curve, and each $X_{t}$ is a Riemann surface of genus 1. Note that $h^{0,1}$ can jump on closed sets, but $H^{1}$ is constant since Riemann-Roch involves genus and degree. What is $\left.\operatorname{deg} \mathcal{O}(1)\right|_{X_{t}}$ ? Take a section $s \in H^{0}\left(\mathbb{P}^{2} ; \mathcal{O}(1)\right)$ which vanishes on a line in $\mathbb{P}^{2}$. How many points lie in a line intersected with $X_{t}$ ? Looking at fundamental classes, we have $\left[X_{t}\right]=3 \ell$, and by Bezout $3 \ell \cdot \ell=3$.

The point is that $H^{q}\left(X_{t} ; \Omega^{p}\right)$ can only possibly increase at special values of $t$. Assuming the $X_{t}$ are all diffeomorphic, then $h^{k}\left(X_{t}\right)$ is constant and $h^{p, q}\left(X_{t}\right)$ can't jump. So the $h^{p, q}$ are invariants of families.

Definition 31.0.7 (Hodge Diamond)
The Hodge Diamond of $X \in \operatorname{Mfd}($ Kähler) (which won't depend on the choice of Kähler form) is given by


## Link to Diagram

Note that there are symmetries, e.g. $\star$ takes $h^{1,0}=h^{n-1, n}$ and $\overline{h^{p, q}}=h^{q, p}$.

## Proposition 31.0.8(CYs have extra Hodge diamond symmetry).

If $X$ is Calabi-Yau, so $K_{X}=\mathcal{O}_{X}$ (i.e the canonical bundle is trivial), then the Hodge diamond has an orientation preserving $(\mathbb{Z} / 2)^{2}$ symmetry, i.e. there is a rotation by $\pi / 2$.

Note: this isn't extra symmetry! Just a proof of the symmetry in this case.

## Proof (?).

Let $\Omega_{X}^{k}$ be the sheaf of holomorphic $k$-forms, then there is a map

$$
\begin{aligned}
& \Omega_{X}^{k} \otimes \Omega_{X}^{n-k} \rightarrow \Omega_{X}^{n}:=K_{X} \\
& \alpha \otimes \beta \mapsto \alpha \wedge \beta .
\end{aligned}
$$

Fiberwise, this is a perfect pairing. If one takes $\alpha:=e_{i_{1}} \wedge \cdots e_{i_{k}} \in \bigwedge^{k} T_{x}{ }^{\vee} X$, there is a unique basis wedge $\beta:=e_{j_{1}} \wedge \cdots \wedge e_{j_{n}-k}$ then $\alpha \wedge \beta$ is a basis wedge $e_{1} \wedge \cdots \wedge e_{n}$. So $\Omega_{X}^{k} \cong\left(\Omega_{X}^{n-k}\right)^{\vee}$
if $X$ is Calabi-Yau. By Serre duality,

$$
\mathcal{H}^{p}\left(X ; \Omega_{X}^{q}\right)^{\vee} \cong \mathcal{H}^{n-p}\left(X ;\left(\Omega_{X}^{q}\right)^{\vee} \otimes K_{X}\right)
$$

Example 31.0.9(?): In dimension 3, take

$$
X:=\left\{x_{0}^{5}+\cdots+x_{4}^{5}=0\right\} \subseteq \mathbb{P}^{4} \in \operatorname{Mfd}^{3}(\mathbb{C})
$$

See Hodge diamond.

Remark 31.0.10: Note that $K 3$ s are special CYs. An example is $\mathbb{C}^{2} / \Lambda$ for $\Lambda$ a rank 4 lattice. This is diffeomorphic to $\left(S^{1}\right)^{4}$, for example $E \times E$.

## 32 Wednesday, March 31

### 32.1 Polyvector Fields

Remark 32.1.1: We have a perfect pairing

$$
\Omega^{k} \otimes \Omega^{n-k} \rightarrow K
$$

and thus $\Omega^{n-k} \cong K \otimes\left(\Omega^{k}\right)^{\vee}$. So we have

$$
H^{p}\left(\Omega^{k}\right)^{\vee} \cong H^{n-p}\left(\left(\Omega^{k}\right)^{\vee} \otimes K\right)=H^{n-p}\left(\Omega^{n-k}\right)
$$

and thus $h^{p, k}=h^{n-p, n-k}$, which recovers what we knew about $\star: \mathcal{H}^{p, q} \rightarrow \mathcal{H}^{n-p, n-q}$.

So we don't get anything new from the Serre duality argument.
What is special when $X \in \mathrm{CY}$ is that

$$
\Omega^{n-k} \cong\left(\Omega^{k}\right)^{\vee}=\bigwedge^{k} T X
$$

for $T X$ the tangent bundle. Note that taking the cotangent bundle gives forms, and instead this gives a bundle of polyvector fields. For $k=1$, we get a holomorphic vector field, which one might think of as an infinitesimal biholomorphism.


Example 32.1.2(?): $\mathbb{P}^{1}$ has a holomorphic vector field in coordinate charts $\mathbb{C} \cong\left\{[z: 1] \in \mathbb{P}^{1}\right\}$ which we'll write as $z \frac{\partial}{\partial z}$. The coordinate chart is $\mathbb{P}^{1} \backslash \infty$, so we obtain


Does this vector field $V$ extend over $\infty$ ? The local coordinate at $\infty$ is $w=1 / z$, so $z=1 / w$ and we can compute

$$
\frac{1}{w} \frac{\partial}{\partial \frac{1}{w}}=\frac{1}{w} \frac{\partial}{\frac{-1}{w^{2}} \partial w}=-w \frac{\partial}{\partial w}
$$

We have $\operatorname{Ord}_{0} V=1$ and $\operatorname{Ord}_{\infty} V=1$, and so $\operatorname{deg} T \mathbb{P}^{1}=2$.

Example 32.1.3(?): For $\bigwedge^{2} T$, the local sections are of the form $\sum f_{I} \frac{\partial}{\partial x_{I}} \wedge \frac{\partial}{\partial x_{J}}$ instead of e.g. $\frac{d}{d x_{I}}$. This yields a Poisson structure $H^{0}\left(X, \bigwedge_{\bigwedge} T\right)$, which is a generalization of symplectic structure, which would be a section $\omega \in H^{0}\left(X, \bigwedge^{2} T^{\vee}\right)$ which is nondegenerate. This would yield an isomorphism $\omega: T \xrightarrow{\sim} T^{\vee}$ which is alternating, in which case $\omega^{-1}: T^{\vee} \xrightarrow{\sim} T$ which is also
alternating, so $\omega^{-1} \in H^{0}\left(X, \bigwedge^{2} T\right)$. However the Poisson structure need not be nondegenerate.

Remark 32.1.4: Polyvector fields show up in Hochschild homology!

### 32.2 Algebraic Surfaces

Definition 32.2.1 (Algebraic Surface)
An algebraic surface is a compact complex 2-fold (so of complex dimension and real dimension 4 , admitting local charts to $\mathbb{C}^{2}$ ) which admits a holomorphic embedding into $\mathbb{C P}^{N}$ for some $N$.

Remark 32.2.2: This implies that $S$ is a projective variety cut out by homogeneous polynomials in $N+1$ variables in $\mathbb{C P}^{N}$.

Example 32.2.3(?): A non-example would be $\mathbb{C}^{2} \backslash\{(0,0)\} /(x, y) \sim(2 x, 2 y)$, The Hopf surface. This is a complex manifold of complex dimension 2. It is compact, but has no projective embedding!

Example 32.2.4(?): Another non-example is $\mathbb{C}^{2} \backslash\{0\} /(x, y) \sim\left(2 x, 2 e^{i \theta} y\right)$, a twisted Hopf surface. This admits no nontrivial holomorphic line bundles.

Remark 32.2.5: What makes having a projective embedding special? If $S \hookrightarrow \mathbb{C} \mathbb{P}^{N}$, it admits a line bundle: $\mathcal{O}_{S}(1):=\left.\mathcal{O}_{\mathbb{C P}^{N}}(1)\right|_{S}$.

## Proposition 32.2.6(Existence of the Fubini-Study form/metric).

$\mathbb{C} \mathbb{P}^{N}$ is a Kähler manifold, and admits a distinguished 2-form $\omega:=\omega_{\mathrm{FS}}$ the Fubini-Study form which induces the Fubini-Study metric $g_{\mathrm{FS}}$.

Remark 32.2.7: This can be written down as $\frac{i}{2} \partial \bar{\partial} \log \left(\sum_{i=1}^{N} z_{i} \bar{z}_{i}\right)$, which is well-defined since scaling comes out as a constant. Being closed follows from $\partial \bar{\partial}=d \bar{\partial}$ since $\bar{\partial}^{2}=0$, which implies $d(\partial \bar{\partial} \cdots)=$ $d^{2} \bar{\partial}(\cdots)=0$. This defines a metric: this follows from checking in local coordinate charts, say $z_{0}=1$, and checking that $g(x, y):=\omega(x, J y)$ yields a metric. This involves taking a fussy derivative!

Remark 32.2.8: Thus given $S \stackrel{\varphi}{\hookrightarrow} \mathbb{C} \mathbb{P}^{N}$, we can restrict or take the pullback of $\omega_{\mathrm{FS}}$ to $S$. Then $\omega:=\varphi^{*} \omega_{\mathrm{FS}}$ is still Kähler:

1. $\omega$ is closed: this is true for any smooth map at the level of smooth manifolds because of the chain rule.
2. $\omega$ defines a metric: this is true because $S$ is a complex submanifold. Suppose $v, w \in T_{p} S$, and we want to check if $g(v, w):=\omega(v, J w)$. This equals $\omega_{\mathrm{FS}}(v, J W)$, viewing $T_{p} S \subseteq T_{p} \mathbb{C P}^{N}$, so this is equal to $g_{\mathrm{FS}}(v, w)$.

Remark 32.2.9: Note that a submanifold of a symplectic manifold is not necessarily a symplectic submanifold, since there are Lagrangian submanifolds for which the symplectic form restricts to 0 and isn't nondegenerate. However, Kähler forms do restrict.

Remark 32.2.10: So we get a Hodge diamond:

|  | $h^{2,2}$ |  |
| :--- | :--- | :--- |
| $h^{2,0}$ | $h^{1,2}$ |  |
|  | $h^{1,1}$ |  |
| $h^{0,2}$ |  |  |
|  | $h^{0,0}$ | $h^{0,1}$ |

## Link to Diagram

Here $h^{2,0}=h^{0}\left(\Omega^{2}\right)=h^{0}(K)=g$ is called the genus in analogy with curves. Similarly, $h^{1,0}=h^{0}\left(\Omega^{1}\right)$ is the space of holomorphic 1 -forms, sometimes referred to as the irregularity. There is some symmetry:

> 1
> $q$
> $g$
> $h^{0,0}$
> $g$
> $q \quad q$
> 1
> Link to Diagram

Exercise 32.2.11 (?)
Solve for $h^{1,1}$ in terms of $q$ and $g$.

## 33 Friday, April 02

### 33.1 When Line Bundles are $\mathcal{O}$ of a Divisor

Remark 33.1.1: Last time: if we have such a Hodge diamond, can we solve for $h^{1,1}$ ?


Recall Noether's formula

$$
\begin{aligned}
\chi\left(S, \mathcal{O}_{S}\right) & =\int \operatorname{ch}\left(\mathcal{O}_{S}\right) \operatorname{td}(S) \\
& =\int_{S} \frac{x_{1}}{1-e^{-x_{1}}} \frac{x_{2}}{1-e^{-x_{2}}} \\
& =\frac{K^{2}+\chi_{\mathrm{Top}}(S)}{12},
\end{aligned}
$$

where $c_{1}(T S)=-K$ and $\chi_{\text {Top }}$ is due to the Chern-Gauss-Bonet formula. We have

$$
\chi\left(\mathcal{O}_{S}\right)=h^{0}\left(\mathcal{O}_{S}\right)-h_{1}\left(\mathcal{O}_{S}\right)+h^{2}\left(\mathcal{O}_{S}\right)=1-q+p
$$

On the other hand,

$$
\chi_{\text {Top }}(S)=1-2 q+\left(2 p+h^{1,1}\right)-4 q=1-4 q+2^{p}+h^{1,1}
$$

so

$$
12(1-q+p)=K^{2}+2-4 g+2 p+h^{1,1} \Longrightarrow h^{1,1}=110-8 q+10 p-K^{2}
$$

Remark 33.1.2: Recall the extraordinarily important exact sequence

$$
0 \rightarrow \mathcal{O}(-p) \rightarrow \mathcal{O} \rightarrow \mathcal{O}_{p} \rightarrow 0
$$

where the right-hand side is the sheaf of holomorphic functions vanishing at $p$ and this is an inclusion into the sheaf of holomorphic functions, and the right-hand term is the skyscraper sheaf. There is a similar exact sequence for an embedded curve $C \hookrightarrow S$ in a surface:

$$
0 \rightarrow \mathcal{O}_{S}(-C) \rightarrow \mathcal{O}_{S} \rightarrow \mathcal{O}_{C} \rightarrow 0
$$

where the left term is the sheaf of holomorphic functions vanishing on $C$. Note that this has no global sections! Any function vanishing along a compact subset (?) are constant (?). Locally on an open set $U$, one can write $C \cap U=V\left(f_{u}\right)$, since algebraically this ring is locally a PID. So this is a line bundle, where we can map into the trivial bundle by $\varphi \mapsto \varphi / f_{u}$. Thus

$$
\mathcal{O}_{S}(U) / \mathcal{O}_{S}(-C)(U) \cong \mathcal{O}_{C}(C \cap U)
$$

We then get surjectivity since every holomorphic function on $C$ extends to a holomorphic function on $S$.

Now letting $\mathcal{E} \in \operatorname{Vect}(\mathrm{Hol})$, we can tensor this exact sequence to get

$$
\left.0 \rightarrow \mathcal{E}(-C) \rightarrow \mathcal{E} \rightarrow \mathcal{E}\right|_{C} \rightarrow 0
$$

which is also exact since locally we have the splitting principle.

Proposition 33.1.3(Every line bundle over a smooth projective complex manifold is $O$ of a divisor).
Let $X$ be a smooth projective ${ }^{a}$ complex manifold. Then every line bundle over $X$ is of the form $L=\mathcal{O}_{X}(D)$ for some divisor $D=\sum n_{i} D_{i} \in \mathbb{Z}\left[\operatorname{SubMfds}\left(\operatorname{codim}_{1}\right)\right]$.

[^2]
### 33.2 Proof

Proof (?).
Let $H$ be a hyperplane section, i.e. an intersection of $X$ with a generic hyperplane in $\mathbb{C P}^{N}$.

## Lemma 33.2.1(Serre Vanishing Theorem).

For any vector bundle $\mathcal{E}$ and all $i>0$, for $k \gg 0$ we have

$$
h^{i}(X, \mathcal{E} \otimes \mathcal{O}(k H))=0
$$

Remark 33.2.2: We'll not prove this! It requires some heavy analysis and the Kähler identities, see Huybrechts complex geometry Prop 5.27.

We can write

$$
\begin{aligned}
\chi(L \otimes \mathcal{O}(k H)) & =\int_{X} \operatorname{ch}(L \otimes \mathcal{O}(k H)) \operatorname{td}(X) \\
& =\int_{X} \operatorname{ch}(L) \operatorname{ch}(H)^{k} \operatorname{td}(X) \\
& =\int_{X}\left(1+c_{1}(L)+\frac{c_{1}(L)^{2}}{2}+\cdots\right) \cdot\left(1+k h+\frac{(k h)^{2}}{2}+\cdots+\frac{(k h)^{\operatorname{dim} X}}{(\operatorname{dim} X)!}\right) \cdot\left(1+\operatorname{td}_{1}(X)+\operatorname{td}_{2}( \right.
\end{aligned}
$$

where $h$ is the restriction of the generator of $H^{2}\left(\mathbb{C P}^{N} ; \mathbb{Z}\right)$ to $X$. Note that for $k$ large, the dominating term grows like $(k h)^{\operatorname{dim} X}$, so asymptotically we have

$$
\cdots \sim \int_{X} \frac{k^{\operatorname{dim} X} h^{\operatorname{dim} X}}{(\operatorname{dim} X)!}
$$

What is this $\operatorname{dim}(X)$-fold intersection?


We can slice $X$ by multiple hyperplanes, each homologically perturbed, and so $\int_{X} h^{\operatorname{dim} X}$ is the number of points where $\operatorname{dim} X$ generic hyperplanes intersect $X$, which is called the degree $\operatorname{deg} X$. This roughly follows from $\int_{X} \omega_{\mathrm{FS}}^{\operatorname{dim} X}>0$. Alternatively, suppose $X \cap H=\emptyset$, then
$X \hookrightarrow H^{c}=\mathbb{A}^{N}$. Then each holomorphic coordinate restricts to a constant on $X$ by the maximal principle.
Back to what we were proving: we have

$$
\chi(L \otimes \mathcal{O}(k H)) \sim c k^{\operatorname{dim} X}
$$

for $c$ some constant. By Serre Vanishing, $h^{i}(L \otimes \mathcal{O}(k H))=0$ for $k \gg 0$, and so we obtain

$$
h^{0}(L \otimes \mathcal{O}(k H)) \sim c k^{\operatorname{dim} X} \Longrightarrow \exists k \text { s.t. } h^{0}(L \otimes \mathcal{O}(k H))>0
$$

We conclude that there is some nonzero section $s \in \mathcal{H}^{0}(X ; L \otimes \mathcal{O}(k H))$ for which $\mathcal{O}(\operatorname{Div} s) \cong$ $L \otimes \mathcal{O}(k H)$. Thus $L \cong \mathcal{O}(\operatorname{Div} s-k H)$, where $\operatorname{Div} s-k H$ is some divisor.

Remark 33.2.3: With some more work, one can show $L \cong \mathcal{O}(C-D)$ for $C, D$ smooth divisors.

### 33.3 Aside

Remark 33.3.1: Felix Klein has a "proof" of the existence of a meromorphic function on a Riemann surface. The argument roughly goes as follows: take your Riemann surface and make it out of metal. Attach it to a battery:


This induces an electric potential function $V: C \rightarrow \mathbb{R}$, where $V$ is the real part of the meromorphic function. Here $V$ is a harmonic function away from $p$ and $q$.

## 34 Monday, April 05

Remark 34.0.1: Last time: line bundles are of the form $\mathcal{O}(D)$ for $D$ a divisor, and the extremely important SES

$$
0 \rightarrow \mathcal{O}_{S}(-D) \rightarrow \mathcal{O}_{S} \rightarrow \mathcal{O}_{D} \rightarrow 0
$$

We now want to discuss an alternative characterization of the intersection form on an algebraic surface. The next result comes from Beauville's "Complex Algebraic Surfaces":

Proposition 34.0.2(Formula for computing intersection numbers between complex curves).
Let $S \in \mathrm{Mfd}^{2}(\mathbb{C})^{\text {compact }}$, then the intersection number between complex curves $C, D$ can be
computed in the following ways:

$$
C \cdot D=\left.\operatorname{deg} \mathcal{O}_{S}(C)\right|_{D}=\sum_{p \in C \cap D} \operatorname{len}_{p}(C \cap D)
$$

where we'll define $\underset{p}{\text { len }}$ soon.

Remark 34.0.3: This will count intersection points after a small perturbation. Note that not every two curves will intersect transversely: consider $\mathbb{P}_{2}$ with a line $C$ and a tangent conic $D$ :


## Proof (?).

We have the first equality because

$$
C \cdot D=\int_{S}[C] \frown[D]=\int_{C} i^{*}[D]
$$

where $i: C \hookrightarrow S$ is the inclusion. This equality holds because if $\alpha \in \Omega^{2}$ is a 2-form,

$$
\int_{S}[C] \cdot \alpha=\left.\int \alpha\right|_{C}
$$

Using the pullback commutes with taking Chern classes, we can write the

$$
\int_{C} i^{*}[D]=\int_{C} i^{*}\left(c_{1}(\mathcal{O}(D))\right)=\int_{C} c_{1}\left(i^{*} \mathcal{O}(D)\right)=\left.\int_{C} \mathcal{O}(D)\right|_{C}=\left.\operatorname{deg} \mathcal{O}(D)\right|_{C}
$$

Note that this formula was symmetric, so we could have done this the other way to obtain $\left.\operatorname{deg} \mathcal{O}_{S}(C)\right|_{D}=\left.\operatorname{deg} \mathcal{O}_{S}(D)\right|_{C}$.
For the second equality, consider the following 4 -term exact sequence:

$$
0 \rightarrow \mathcal{O}_{S}(-C-D) \xrightarrow[p_{1}]{\stackrel{\left[s_{D}, s_{C}\right]}{\longrightarrow}} \mathcal{O}_{S}(-C) \oplus \mathcal{O}_{S}(-D) \xrightarrow[p_{2}]{\left[s_{D},-s_{C}\right]^{t}} \mathcal{O}_{S} \rightarrow \mathcal{p}_{3} \mathcal{O}_{C \cap D} \rightarrow 0
$$

For the first map, we have
$\{$ Functions vanishing on $C+D\} \hookrightarrow\{$ Functions vanishing on $C\} \oplus\{$ Functions vanishing on $D\}$.
Locally we can write $C=V(f)$ and $D=V(g)$ for some holomorphic functions $f, g \in \operatorname{Hol}(U, \mathbb{C})$. We have the following picture:

## $S$



We have $s_{C} \in H^{0}\left(S ; \mathcal{O}_{S}(C)\right)$ and $s_{D} \in H^{0}\left(S ; \mathcal{O}_{S}(D)\right)$ as global sections where $V\left(s_{c}\right)=$ $C, V\left(s_{D}\right)=D$. In a local trivialization, we can assume $\left.s_{C}\right|_{U}=f$ and $\left.s_{D}\right|_{U}=g$. So the first map is $\left(s_{D}, s_{C}\right)$. The next map is $\left[s_{C},-s_{D}\right]^{t}$ as a column vector, i.e. given a section we map it in the following way:

$$
\left(\varphi_{1}, \varphi_{2}\right) \in H^{0}\left(U, \mathcal{O}_{S}(-C) \oplus \mathcal{O}_{S}(-D)\right) \mapsto \varphi_{1} \cdot s_{D}-\varphi_{2} \cdot s_{C}
$$

Why is this exact? Considering the composition, we have

$$
\varphi \xrightarrow{p_{1}}\left(\varphi s_{D}, \varphi s_{C}\right) \xrightarrow{p_{2}}\left(\varphi s_{D}\right) s_{C}-\left(\varphi s_{C}\right) s_{D}=0 .
$$

So we get $\operatorname{im} p_{1} \subseteq \operatorname{ker} p_{2}$. Why do we have the reverse containment for exactness? Looking locally, given a pair $\varphi_{1}, \varphi_{2} \in \operatorname{Hol}(U ; \mathbb{C})$ such that $\varphi_{1} \varphi-\varphi_{2} g=0$ and locally $\left(\varphi_{1}, \varphi_{2}\right) \in \operatorname{ker} p_{2}$, we want to show that $\varphi_{1}=g \varphi, \varphi_{2}=f \varphi$ for some $f, g \in \operatorname{Hol}(U ; \mathbb{C})$. Equivalently, we want to show that

$$
\varphi_{1} f=\varphi_{2} g \Longrightarrow g \mid \varphi_{1}
$$

If this is true, then we can set $\varphi:=\frac{\varphi_{1}}{g}$, since this would yield $g \varphi=\varphi_{1}$ and $f \varphi=\frac{f \varphi_{1}}{g}=\varphi_{2}$. Note that we can divide here because the $\operatorname{ring} \operatorname{Hol}(U ; \mathbb{C})$ is a domain (i.e. it has no zero divisors) on small sets.

## Question

Is $\operatorname{Hol}(U, \mathbb{C})$ a PID in general?

## Answer

No! Take $U \subseteq \mathbb{C}^{2}$ a ball around $z=0$, then $\langle x, y\rangle$ is not principal.

However, this will form a UFD, which is weaker but still enough here. This is not obvious, but can be proved using the Weierstrass preparation theorem. This should be believable since $R$ a UFD implies $R[x]$ is a UFD, and $\mathbb{C}[x, y] \subsetneq \operatorname{Hol}(U ; \mathbb{C}) \subsetneq \mathbb{C}[[x, y]]$, and the latter is a UFD. So we do get exactness at this position.
For exactness at the next position $\mathcal{O}_{S}(-C) \oplus \mathcal{O}_{S}(-D) \rightarrow \mathcal{O}_{S}$, locally we have $\left(\varphi_{1}, \varphi_{2}\right) \mapsto$ $\varphi_{1} f-\varphi_{2} g$ where $V(f)=C \cap U$ and $V(g)=D \cap U$. We can write $\varphi_{1} f-\varphi_{2} g=\langle f, g\rangle$ locally, so the cokernel sheaf of $p_{2}$ is given by

$$
\operatorname{coker} p_{2}(U):=\frac{\mathcal{O}_{S}(U)}{\operatorname{im} p_{2}}=\frac{\mathcal{O}_{S}(U)}{\langle f, g\rangle}
$$

By definition, this is equal to $\mathcal{O}_{V(f, g)}=\mathcal{O}_{C \cap D}$, and if $C \cap D \cap U=\emptyset$ then $\mathcal{O}_{C \cap D}(U)=0$. So let $p \in \mathcal{O}_{C \cap D}$ and let $U_{p} \ni p$ which contains no other points $q \in C \cap D$, since the set of intersection points is isolated (and thus finite). Note that compactness here prevents accumulation of intersection points. In this case, $\mathcal{O}_{C \cap D}\left(U_{p}\right)$ will be a finite-dimensional vector space $\mathbb{C}^{d}$, and we'll define $\operatorname{len}_{p}(C \cap D):=d$.

Example 34.0.6(?): Let $U=\mathbb{C}^{2}$ and take $f=y$ so $C:=V(f)$ is the x-axis, and set $g=y-x^{2}$
so $D:=V(g)$ is a parabola. We're then considering

$$
\frac{\operatorname{Hol}\left(\mathbb{C}^{2}\right)}{y \operatorname{Hol}\left(\mathbb{C}^{2}\right)+\left(y-x^{2}\right) \operatorname{Hol}\left(\mathbb{C}^{2}\right)}=\frac{\operatorname{Hol}\left(\mathbb{C}^{2}\right)}{\left\langle y, x^{2}\right\rangle} .
$$

Elements in the ideal can be expanded as power series of the form $a_{0,1} y+a_{2,0} x^{2}+a_{1,1} x y+a_{2,2} y^{2}$, where there is no $a_{1,0} \sim x^{1} y_{0}$ coefficient, nor any $a_{0,0} \sim x^{0} y^{0}$ coefficient. So this quotient is isomorphic to $\mathbb{C} 1 \oplus \mathbb{C} x$, which is 2-dimensional, so $\underset{(0,0)}{\operatorname{len}} V(y) \cap V(x)=2$. Geometrically we have the following, where this is picking up the multiplicity 2 intersection:


Remark 34.0.7: What's the payoff of this algebraic work? We can compute the Euler characteristic as

$$
\chi\left(\mathcal{O}_{C \cap D}\right)=h^{0}\left(\mathcal{O}_{C \cap D}\right)=\sum_{p \in C \cap D} \operatorname{len}_{p}(C \cap D) .
$$

But by additivity of $\chi$ over exact sequences, we also have

$$
\begin{aligned}
\chi\left(\mathcal{O}_{C \cap D}\right) & =\chi\left(\mathcal{O}_{S}\right)-\chi\left(\mathcal{O}_{S}(-C)\right)-\chi\left(\mathcal{O}_{S}(-D)\right)+\chi\left(\mathcal{O}_{S}(-C-D)\right) \\
& \stackrel{H R R}{=} \int_{S}\left(\operatorname{ch}\left(\mathcal{O}_{S}\right)-\operatorname{ch}\left(\mathcal{O}_{S}(-C)\right)-\operatorname{ch}\left(\mathcal{O}_{S}(-D)\right)+\operatorname{ch}\left(\mathcal{O}_{S}(-C-D)\right)\right) \operatorname{td}(S) \\
& =c_{1}\left(\mathcal{O}_{S}(-C)\right) \cdot c_{1}\left(\mathcal{O}_{S}(-D)\right) \\
& =(-[C]) \cdot(-[D]) \\
& =C \cdot D
\end{aligned}
$$

Remark 34.0.8: Next time: adjunction formula that allows computing genus for surfaces.

## 35 Wednesday, April 07

Remark 35.0.1: Last time: let $C, D \subset S$ be distinct curves, then the intersection number is given by

$$
C \cdot D=\left.\operatorname{deg} \mathcal{O}_{S}(C)\right|_{D}=\sum_{p \in C \cap D} \operatorname{len}_{p}(C \cap D)
$$

where $\operatorname{len}_{p}(C \cap D):=\operatorname{dim}_{\mathbb{C}} \mathcal{O}(U) /\langle f, g\rangle$ where $V(f)=C \cap U$ and $V(g)=D \cap U$ with $f, g \in \mathcal{O}(U)=$ $\operatorname{Hol}(U)$. Here we're also assuming that $C \cap D \cap U=\{p\}$.

### 35.1 Adjunction Formula

Remark 35.1.1: We'll now discuss a way to compute the genus of a curve in a surface.

## Proposition 35.1.2 (Adjunction Formula).

Let $C \subset S$ be a smooth curve, then $K_{C}=\left.\left(K_{S} \otimes \mathcal{O}_{S}(C)\right)\right|_{C}$, which is restriction of a line bundle. Note that $K_{C}=\Omega_{C}^{1}$ is the sheaf of holomorphic 1-forms, but $K_{S}=\Omega_{S}^{2}$ since we take the sheaf of top forms.

## Proof (?).

Let $s \in \Omega_{S}^{2} \otimes \mathcal{O}(C)(U)$ be a section, then $s_{C}$ is a section of $\mathcal{O}_{C}$ vanishing along $c$ and have $s / s_{C}$ a meromorphic section of $\Omega_{S}^{2}(U)$. Here dividing by $s_{C}$ is like tensoring with $\mathcal{O}(-C)$. This can have poles along $\left\{s_{C}=0\right\}=C$ up to first order.
There is a residue map: let $p \in C$ be a point and $\gamma_{p}(r)$ be an oriented loop in $S \backslash C$ around $p \in C$ of radius $r$ (a meridian):


We can assemble a 1-form from the following contour integral:

$$
\operatorname{Res}_{C} \frac{s}{s_{C}}:=\lim _{r \rightarrow 0} \frac{1}{2 \pi i} \oint_{\gamma_{p}(r)} \frac{s}{s_{C}} \in \Omega^{1}(U \cap C)
$$

Locally $C=V(x)$ in a coordinate chart of $\mathbb{C}^{2}$ where $s_{C}=x$, so this is roughly of the form $\oint_{|x|=r} \frac{f(x, y)}{x} d x \wedge d y$, which is a one form in the variable $y$. Note that if $f$ were analytic, writing $f=a_{0,0}+a_{0,1} y+a_{0,2} y^{2}+\cdots+a_{1,0} x+\cdots$, we would have

$$
\operatorname{Res}_{C} \frac{s}{s_{C}}=\left(a_{0,0}+a_{0,1} y+a_{0,2} y^{2}+\cdots\right) d y=f(0, y) d y \text { locally }
$$

which picks out all components not involving $x$. This defines an $\mathcal{O}$-linear map

$$
\begin{aligned}
\Omega_{S}^{2} \otimes \mathcal{O}_{C} & \rightarrow \Omega_{C}^{1} \\
s & \mapsto \operatorname{Res}_{C} \frac{s}{s_{C}}
\end{aligned}
$$

since it doesn't involve any derivatives of $f$. Note that this only depends on the restriction of $s$ to $C$. What is the kernel of Res? We claim it is $\Omega 2_{S}$, which follows from the fact that the contour integral of any holomorphic form $\omega$ will integrate to zero. We thus get a SES of sheaves

$$
0 \rightarrow \Omega_{S}^{2} \xrightarrow{\cdot_{C}} \Omega_{S}^{2} \otimes \mathcal{O}(C) \rightarrow \Omega^{1}(C) \rightarrow 0
$$

where we send holomorphic forms to meromorphic forms with at most order 1 poles along $C$ to holomorphic 1-forms on $C$. The residue map is surjective since we can take

$$
\underset{x=0}{\operatorname{Res}} \frac{g(y)}{x} d x \wedge d y=g(y) d y
$$

so locally an arbitrary 1-form is a residue of some 2-form with simple poles along $C$. We have a SES
and tensoring with the line bundle $\Omega^{2} \otimes \mathcal{O}(C)$ we obtain

$$
\left.0 \rightarrow \Omega_{S}^{2} \rightarrow \Omega_{S}^{2} \otimes \mathcal{O}(C) \rightarrow \Omega_{S}^{2} \otimes \mathcal{O}(C)\right|_{C} \rightarrow 0
$$

Since cokernels are unique, we have $\left.\Omega_{C}^{1} \cong \Omega_{S}^{2} \otimes \mathcal{O}(C)\right|_{C}$, which yields the adjunction formula.

## Corollary 35.1.3(The Genus Formula).

We have

$$
\left.\operatorname{deg} \Omega_{S}^{2} \otimes \mathcal{O}(C)\right|_{C}=\operatorname{deg} \Omega_{C}^{1}=2 g-2
$$

where $g=g(C)$ is the genus of $C$. On the other hand, the left-hand side is equal to

$$
\left(K_{S}+C\right) \cdot C=2 g(C)-2
$$

Example 35.1.4(?): We showed $K_{\mathbb{P}^{n}}=\mathcal{O}(-n-1)$ where $\mathcal{O}(-1)$ was the tautological line bundle over $\mathbb{P}^{n}$. So for example $K_{\mathbb{P}^{2}}=\mathcal{O}(-3)=-3 L$ where $L \in H^{2}\left(\mathbb{P}^{2}, \mathbb{Z}\right)$ is a hyperplane (here a line) in $\mathbb{P}^{2}$.

Corollary 35.1.5(Formula for genus of a curve in terms of degree).
Let $f$ be a degree $d$ homogeneous polynomial in $x, y, z$, then $V(f) \subseteq \mathbb{P}^{2}=\{[x: y: z]\}$. If $C:=V(f)$ is a smooth complex curve, then applying the genus formula yields

$$
2 g(C)-2=(-3 L+d L) \cdot d L
$$

Using that $L^{2}=1$, this equals $d(d-3)$ and thus

$$
g(C)=\frac{d^{2}-3 d+2}{2}=\binom{d-1}{2}
$$

Example 35.1.6(?): If $d=3$ and say $f(x, y, z)=x^{3}+y^{3}+z^{3}$, then $V(f) \subseteq \mathbb{P}^{2}$ has genus $\binom{3-1}{2}=1$. So this is diffeomorphic to a torus.

Example 35.1.7(?): If $d=2$ then $g(C)=0$, so conics in $\mathbb{P}^{2}$ have genus zero, and we proved that every genus zero curve is isomorphic to $\mathbb{P}^{1}$. So conics in $\mathbb{P}^{2}$ are isomorphic to $\mathbb{P}^{1}$ (as are lines of course!).

Example 35.1.8(?): If $d=4$ then $g(C)=3$

## Theorem 35.1.9(Harnack Curve Theorem).

Noting that $\mathbb{R P}^{2} \subset \mathbb{C P}^{2}=\mathbb{P}^{2}$, the number $n_{C}$ of connected components of a curve $C \cap \mathbb{R} \mathbb{P}^{2}$ satisfies

$$
n_{C} \leq 1+g(C)
$$

Remark 35.1.10: See the Trott curve:

$$
144\left(x^{4}+y^{4}\right)-225\left(x^{2}+y^{2}\right)+350 x^{2} y^{2}+81=0
$$

whose plot looks like the following:
$f(x, y)=12^{\wedge} 2 *\left(x^{\wedge} 4+y^{\wedge} 4\right)-15^{\wedge} 2 *\left(x^{\wedge} 2+y^{\wedge} 2\right)+350 * x^{\wedge} 2 * y^{\wedge} 2+81$
implicit_plot(f, (x,-1,1), (y,-1,1))


Figure 4: image_2021-04-09-16-40-49

Example 35.1.11(?): Consider $S:=\mathbb{P}^{1} \times \mathbb{P}^{1}$, which is homeomorphic to $S^{2} \times S^{2}$. The homology is given by $\mathbb{Z}$ in degrees 0 and $4, \mathbb{Z}^{\oplus 2}$ in degree 3 , and 0 elsewhere. What is the intersection form on $\mathbb{Z}^{\oplus 2}=H^{2}\left(\mathbb{P}^{1} \times \mathbb{P}^{1} ; \mathbb{Z}\right)$ ? The two generators are $f_{1}=\left[S^{2} \times \mathrm{pt}\right], f_{2}=\left[\mathrm{pt} \times S^{2}\right]$. We can compute

- $f_{1} \cdot f_{1}=0$
- $f_{1} \cdot f_{2}=1$
- $f_{2} \cdot f_{2}=0$

This is because we can perturb these to be transverse:


Since $f_{2} \cap f_{2}^{\prime}=\emptyset$, we have $f_{2} \cdot f_{2}^{\prime}=f_{2} \cdot f_{2}=0$, and similarly with 1 . So the Gram matrix is

$$
G=\left[\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right] .
$$

So setting $C=\mathbb{P}^{1} \times \mathbb{P}^{1}=V\left(f_{2,3}\right)$, a function of bidegree (2,3), writing the coordinates as $[x: y],[z$ : $w$ ], we can write this as $x^{2} z^{3}+y^{2} z^{2} w+x y w^{3}=0$. We get

$$
2 g(C)-2=\left(K_{\mathbb{P}^{1} \times \mathbb{P}^{1}}+2 f_{1}+3 f_{2}\right) \cdot\left(2 f_{1}+3 f_{2}\right)=f_{2} \cdot\left(2 f_{1}+3 f_{2}\right)=2,
$$

since $K_{\mathbb{P}^{1}}=-2 f_{1}-2 f_{2}$ and so $g(C)=2$.

## 36 Friday, April 09

Remark 36.0.1: Recall the adjunction formula: for $D \subset X \in \operatorname{Mfd}_{\mathbb{C}}$ a codimension 1 complex submanifold, we have

$$
K_{D}=\left.\left(K_{x}+\mathcal{O}_{x}(0)\right)\right|_{D} .
$$

We'll apply this to curves $C$ in a surface $S$. Recall the genus formula, which was given by $2 g(C)-2=$ $\left(C+K_{S}\right) \cdot C$. For example, a degree 4 equation in $\mathbb{P}^{2}$ carves out a genus $g(C)=3$ complex curve.

Remark 36.0.2: Recall that line bundles on $\mathbb{C P}^{n}$ were in bijection with $\mathbb{Z}$, where send $d$ to a bundle $\mathcal{O}(d):=\mathcal{O}_{\mathbb{C P}^{N}}(d)$. We produced the tautological line bundle $\mathcal{O}(-1)$ whose fiber over $\mathbf{x} \subseteq \mathbb{C P}^{n}$ is the line in $\mathbb{C}^{n}$ spanned by its coordinates. We have $\mathcal{O}(-1)^{\vee}:=\mathcal{O}(1)$, and $\mathcal{O}(n):=\mathcal{O}(1)^{\otimes n}$. Alternatively, it was characterized in terms of homogeneous functions, where the fiber $\mathcal{O}(n)_{\mathbf{x}}$ are the linear functions $L$ on lines $\{\lambda \mathbf{x}\} \rightarrow \mathbb{C}$ such that $L(\lambda p)=\lambda^{n} L(p)$. Noting that these are linear functions, such $L$ form a 1-dimensional $\mathbb{C}$-vector space.

Example 36.0.3(K3 Surfaces): The classic example is $x_{0} \in \mathcal{O}(1)_{\mathbf{x}}$ since $x_{0}(\lambda p)=\lambda x_{0}(p)$. Similarly, $x_{0}^{2}+x_{1} x_{2} \in \mathcal{O}(2)_{\mathbf{x}}$ since

$$
x_{0}^{2}+x_{1} x_{2}(\lambda p)=\lambda^{2}\left(x_{0}^{2}+x_{1} x_{2}(p)\right)
$$

Remark 36.0.4: Note that the global sections were given by $\Gamma^{0}\left(\mathbb{P}^{n}, \mathcal{O}(d)\right)=H^{0}\left(\mathbb{P}^{n} ; \mathcal{O}(d)\right)$ was the span of degree $d$ monomials in $x_{0}, \cdots, x_{n}$. For example $x_{0}^{2}+x_{1} x_{2}$ is a well-defined element of $\mathcal{O}(2)_{p}$ which varies holomorphically with $p$, yielding a section:


Example 36.0.5(?): For a K3 surface, consider $S=\left\{\sum_{i=0}^{4} x_{i}^{4}=0\right\} \subset \mathbb{C P}^{3}$. By the adjunction formula,

$$
K_{S}=\left.\left(K_{\mathbb{C P}^{3}} \otimes \mathcal{O}_{\mathbb{C P}^{3}}(S)\right)\right|_{S}
$$

Note that if $s \in H^{0}(\mathcal{L})$, we can recover $\mathcal{O}(\operatorname{Div} S)=\mathcal{L}$. Moreover, $K_{\mathbb{C P}^{3}}=\mathcal{O}(-4)$ and $\mathcal{O}_{\mathbb{C P}^{3}}(S)=$ $\mathcal{O}(4)$ since we can view the formula as a function on the tautological line, which yields a section. So we get $K_{S}=\mathcal{O}(-4) \otimes \mathcal{O}(4)=\mathcal{O}(0)=\mathcal{O}$, i.e. these yield actual functions on $\mathbb{C P}^{n}$ since they're products of functions that scale by $\lambda^{-4}$ and functions that scale by $\lambda^{4}$. We're using the fact that $\mathcal{O}_{\mathbf{p}=\left[x_{0}: \cdots: x_{n}\right]}$ are functions $L$ such that $L(\lambda p)=\lambda^{0} L(p)=L(p)$, which yields a well-defined function on $\mathbb{C P}^{n}$. So quartics in $\mathbb{P}^{3}$ have trivial canonical bundle, i.e. $K_{S}=\mathcal{O}_{S}$ for $S=V\left(x_{0}^{4}+x_{1}^{4}+x_{2}^{4}+x_{3}^{4}\right)$.

Remark 36.0.6: We know that $H^{0}\left(S, K_{S}\right)$ are the globally holomorphic 2-forms on $S$, and here this is isomorphic to $H^{0}\left(S, \mathcal{O}_{S}\right)=\mathbb{C} \Omega_{S}$ for some single holomorphic 2-form. Moreover $\operatorname{Div}\left(\Omega_{S}\right)=0$ since $\mathcal{O}\left(\operatorname{Div}\left(\Omega_{S}\right)\right)=K_{S}=\mathcal{O}_{S}$. So these are the analogs of elliptic curves in dimension 2 , since for example $E:=\mathbb{C} / \Lambda$ has a nonvanishing section $d z \in H^{0}\left(E, K_{E}\right)$, and we can write $E=V(f)$ for $f$ a cubic in $\mathbb{P}^{3}$, and we computed the genus of cubics. Moreover, every genus 1 curve is $\mathbb{C}$ mod a lattice.

Remark 36.0.7: Recall an exercise from the notes: computing the Hodge diamond of a genus 5 curve. We'll compute the diamond for a K3 surface:

|  | $h^{2,2}$ |  |
| :--- | :--- | :--- |
| $h^{2,0}$ | $h^{1,3}$ |  |
|  | $h^{1,1}$ |  |
| $h^{1,0}$ | $h^{0,2}$ |  |
|  | $h^{0,0}$ |  |

## Link to Diagram

We know $h^{2,0}=H^{0}\left(S, \Omega_{S}^{2}\right)$, which yields 1s:

$$
\begin{array}{ccc}
h^{3,1} & & h^{1,3} \\
1 & h^{1,1} & \\
h^{1,0} & & h^{0,1}
\end{array}
$$

1

## Link to Diagram

We'll use the following theorem:

Theorem 36.0.8(Lefschetz Hyperplane Theorem).
Let $X \subset \mathbb{P}^{n}$ with $\operatorname{dim} X>3$. Then $\pi_{1}(X) \cong \pi_{1}(X \cap H)$ for $H$ a hypersurface intersection $X$ at a smooth codimension 1 complex manifold.

Remark 36.0.9: Applying this to $X=\mathbb{P}^{3}$, we have $V\left(x_{0}^{4}+\cdots+x_{3}^{4}\right)=S$, we have $\pi_{1}\left(\mathbb{P}^{3}\right)=\pi_{1}(S)$. We can write $\mathbb{P}^{3}=\mathbb{C} \cup \mathbb{C}^{2} \cup \mathbb{C}^{4}$, which is a cell decomposition with cells only in degrees $0,2,4$, and so in fact $\pi_{1}\left(\mathbb{P}^{n}\right)=0$.

## Corollary 36.0.10(h1 of K3 surfaces).

K3 surfaces are simply connected, and $h^{1}(S ; \mathbb{C})=0$.
Note that anything embedded in projective space as a complex submanifold is Kähler by restricting the Fubini-Study form. Using simple connectedness and Serre duality, we have

0

0

0

$$
h^{1,1}
$$

0

1

## Link to Diagram

We know $\chi\left(\mathcal{O}_{S}\right)=(1 / 12)\left(K^{2}+\chi_{\text {Top }}\right)$, and since $K_{S}=\mathcal{O}_{S}$ is trivial, we have $c_{1}\left(\mathcal{O}_{S}\right)=0$. Noting that $h^{p, q}=H\left(\Omega^{p}\right)$, so we can sum the lower-right part of the diamond to get $\chi\left(\mathcal{O}_{S}\right)=1-0+1=2$, since we take $p=0$ to get $\Omega^{p}=\mathcal{O}$. Computing $\chi_{\text {Top }}$, we get $h_{1,1}=20$.

## 37 Monday, April 12

Remark 37.0.1: Last time: the Lefschetz hyperplane theorem. Intersecting a projective variety of dimension $d \geq 3$ with a hypersurface $S$, the map $\pi_{1}\left(\mathbb{P}^{3}\right) \rightarrow \pi_{1}(S)$ is an isomorphism. We saw that K3 surfaces were thus simply connected, and $h^{1}(S ; \mathbb{C})=0$, so we could compute the Hodge diamond.

Example 37.0.2(?): What is the Hodge diamond for a cubic surface $S \subseteq \mathbb{P}^{3}$, such as $\sum x_{i}^{3}=0$ ? We first need to compute the canonical bundle $K$, for which we have a useful tool: the adjunction formula. This say $K_{S}=\left.\left(K_{\mathbb{P}^{3}} \otimes \mathbb{P}_{\mathbb{P}^{3}}(S)\right)\right|_{S}=\left.(\mathcal{O}(-4) \otimes \mathcal{O}(3))\right|_{S}=\left.\mathcal{O}(-1)\right|_{S}$.

Proposition 37.0.3(If a holomorphic line bundle has a section, its inverse doesn't).
Let $\mathcal{L} \rightarrow X$ be a holomorphic line bundle. If $h^{0}\left(\mathcal{L}^{-1}\right)>0$, then either $\mathcal{L}=\mathcal{O}$ or $h^{0}(\mathcal{L})=0$.

## Slogan 37.0.4

If a line bundle has a section, its inverse does not.

## Proof (?).

Suppose that both $\mathcal{L}, \mathcal{L}^{-1}$ have a section, so $h^{0}(\mathcal{L}), h^{0}(\mathcal{L})>0$. Let $s, t$ be sections of each, then $s t \in H^{0}\left(\mathcal{L} \otimes \mathcal{L}^{-1}\right)=H^{0}(\mathcal{O})=\mathbb{C}$. So taking zero loci yields $\operatorname{Div}(s)+\operatorname{Div}(t)=0$ Writing these as $\operatorname{Div}(s):=\sum n_{D} D, \operatorname{Div}(t):=\sum n_{C} C$, we have $n_{D}, n_{C} \geq 0$, which implies that $\operatorname{Div}(s)=\operatorname{Div}(t)=0$. So $s, t$ are nowhere vanishing, making $\mathcal{O} \xrightarrow{s s} \mathcal{L}$ is an isomorphism.

Corollary 37.0.5(HO of cubic surfaces).
For $S$ a cubic surface, $H^{0}\left(S ; K_{S}\right)=0$.
Proof (?).
This follows because $K_{S}=\mathcal{O}_{S}(-1)$, so $K_{S}^{-1}=\mathcal{O}_{S}(1)$ which has a nontrivial section: namely $\mathcal{O}_{\mathbb{C P}^{1}}(1)$ which has sections vanishing along hyperplanes.
$H_{2}$
$H_{1} \quad \mathbb{P}^{3}$


Letting $H$ be a hyperplane containing $S$, there exists an $f \in H^{0}\left(\mathbb{P}^{3} ; \mathcal{O}_{\mathbb{C P}^{3}}(1)\right)$. Since $\operatorname{Div}(f)=$ $H$, the restriction $\left.f\right|_{S}$ is a section of $\mathcal{O}_{S}(-1)=K_{S}^{-1}$ which is not identically zero and vanishes along $H \cap S$.

We now know $h^{0}\left(S ; K_{S}\right)=0$, and this equals $h^{0}\left(S, \Omega^{2}\right)=h^{2,0}(S)$, so we have the following Hodge diamond:
1

0

0

|  | 1 |  |
| :---: | :---: | :---: |
| 0 |  | 0 |
|  | $h^{1,1}$ |  |
|  |  | 0 |
| 0 |  | 0 |

1

## Link to Diagram

We have $h^{0,1}+h^{1,0}=h^{1}=0$ since $S$ is simply connected. We can now apply Noether's formula as before: $\chi\left(\mathcal{O}_{S}\right)=\frac{1}{12}\left(K_{S}^{2}+\chi_{\operatorname{Top}}(S)\right)$. We have $K_{S}=\mathcal{O}_{S}(-1)$, so $K_{S}^{2}=c_{1}(\mathcal{O}(-1))^{2}$, and $\chi\left(\mathcal{O}_{S}\right)=1-0+1=1$. We now want to compute $\int_{S}\left(-c_{1}\left(\mathcal{O}_{S}(1)\right)\right)^{2}$. We know $c_{1}(\mathcal{L})=[\operatorname{Div} s]$ where $s \in H^{0}(\mathcal{L})$ is a section of a line bundle. This equals $[H \cap S]$. On the other hand, $\int_{S} c_{1}\left(\mathcal{O}_{S}(1)\right)^{2}$ is the self-intersection number of $H \cap S$.

Take $H_{1}:=\left\{x_{0}=0\right\}$ and $H_{2}:=\left\{x_{1}=0\right\}$. Points in this intersection are of the form $\left[0: 0: 1: \zeta_{6}^{a}\right]$ where $a=1,3,5$ since this is in the triple intersection $H_{1} \cap H_{2} \cap S$. So there are exactly 3 points here, and in fact $\operatorname{deg} S=3$. This is the same as integrating $\int_{\mathbb{P}^{3}} c_{1}(S) c_{1}(\mathcal{O}(1)) c_{1}(\mathcal{O}(2))$, which contains 3 elements in $H^{2}$ and lands in $H^{6}$, so this yields a number.

We thus have $K_{S}=\mathcal{O}_{S}(-1):=\left.\mathcal{O}_{\mathbb{C P}^{3}}(-1)\right|_{S}$. Thus $\chi_{\text {Top }}(S)=9$ and $h^{1,1}=7$.
Example 37.0.6(Hypersurfaces): Note that a degree 5 surface (a quintic) such as $x_{0}^{5}+x_{3}^{5}=0$ would be harder, since $h^{2,0} \neq 0$. We would get $K_{S}=\left.\mathcal{O}(-4) \otimes \mathcal{O}(5)\right|_{S}=\mathcal{O}_{S}(1)$, and there are nontrivial sections so $h^{0}\left(K_{S}\right)=\operatorname{span} x_{0}, x_{1}, x_{2}, x_{3}$. This follows because there is a map given by restriction which turns out to be an isomorphism

$$
\begin{aligned}
& 0 \rightarrow H^{0}\left(\mathbb{P}^{3} ; \mathcal{O}(1)\right) \xrightarrow{\mathrm{res}_{S}} H^{0}(S ; \mathcal{O}(1)) \rightarrow 0 \\
& f\left.\mapsto f\right|_{S} .
\end{aligned}
$$

Injectivity isn't difficult, surjectivity is harder. We have a SES

$$
0 \rightarrow \mathcal{O}_{\mathbb{C P}^{3}}(-S) \rightarrow \mathcal{O}_{\mathbb{C P}^{3}} \rightarrow \mathcal{O}_{S} \rightarrow 0
$$

Tensor all of these with $\mathcal{O}(1)$ to obtain

$$
0 \rightarrow \mathcal{O}_{\mathbb{C P}}^{3}(-4) \rightarrow \mathcal{O}_{\mathbb{C P}^{3}}(1) \rightarrow \mathcal{O}_{S}(1) \rightarrow 0
$$

Taking the associated LES yields


## Link to Diagram

This gives us a way to relate things back to the cohomology of $\mathbb{C P}^{3}$. Showing that the indicated term is zero involves computing Čech cohomology.

It turns out that $h^{0}\left(K_{S}\right)=4$ here, and it turns out that the Hodge diamond is the following:

1
0
4

$$
h^{1,1}=45
$$

Here $K_{S}^{2}=c_{1}\left(\mathcal{O}_{S}(1)\right)^{2}=5$ and $\chi_{\text {Top }}=55$.

Example 37.0.7(Products): Consider now a product of curves $C \times D$ of genera $g, h$ respectively.
Computing the Hodge diamond is easy here due to the Kunneth formula:

$$
H^{k}(S ; \mathbb{C})=\bigoplus_{i+j=k} H^{i}(C ; \mathbb{C}) \otimes H^{j}(D ; \mathbb{C})
$$

What is the actual map? Take cohomology classes $[\alpha],[\beta]$, closed $i$ and $j$ forms respectively. The surface has two maps:


Here we send $[\alpha] \otimes[\beta] \mapsto\left[\pi_{C}^{*} \alpha \wedge \pi_{D}^{*} \beta\right]$ where we take pullbacks. Note that $\pi_{D}, \pi_{C}$ are holomorphic maps, and pullbacks of $(p, q)$ forms are still $(p, q)$ forms. Thus the Kunneth formula gives a decomposition

$$
H^{p, q}(S ; \mathbb{C})=\sum_{\substack{i_{1}+j_{1}=p \\ i_{2}+j_{2}=q}} H^{i_{1}, j_{1}}(C) \oplus H^{i_{2}, j_{2}}(D)
$$

So we can "tensor" the Hodge diamonds:


1

Remark 37.0.8: Check out complete intersections.

## 38 Blowups and Blowdowns (Wednesday, April 14)

Definition 38.0.1 (Blowup)
Let $S \in \mathrm{Mfd}_{\mathbb{C}}^{2}$ be a complex surface and $p \in S$ a point, and let $(x, y)$ be local holomorphic coordinates on a neighborhood of $U$ containing $p$. Without loss of generality, $p=(0,0)$ in these coordinates. Set $U^{*}:=U \backslash\{p\}$, and consider the holomorphic map

$$
\begin{aligned}
\varphi: U^{*} & \rightarrow U \times \mathbb{C P}^{2} \\
(x, y) & \mapsto((x, y),[x: y])
\end{aligned}
$$

We'll define the blowup at $p$ to be $\underset{p}{\mathrm{Bl}}(U) \operatorname{cl}\left(\varphi\left(U^{*}\right)\right)$ to be the closure of the image of $U^{*}$.

## Observation 38.0.2

There is a map $\underset{p}{\mathrm{Bl}}(U) \rightarrow U$ given by projection onto the first coordinate which is the identity on $U^{*}$.

$$
q=(x, y)
$$

$$
U
$$



Here $q$ maps to the pair $(q, s)$ where $s$ is the slope of a line through $q$, and this will be continuous.

## Missed part

We claim that $\pi_{U}^{-1}(0,0) \subset \underset{p}{\operatorname{Bl}}(U)=\{p\} \times \mathbb{C P}^{1}$, and for a fixed $\left.9 x_{0}, y_{0}\right) \in U^{*}$, considering $\varphi\left(x_{0} t, y_{0} t\right)$
as $t \rightarrow 0$, we can write

$$
\begin{aligned}
& \left(\left(x_{0} t, y_{0} t\right),\left[x_{0}: y_{0}\right]\right) \in U \times \mathbb{C P}^{1} \\
& \quad\left({ }^{t \rightarrow 0}(0,0)\left[x_{0}: y_{0}\right]\right) \subset \operatorname{cl}\left(\varphi\left(U^{*}\right)\right) .
\end{aligned}
$$

So approaching $(0,0)$ along any slope $s$ just yields the point $(0, s)$ in the blowup.

Remark 38.0.3: We can thus write

$$
\underset{p}{\mathrm{Bl}} S S \backslash\{p\} \amalg_{U^{*}} \mathrm{Bl}_{p} U .
$$

Writing $\pi: \mathrm{Bl}_{p} S \rightarrow S$, we have $\pi^{-1}(p) \cong \mathbb{C P}^{1}$ and $\pi^{-1}(q)$ is a point for all $q \neq p$. Then all limits approaching $p$ in $S$ turn into distinct limit points in $\underset{p}{\operatorname{Bl}}(S)$

## S



## Slogan 38.0.4

The blowup separates all tangent directions at $p$.

Example 38.0.5(?): Consider

$$
\left\{y^{2}=x^{3}-x^{2}\right\} \subseteq \mathbb{C}^{2}
$$

This yields a nodal curve with a double-point:


Here we'll consider $\mathrm{Bl} \mathbb{C}^{2}$.
$(0,0)$

## Definition 38.0.6(Strict Transform)

Letting $C \subset S$ be a curve, define the strict transform

$$
\widehat{C}:=\operatorname{cl}\left(\pi^{-1}(C \backslash\{p\})\right)
$$

Note that approaching by different sequences yields different limiting slopes


The curve in the blowup is called the exceptional divisor.

Example 38.0.7(?): Consider all lines in $\mathbb{C P}^{2}$ through $[0: 0: 1]$, which we can model in the following way:


Figure 5: image_2021-04-14-14-18-15

These are in bijection with $\mathbb{C P}^{1}$ since there is always a unique line through $[0: 0: 1]$ and $[s: t: 0]$, where the latter is a copy of $\mathbb{C P}^{1}$ as $s, t$ are allowed to vary. So consider $\underset{p}{\mathrm{Bl}} \mathbb{C P}^{2}$ for $p=[0: 0: 1]$, and consider the strict transforms of the lines $L$ to obtain $\widehat{L} \subset \underset{p}{\mathrm{Bl}} \mathbb{C P}^{2}$. Any two are disjoint since they pass through different slopes of the exceptional divisor. Thus the red lines in the blowup go through distinct slopes, yielding a fibration of $\mathbb{C P}^{1}$ s:


Figure 6: image_2021-04-14-14-24-31

So consider the map

$$
\begin{aligned}
\sigma: & \mathrm{Bl}_{p} \mathbb{C P}^{2} \\
& \rightarrow \mathbb{C P}^{2} \\
& p \in \widehat{L} \mapsto[0: s: t] .
\end{aligned}
$$

which projects points to the boundary copy of $\mathbb{C P}^{1}$ :


We can't necessarily project from the blue point itself, but if we add in the data of a tangent vector at that point, the map becomes well-defined. Thus the blowup makes projecting from a point in $\mathbb{C P}^{2}$ to a line in $\mathbb{C P}^{2}$ a well-defined map on $\mathrm{Bl} \mathbb{C P}^{2}$.

Remark 38.0.8: This is referred to as $\mathbb{F}_{1}$, the first Hirzebruch surface.
Proposition 38.0.9(Blowup for smooth manifolds is connect-sum with CP2).
For $S \in \operatorname{Mfd}_{\mathbb{R}}\left(C^{\infty}\right)$ a smooth manifold, we can identify

$$
\underset{p}{\operatorname{Bl}} S=S \# \overline{\mathbb{C P}^{2}}
$$

## Proof (?).

It suffices to work in coordinate charts and prove this for $p=0$.

## Claim:

$$
\underset{0}{\mathrm{Bl}} \mathbb{C}^{2}=\operatorname{Tot}\left(\mathcal{O}_{\mathbb{C P}^{1}}(-1)\right)
$$

Recall that this was the tautological line bundle that whose fibers at a point $p \in \mathbb{C P}^{1}$ was the line in $\mathbb{C}^{2}$ spanned by $p$. We can write this as $\left\{[x: y] \mid(x, y) \in L_{[x: y]}\right\}$ :


Figure 7: image_2021-04-14-14-32-58
We have $\mathcal{O}(-1) \xrightarrow{\sim} \overline{\mathcal{O}(1)}$, where this map is a diffeomorphism that can be constructed using a Hermitian metric. However we can identify $\mathcal{O}(1)$ with the set of lines in $\mathbb{C P}^{2}$ through [0:0:1], leaving out the point $[0: 0: 1]$ itself. This follows by checking that there exists a section that vanishes at only one point. In fact $\operatorname{Tot} \mathcal{O}(1)$ is diffeomorphic to the complement of a ball in $\mathbb{C P}^{2}$, which ends up precisely being taking a connect-sum. So we obtain $\underset{0}{\operatorname{Bl}} \mathbb{C}^{2} \cong \mathbb{C}^{2} \# \overline{\mathbb{C P}^{2}}$.

## Proof (Alternative).

Cut out a ball $B^{4} \subseteq \mathbb{C}^{2}$, so $\partial B^{4}=S^{3}=\left\{|x|^{2}+|y|^{2}=\varepsilon\right\}$. Then $\underset{0}{\mathrm{Bl}} \mathbb{C}^{2}$ is the result of collapsing $S^{3}$ along an $S^{1}$-foliation $\left(e^{i \theta} x, e^{i \theta} y\right)$. This has an $S^{2}$ quotient, yielding the Hopf fibration

$$
S^{1} \hookrightarrow S^{3} \rightarrow S^{2}
$$

Exercise 38.0.10 (?)
Show that the blowup over $\mathbb{R}$ is gluing in a mobius strip.
See the Tate curve!

## 39 Friday, April 16

Remark 39.0.1: Last time: we defined the blowup $\underset{0}{\mathrm{Bl}} \mathbb{C}^{2}$ as the closure of

$$
\underset{0}{\mathrm{Bl}} \mathbb{C}^{2}:=\operatorname{cl}\{(x, y),[x: y] \mid(x, y) \neq 0\} \subseteq \mathbb{C}^{2} \times \mathbb{C P}^{2}
$$

This had the effect of adding in all limits of slopes as points approach $(0,0) \in \mathbb{C}^{2}$. We defined this using local holomorphic coordinate charts to $\mathbb{C}^{2}$. Why is this a complex manifold? We can cover it with charts: given a point $(x, \mu)$ where $\mu=\frac{y}{x} \in \mathbb{P}^{1}$ is a slope, we can form a first chart by sending

$$
(x, \mu) \mapsto\{(x, x \mu),[1: \mu]\} .
$$

This yields the first chart, as long as the slope is not infinite, so this applies to all finite slopes. The second chart will work for all nonzero slopes, where we take

$$
(v, y) \in \mathbb{C}^{2} \mapsto\{(y v, y),[v: 1]\}
$$

Note that restricting to $(x, y)=(0,0)$, these give the standard $\mathbb{C}$-charts on $\mathbb{C P}^{2}$. How do these two charts glue? When $\mu, \nu \neq 0$, we have well-defined transition functions $\mu=\nu^{-1}$ and $x=y \nu$.

Remark 39.0.2: Recall that for a complex curve $C \in \operatorname{Mfd}_{\mathbb{C}}^{2}$, we have the blowup morphism $\pi: \underset{p}{\mathrm{Bl}} S \rightarrow S$ and we defined the strict transform $\widehat{C}:=\operatorname{cl} \pi^{-1}(C \backslash\{\mathrm{pt}\})$.


Here $E=\mathbb{C P}^{1}$ is the exceptional curve of the blowup, and intersects the curve twice. This has the effect of changing $D$ into an embedded curve.

Note that here $\pi^{*} D=\widehat{D}+2 E$, where we'll define this next.

Definition 39.0.3 (Pullback of a Curve)
The pullback of $C$, denoted $\pi^{*} C$, is constructed by writing $C=V(f)$ locally. We then set $\pi^{*} C:=V\left(\pi^{*} f\right)$.

Example 39.0.4(?): Take $C:=\{y=x\} \subset \mathbb{C}^{2}$ and consider $\underset{0}{\mathrm{Bl}} \mathbb{C}^{2}$. Then

$$
\widehat{C}:=\operatorname{cl}\{((x, x),[x: x]) \mid x \neq 0\}=\operatorname{cl}\{((x, x),[1: 1]) \mid x \neq 0\} \subset \underset{0}{\operatorname{Bl}} \mathbb{C}^{2} .
$$

By projecting onto the first component, $\pi: \widehat{C} \xrightarrow{\sim} C$ is an isomorphism. We can compute the pullback: we first have $\pi^{*} C=\pi^{*} V(y-x)=V\left(\pi^{*}(y-x)\right)$, so consider $\pi^{*}(y-x)$ in the coordinate chart $(x, \mu)$. In this chart, $y=x \mu$, and so $\pi^{*}(y-x)=x \mu-x=x(\mu-1)$, and so

$$
V\left(\pi^{*}(y-x)\right)=V(x)+V(\mu-1) \Longrightarrow \pi^{*} C=E+\widehat{C} \text { as a divisor. }
$$

Example 39.0.5 (A nodal curve): Take the nodal curve $C=\left\{y^{2}-x^{3}+x^{2}\right\}$ :


The pullback is then given by

$$
\begin{aligned}
\pi^{*} C & =V\left(\pi^{*}\left(y^{2}-x^{3}+x^{2}\right)\right) \\
& =V\left(\mu^{2} x^{2}-x^{3}+x^{2}\right) \\
& =V\left(x^{2}\right)+V\left(\mu^{2}-x+1\right) \\
& =2 V(x)+V\left(\mu^{2}-x+1\right)
\end{aligned}
$$



In the second coordinate chart, we have

$$
\pi^{*} C=V\left(y^{2}-y^{4} \nu^{3}+y^{2} \nu^{2}\right)=2 V(y)+V\left(1-y \nu^{3}+\nu^{2}\right.
$$



Gluing along $\mu, \nu \neq 0$ we get the following picture for $\pi^{*} C$ :


Writing $C=\{x=0\}$, note that $\widehat{C}$ doesn't intersect the first coordinate chart. In the $\mu, x$ coordinate chart, for example, we can't get an infinite slop:


### 39.1 Change in Canonical Bundle Formula

Question 39.1.1
Given $\Omega_{S}^{2}=K_{S} \rightarrow S$ the canonical line bundle, can we relate $K_{\mathrm{Bl}_{p} S}$ to $K_{S}$ ?

Proposition 39.1.2(Canonical of a blowup).

$$
K_{\mathrm{Bl}_{p} S}=\pi^{*} K_{S} \otimes \mathcal{O}_{S}(E) .
$$

Proof (?).
We'll abbreviate $\widehat{S}:={\underset{p}{1}}^{\mathrm{Bl}}(S)$. Let $\omega$ be a local section of $K_{S}$ near $p$, and in coordinate charts $(x, y)$, write $\omega=d x \wedge d y$. In the first coordinate chart on the blowup, we can write

$$
\pi^{*} \omega=d x \wedge d(x \mu)=d x \wedge(\mu d x+x d \mu)=x d x \wedge d \mu
$$

Note that $V(x)=E$, and that pulling back the canonical bundle yields something vanishing to order 1 (?). So $\pi^{*} K_{S}$ is isomorphic to the subsheaf of $K_{\widehat{S}}$ whose sections vanish along $E$, which is isomorphic to $K_{\widehat{S}} \otimes \mathcal{O}(-E)$, since the latter are the functions which vanish along $E$. Tensoring both sides with $\mathcal{O}(E)$ yields

$$
K_{\widehat{S}}=\pi^{*} K_{S} \otimes \mathcal{O}_{\widehat{S}}(E)
$$

as a line bundle, or in divisor notation $K_{\widehat{S}}=\pi^{*} K_{S}+E$ where we take the divisor representing the line bundle instead.

Remark 39.1.3: Using $\pi: \widehat{S} \rightarrow S$, we get pullback maps

$$
\begin{aligned}
\pi^{*}: H^{2}(S ; \mathbb{Z}) & \rightarrow H^{2}(\widehat{S} ; \mathbb{Z}) \\
\pi^{*}: \operatorname{Div}(S) & \rightarrow \operatorname{Div}(\widehat{S}) .
\end{aligned}
$$

These are compatible in the sense that

$$
\left[\pi^{*} C\right]=\pi^{*}[C] .
$$

. This can be seen by expressing $\mathcal{O}_{S}(C) \cong \mathcal{O}_{S}(A-b)$ for $A, B$ hyperplane section. We can assume $A, B$ avoid $p$ in their projective embeddings, making $[C]=[A]-[B]$ since $c_{1}\left(\mathcal{O}_{S}(c)\right)=[C]$ is the fundamental class of $C$. So it suffices to prove the formula for curves not passing through $p$, but this is obvious! It follows from the fact that $\pi: \widehat{S} \backslash E \xrightarrow{\sim} S \backslash\{p\}$ is an isomorphism.

Remark 39.1.4: In fact,

$$
H^{2}(\widehat{S} ; \mathbb{Z}) \cong \pi^{*} H^{2}(S, \mathbb{Z}) \oplus \mathbb{Z}[E]
$$

, which follows from Mayer-Vietoris. So this adds one to the rank.

## 40 Monday, April 19

Remark 40.0.1: Recall that we have the following:

$$
H^{2}(\widehat{S} ; \mathbb{Z})=\pi^{*} H^{2}(S ; \mathbb{Z}) \oplus \mathbb{Z}[E]
$$

where $E$ is the exceptional curve, which follows from Mayer-Vietoris. We can write $\widehat{S}=S \# \overline{\mathbb{C P}^{2}}$, and by excision $H^{2}\left(S \backslash \mathbb{B}^{4}\right)=H^{2}(S)$. So we get a LES


Link to Diagram

We have $H^{i}\left(S, S \backslash \mathbb{B}^{4}\right)=H^{i}\left(T, T \backslash \mathbb{B}^{4}\right)=H^{i}\left(\mathbb{B}^{4}, \partial\right)$, and by Poincaré-Lefschetz duality, this is isomorphic to $H_{4-i}\left(\mathbb{B}^{4}\right)$. This is equal to 0 if $i \neq 0$ or 4 . Writing $\widehat{S}=\left(S \backslash \mathbb{B}^{4}\right) \coprod_{S^{3}}\left(\overline{\mathbb{C P}^{2}} \backslash \mathbb{B}^{4}\right)$ and applying Mayer-Vietoris yields


## Link to Diagram

Combining this with the isomorphisms from earlier, we can write the direct sum as $H^{2}(S) \oplus H^{2}\left(\overline{\mathbb{C P}^{2}}\right)$ where the latter is equal to $\mathbb{Z} \ell=[E]$ for $\ell$ a line class.

## Question 40.0.2

What is the intersection form on $H^{2}(\widehat{S} ; \mathbb{Z})$ ?

Remark 40.0.3: Using the proposition, along with the fact that

1. its an orthogonal decomposition,
2. $\pi^{*}$ is an isometry, and
3. $[E]^{2}=-1$,
we know that the Gram matrix for $H^{2}(\widehat{S})$ is the same as that for $H^{1}(S) \oplus[-1]$, i.e. it is of the form

$$
\left[\begin{array}{cc}
A & 0 \\
0 & -1
\end{array}\right] .
$$

## Proof (of 2).

Consider $\left[\Sigma_{1}\right],\left[\Sigma_{2}\right] \in H^{2}(S ; \mathbb{Z})$ where the $\Sigma_{i}$ are real surfaces, and suppose $\Sigma_{1} \pitchfork \Sigma_{2}$ and $p \notin \Sigma_{1}, \Sigma_{2}$. We then have

$$
\left[\pi^{-1}\left(\Sigma_{i}\right)\right]=\pi^{*}\left[\Sigma_{i}\right]
$$



The intersection number is preserved because $\pi$ is generically injective.

## Proof (of 1).

It also follows that if $p \notin \Sigma, \pi^{*}[\Sigma]=\left[\pi^{-1} \Sigma\right]$ where the latter is disjoint from $E$. So $\pi^{*}[\Sigma] \cdot E=0$.

## Proof (of 3).

Since $[E] \sim[$ line $] \in \overline{\mathbb{C P}^{2}} \backslash \mathbb{B}^{4}$, and $E^{2}=[E] \cdot[E]=-1$ since the orientations disagree in $\overline{\mathbb{C P}^{2}}$.

## Proposition 40.0.4(Computing the pullback of a curve).

Let $C \subset S$ be a curve on a surface and suppose $C$ is locally cut out by

$$
f(x, y)=a_{m, 0} x^{m}+a_{n-1,1} x^{m-1} y+\cdots+a_{0, m} y^{m}+O\left(x^{m+1}, y^{m+1}\right)
$$

near $p \in S$, so the lowest order terms in the Taylor expansion are degree $m$. Then

$$
\pi^{*} C=\widehat{C}+m E
$$

## Proof (?).

On the blowup, take local coordinates $(x, \mu)$ where $y=x \mu$ and write

$$
\begin{aligned}
V\left(\pi^{*} f\right) & =V\left(x^{m}\left(a_{m, 0}+a_{m-1,1} \mu+\cdots+a_{0, m} \mu^{m}+O\left(x^{m+1}, \mu^{m+1}\right)\right)\right) \\
& =m V(x)+V\left(a_{m, 0}+\cdots\right) \\
& =E+\widehat{C} .
\end{aligned}
$$

Example 40.0.5(?): Take

$$
C=\left\{y^{2}=x^{3}-x^{2}\right\} \subseteq \mathbb{C}^{2}
$$

where $\underset{0}{\mathrm{Bl}} \mathbb{C}^{2} \rightarrow C$. Then $\pi^{*} C=\widehat{C}+2 E$, so

$$
C=V\left(x^{2}+y^{2}+O(\operatorname{deg}(3)) .\right.
$$

Corollary 40.0.6(Computing the square of the strict transform). $\widehat{C}^{2}=C^{2}-m^{2}$.

Proof (?).
Write $\pi^{*} C=\widehat{C}+m E$, then $\widehat{C}=\pi^{*} C-m E$ implies that $\widehat{C}^{2}=\left(\pi^{*} C-m E\right)^{2}$. This equals

$$
\begin{aligned}
\left(\pi^{*} C\right)^{2}-2 m \pi^{*} C \cdot E+m^{2} E^{2} & =C^{2}-0-m^{2} \\
& =C^{2}-m^{2},
\end{aligned}
$$

where we've used (2), (1), and (3) respectively to identity these terms.

Example 40.0.7(?): Let

$$
C:=\left\{z y^{2}=x^{3}-x^{2} z\right\} \subset \mathbb{C P}^{2},
$$

then $C^{2}=(3 \ell)^{2}=9$. The multiplicity of $C$ at the point $[0: 0: 1]$ is 2 . Taking the coordinate chart $\{z=1\} \cong \mathbb{C}^{2}$, we recover the curve $y^{2}=x^{3}-x^{2}$ which has multiplicity 2 at $(0,0)$. We can conclude $\widehat{C}=\underset{[0: 0: 1]}{\mathrm{Bl}} \mathbb{C P}^{2}$ has self-intersection number $\widehat{C}^{2}=9-2^{2}=5$.

## Theorem 40.0.8(Castelnuovo Contractibility Criterion).

Let $S$ be a complex surface and let $E \subset S$ be a holomorphically embedded $\mathbb{C P}^{2}$ such that $E^{2}=-1$ Then there exists a smooth surface $\bar{S}$ and $p \in \bar{S}$ such that $S=\underset{p}{\mathrm{Bl}} \bar{S}$ with $E$ as the exceptional curve.

Definition 40.0.9 (Blowdown)
This $\bar{S}$ is called the blowdown of $S$ along $E$.

Remark 40.0.10: Note that this is the exact situation when we blow things up. This is a converse: if we have something that looks like a blowup, we can find something that blows up to it.

## Exercise 40.0.11 (?)

Show that the category $\mathrm{Mfd}_{\mathbb{C}}$ is not closed under blowdowns, i.e. there is no blowdown of a holomorphically embedded $\mathbb{C P}^{1}$, say $E$, with $E^{2}=1$.

$$
\text { Hint: think about } \mathbb{C P}^{2} \text {. }
$$

Remark 40.0.12: This is interesting because there does exist a blowdown in the smooth category $\operatorname{Mfd}\left(C^{\infty}(\mathbb{R})\right)$. This is because $S \rightarrow S \# \mathbb{C P}^{2}$ and $S \rightarrow S \# \mathbb{C P}^{2}$ are indistinguishable here. One can just reverse orientations.

Example 40.0.13(?): A complex surface with a holomorphically embedded $\mathbb{C P}^{1}$ of self intersection -1 . Let $p, q \in \mathbb{C P}^{2}$ be distinct points, and let $\underset{p, q}{\mathrm{Bl}} \mathbb{C P}^{2}:=\underset{p}{\mathrm{Bl}} \underset{q}{\mathrm{Bl}} \mathbb{C P}^{2}$. Note that these two operations commute since these are distinct points and blowing up is a purely local operation. Let $\ell \subset \mathbb{C P}^{2}$ be the unique line through $p$ and $q$. Viewing $p, q$ as lines in $\mathbb{C}^{3}$, they span a unique plane, which is a line in projective space, so this makes sense and we can write $\ell \approx \operatorname{span}\{p, q\}$. Since $\ell$ is defined by a linear equation in local coordinates near $p, q$, we have $\operatorname{mult}_{p} \ell=\operatorname{mult}_{q} \ell=1$. We hve

$$
\begin{array}{r}
\hat{\ell}=\pi^{*} \ell-E_{p}-E_{q} \\
\widehat{\ell}^{2}=\ell^{2}-1^{2}-1^{2}=1-1-1=-1
\end{array}
$$

Under $\pi: \underset{p, q}{\mathrm{Bl}} \mathbb{C P}^{2} \rightarrow \mathbb{C P}^{2}$, we have $\widehat{\ell} \xrightarrow{\sim} \ell$.

$$
\mathrm{Bl}_{p, q} \mathbb{C P}^{2}
$$

$$
E_{q}
$$



Here since all of the lower order terms have degree 1, there is a well-defined tangent line. Since $\ell \cong \mathbb{C P}^{2}$, we have $\widehat{\ell} \cong \mathbb{C P}^{2}$. Letting $\sigma$ be the blowdown of $\widehat{\ell}$, we have


## Link to Diagram

Remark 40.0.14: There's a way to do this with Kirby Calculus.

## 41 Wednesday, April 21

Remark 41.0.1: Why can't one blow down a curve $E \cong \mathbb{C P}^{1}$ with $E^{2}=1$ in a complex surface? Disproof: consider $S:=\mathbb{C P}^{2}$ and $E$ a line, where $E^{2}=1$. If there were a blowdown in the complex analytic category

$$
\begin{aligned}
& S \rightarrow \bar{S} \\
& E \mapsto \mathrm{pt}
\end{aligned}
$$

But $\bar{S} \cong$ Top $S^{4}$, since $S^{4} \# \mathbb{C P}^{2} \cong \mathbb{C P}^{2}$, and this would yield a complex structure on $S^{4}-\mathrm{a}$ contradiction. This also follows because $\bar{S} \in \mathbb{Z} \mathrm{HS}^{4}$, and Noether's formula implies that every $\mathbb{Z} \mathrm{HS}^{4}$ has no complex structure.

Remark 41.0.2: Recall that we were considering the following:


Link to Diagram

Let $\bar{\ell} \subset \underset{p, q}{\mathrm{Bl}}\left(\mathbb{C P}^{2}\right)$ the strict transform of a line through $p, q$ with $\widehat{\ell}^{2}=-1$. Goal: we want to construct the map $\sigma$ sending $\hat{\ell}$ to a single point. Let $r \in \underset{p, q}{\mathrm{Bl}} \mathbb{C P}^{2}$, then there are three possibilities:

1. $r \in \mathbb{C P}^{2} \backslash\{p, q\}$
2. $r \in E_{p}$
3. $r \in E_{q}$

If a point $r \neq p, q$, we can take lines $\ell_{p r} \cdot \ell_{q r}$. We can take slopes of these lines to get points in $\mathbb{C P}^{1}$, and in fact it's the exceptional divisor (since these are sets of slopes through a point).

So we can map

$$
r \mapsto \begin{cases}\left(\text { slope }_{p} \ell_{p r}, \text { slope }_{q} \ell_{q r}\right) \in \mathbb{C P}^{2} \times \mathbb{C P}^{2} & \text { Case } 1 \\ \left(r, \text { slope }_{q} \ell_{q p}\right) & \text { Case } 2 \\ \left(\text { slope }_{p} \ell_{p q}, r\right) & \text { Case } 3 .\end{cases}
$$

This is clearly continuous, is this injective? The outputs will be the same for any point on the line between $p$ and $q$ :


So this realizes the blowdown map, since $\left.\Phi \widehat{\ell}_{p q}\right)=$ pt and restricting it to the complement of the line is injective.

### 41.1 Spin and Spinc Groups

Remark 41.1.1: Goal: show that $3[\ell]$ can't be realized by a sphere, we'll need Rohklin's theorem for this. Let $(V,\langle-,-\rangle)$ be an inner product space, and assume the inner product is positive-definite. Recall that the tensor algebra is defined as $T(V):=\bigoplus_{n \geq 0} V^{\otimes n}$.

Definition 41.1.2 (Clifford Algebra)
Define the Clifford Algebra of $V$ as

$$
\mathrm{Cl}(V):=T(V) /\left\langle v \otimes v+\|v\|^{2} 1\right\rangle .
$$

Example 41.1.3(The reals): Take $\mathbb{R}$ with the standard inner product, so $\langle x, y\rangle:=x y$. Then $T(\mathbb{R})=\bigoplus_{n \geq 0} \mathbb{R}$. Letting $\{e\}$ be a basis of $\mathbb{R}$, we have $T(\mathbb{R})=\mathbb{R} \oplus \mathbb{R} e \oplus \mathbb{R}\left(e^{2}\right) \oplus \cdots \cong \mathbb{R}[x]$ by sending
$e^{n} \mapsto x^{n}$. Since $\|e\|=1$, and we mod out by $e^{2}+\|e\|^{2} 1$ where $e^{2}=-1$ and thus

$$
\mathrm{Cl}\left(\mathbb{R},\langle-,-\rangle_{\mathrm{std}}\right) \cong \mathbb{R}[x] /\left\langle x^{2}=-1\right\rangle \cong \mathbb{C} .
$$

The denominator is referred to as the Clifford relation.
Example 41.1.4(More reals): Take $\mathbb{R}^{2}$ with the standard inner product and an orthonormal basis $\left\{e_{1}, e_{2}\right\}$. Then

$$
T(\mathbb{R})=\mathbb{R} \oplus \mathbb{R}\left\langle e_{1}, e_{2}\right\rangle \oplus \mathbb{R}\left\langle e_{1}^{2}, e_{1} e_{2}, e_{2} e_{1}, e_{2}^{2}\right\rangle \oplus \cdots
$$

Note that there are $2^{k}$ terms in the $k$ th graded piece. It suffices to mod out only by the relations on the orthonormal basis. This is of the form $(v+w)^{2}=-\|v+w\|^{2}=-\|v\|^{2}-2\langle v, w\rangle-\|w\|^{2}$. On the other hand, this equals $v^{2}+v w+w v+w^{2}$. So we obtain

$$
v w+w v=2\langle v, w\rangle,
$$

and setting $v=w$ and dividing by 2 yields the original Clifford relation.
For $\mathbb{R}^{2}$, we can explicitly check

1. $e_{1}^{2}=-1$,
2. $e_{2}^{2}=-1$,
3. $e_{1} e_{2}+e_{2} e_{1}=-2 e_{1} e_{2}=0$,
4. $e_{1} e_{2}=-e_{2} e_{1}$.

Here (1), (2), and (4) generate all of the relations, so

$$
\mathrm{Cl}\left(\mathbb{R}^{2}\right)-\mathbb{R}\left\langle e_{1}, e_{2}\right\rangle /\left\langle e_{1}^{2}=-1, e_{2}^{2}=-1, e_{1} e_{2}=-e_{2} e_{1}\right\rangle \cong H H .
$$

We can form this map by

$$
\begin{aligned}
1 & \mapsto 1 \\
e_{1} & \mapsto i \\
e_{2} & \mapsto j \\
e_{1} e_{2} & \mapsto k,
\end{aligned}
$$

and then checking that the appropriate relations hold. These hold since $i^{2}=j^{2}=-1$ and $i j=-j i=k$. These suffice, but you can check the rest: for example, does $j k=i$ hold? We can write this as

$$
e_{2}\left(e_{1} e_{2}\right)=-e_{2}\left(e_{2} e_{1}\right)=-e_{2}^{2} e_{1}=-(-1) e_{1}=e_{1} .
$$

Exercise 41.1.5 (?)
Check that $\operatorname{dim}_{\mathbb{R}} \mathrm{Cl}(V)=2^{\operatorname{dim} V}<\infty$.

## $42 \mid$ Friday, April 23

Remark 42.0.1: Given $(V, \cdot)$ an inner product space, we defined

$$
\mathrm{Cl}(V):=\frac{\bigoplus_{n \geq 0} V^{\otimes n}}{\langle v \otimes w+w \otimes v=2 v \cdot w\rangle}
$$

Example 42.0.2(?): We saw that

$$
\begin{aligned}
\mathrm{Cl}(\mathbb{R}, \cdot) & \cong \mathbb{R}[e] / e^{2}=-1 \cong \mathbb{C} \\
\mathrm{Cl}\left(\mathbb{R}^{2}, \cdot\right) & =\mathbb{R}\left\langle e_{1}, e_{2}\right\rangle /\left\langle e_{1}^{2}=e_{2}^{2}=-1, e_{1} e_{2}=-e_{2} e_{1}-\right\rangle \cong \mathbb{H}
\end{aligned}
$$

where $e_{1} \mapsto i, e_{2} \mapsto j, e_{3}=e_{1} e_{2} \mapsto k$. Can we describe $\operatorname{Cl}\left(\mathbb{R}^{n}, \cdot\right)$ in general? Choose an orthonormal basis $\left\{e_{i}\right\}$, then

$$
\mathrm{Cl}\left(\mathbb{R}^{n}, \cdot\right)=\frac{\mathbb{R}\left\langle e_{1}, \cdots, e_{n}\right\rangle}{\left\langle e_{i}^{2}=-1, e_{i} e_{j}=-e_{j} e_{i} \mid i \neq j\right\rangle}
$$

We saw that replacing 2 with $\epsilon$ in the defining relation recovers $\bigwedge^{*} V$.
Definition 42.0.3 (Degree Filtration)
Define the degree filtration on $\mathrm{Cl}(V, \cdot)$ as the filtration induced by the degree filtration on $T(V):=\bigoplus_{n \geq 0} V^{\otimes n}$.

Example 42.0.4(?): Consider $\operatorname{Cl}\left(\mathbb{R}^{2}, \cdot\right)$. Then

- Degree 0: $\mathbb{R}$.
- Degree 1: $\mathbb{R} \oplus \mathbb{R} e_{1} \oplus \mathbb{R} e_{2}$
- Degree 2: $\mathbb{R} \oplus \mathbb{R} e_{1} \oplus \mathbb{R} e_{2} \oplus \mathbb{R} e_{1} e_{2}$

Definition 42.0.5 (Grading and Filtration)
Recall that there's a distinction between gradings and filtration:

- Gradings: $R^{i} R^{j} \subset R^{i+j}$ and $R=\bigoplus R^{i}$.
- Filtrations: $F^{1} \subset F^{2} \subset \cdots$ with $F^{i} F^{j} \subseteq F^{i+j}$

An algebra equipped with a grading is a graded algebra, and similarly an algebra equipped with a filtration is a filtered algebra.

Remark 42.0.6: Note that

- $k\left[x_{1}, \cdots, x_{n}\right]$ is graded (by monomials of uniform degree) and filtered (by polynomials of a bounded degree)
- $T(V)$ is graded and filtered, since multiplying a pure $p$ tensor with a pure $q$ tensor yields a pure $p+q$ tensor
- $\mathrm{Cl}(V)$ is a quotient of $T(V)$, but one can't simply define $\mathrm{Cl}(V, \cdot)^{i}=\operatorname{im} T(V)^{i}$ since the relations have mixed degree: for example $e_{1}^{2}=-1 \mathrm{So} \mathrm{Cl}(V)$ isn't graded, but is still filtered: take the filtration $F$ on $T(V)$ defined by $F^{i}:=\bigoplus_{j \leq i} V^{\otimes j}$ and descend it through the quotient map. The relations can only decrease degree, so this is well defined.

Definition 42.0.7 (Filtration on the Clifford Algebra)
Define a filtration $F^{-}$on $\mathrm{Cl}(V)$ by the following:

$$
F^{i} \mathrm{Cl}(V):=\operatorname{span}\left\{e_{j_{1}}, e_{j_{2}}, \cdots, e_{j_{i}}\right\} .
$$

Definition 42.0.8 (The associated graded)
The associated graded ring $\mathrm{gr}_{F^{-}} R$ is the graded ring defined by

$$
\left(\operatorname{gr}_{F^{-}}\right)^{i}:=F^{i} R / F^{i-1} R .
$$

This induces a decomposition

$$
\mathrm{gr}_{F^{-}} \cong \bigoplus_{i \geq 0} F^{i} R / F^{i-1} R=\bigoplus_{i \geq 0}\left(\mathrm{gr}_{F^{-}}\right)^{i}
$$

which has a multiplicative structure

$$
F^{i} / F_{i-1} \cdot F^{j} / F_{j-1} \rightarrow F^{i+j} / F^{i+j-1}
$$

Remark 42.0.9: Note that if $R \in \operatorname{gr}$ Ring, then $\operatorname{gr}(R)=R$, so taking the associated graded recovers the ring itself. What's happening: taking the smallest homogeneous ideal.

## Fact 42.0.10

If one has relations of mixed degree, the associated graded also has the top degree part of each relation.

Remark 42.0.11: In our case, the Clifford relation relates degree $k$ pieces to degree $k-2$ pieces, so we obtain

$$
\operatorname{gr}_{F^{-}} \mathrm{Cl}(V) \cong T(V) /\langle v \otimes w+w \otimes v=0\rangle:=\bigwedge^{*} V .
$$

There is an isomorphism of $k$-vector spaces

$$
\begin{aligned}
\mathrm{Cl}(V) & \xrightarrow{\rightarrow} \operatorname{grCl}(V) \\
x \in F^{i} & \mapsto \bar{x} \in F^{i} / F^{i-1} .
\end{aligned}
$$

This is because $F^{0} \subseteq \cdots \subseteq \cdots$ with $\cup_{i} F^{i}=\mathrm{Cl}(V)$. We can conclude $\operatorname{dim}_{\mathbb{R}} \mathrm{Cl}(V)=\operatorname{dim}_{\mathbb{R}} \bigwedge^{*} V=$
$2^{\operatorname{dim}_{k} V}$ and use this to construct a basis for $\mathrm{Cl}(V)$. The relevant map is

$$
e_{j_{1}}, e_{j_{2}}, \cdots, e_{j_{i}} \mapsto e_{j_{1}} \wedge \cdots \wedge e_{j_{i}}
$$

## Corollary 42.0.12 (of the fact).

The following set forms an $\mathbb{R}$-basis for $\mathrm{Cl}\left(\mathbb{R}^{n}, \cdot\right)$ :

$$
\left\{e_{j_{1}}, e_{j_{2}}, \cdots, e_{j_{i}} \mid j_{1}<j_{2}<\cdots<j_{i}, i \leq n\right\} .
$$

Example 42.0.13(?): Consider

$$
\mathrm{Cl}\left(\mathbb{R}^{3}, \cdot\right) \cong \operatorname{span}_{\mathbb{R}}\left\{1, e_{1}, e_{2}, e_{3}, e_{1} e_{2}, e_{1} e_{3}, e_{1} e_{2} e_{3}\right\}
$$

Then

$$
\begin{aligned}
e_{1} e_{2} \cdot e_{1} e_{3} & =-e_{1} e_{1} e_{3} e_{3} & & e_{2} e_{1}=-e_{1} e_{2} \\
& =e_{2} e_{3} & & e_{1}^{2}=-1 .
\end{aligned}
$$

Exercise 42.0.14 (?)
Show that $\mathrm{Cl}\left(\mathbb{R}^{3}\right) \cong \mathbb{H} \oplus \mathbb{H}$.

Definition 42.0.15 (Even and odd parts of the Clifford algebra)
$\mathrm{Cl}(V)$ has a $\mathbb{Z} / 2$ ("super") grading, so

$$
\mathrm{Cl}(V) \circ \mathrm{Cl}_{0}(V) \oplus \mathrm{Cl}_{1}(V) \quad \mathrm{Cl}_{i}(V) \cdot \mathrm{Cl}_{j}(V) \subset \mathrm{Cl}_{i+j}^{(\bmod 2)}(V)
$$

The even subalgebra is given by

$$
\mathrm{Cl}_{0}(V)=\operatorname{span}_{k}\left\{e_{i 1}, e_{i 2}, \cdots, e_{i 2 k} \mid 2 k \leq n\right\}
$$

where we take an even number of basis elements, which makes sense because the Clifford relation $v w+2 v=-2 v \cdot w$ preserves degree mod 2 . This is still an algebra. The odd sub-vector space (not an algebra) is given by

$$
\mathrm{Cl}_{1}(V)=\operatorname{span}_{k}\left\{e_{i 1}, e_{i 2}, \cdots, e_{i 2 k+1} \mid 2 k+1 \leq n\right\}
$$

## Example 42.0.16(?):

$$
\mathrm{Cl}\left(\mathbb{R}^{3}\right)=\operatorname{span}_{\mathbb{R}}\left\{1, e_{1} e_{2}, e_{1} e_{3}, e_{2} e_{3}\right\}
$$

and we saw $e_{1} e_{2}=e_{1} e_{3}=e_{2} e_{3}$. This product has degree 4 , and when we applied the relation $e_{1}^{2}=1$ we dropped the degree by 2 . For the odd part, $e_{3} \in C l_{1}\left(\mathbb{R}^{3}\right)$ and $e_{1} e_{2} \in \mathrm{Cl}_{0}\left(\mathbb{R}^{3}\right)$, and we have

$$
e_{3} \cdot\left(e_{1} e_{2}\right)=-e_{1} e_{3} e_{2}=e_{1} e_{2} e_{3} \in \mathrm{Cl}_{1}\left(\mathbb{R}^{3}\right)
$$

## Proposition 42.0.17(Decomposing the Clifford algebra of V).

$$
\mathrm{Cl}(V) \cong \mathrm{Cl}_{0}(V \oplus \mathbb{R}) .
$$

## Proof (?).

Let $e \in \mathbb{R}$ be a unit vector. Given $x \in \mathrm{Cl}(V)$, decompose $x=x_{0}+x_{1} \in \mathrm{Cl}_{0}(V) \oplus \mathrm{Cl}_{1}(V)$. Define an isomorphism

$$
\begin{aligned}
\varphi: \mathrm{Cl}(V) & \rightarrow \mathrm{Cl}_{0}(V \oplus \mathbb{R}) \\
x & \mapsto x_{0}+x_{1} e,
\end{aligned}
$$

which is well-defined since $x_{0}$ was odd degree, and both $x_{1}, e$ were odd degree and thus $x_{1} e$ is even. One checks that this preserves multiplication:

$$
x \cdot y=\left(x_{0}+x_{1}\right) \cdot\left(y_{0}+y_{1}\right)=\left(x_{0} y_{0}+x_{1} y_{1}\right)+\left(x_{0} y_{1}+x_{1} y_{0}\right) \in \mathrm{Cl}_{0}(V) \oplus \mathrm{Cl}_{1}(V),
$$

and so

$$
\begin{aligned}
\varphi(x) \cdot \varphi(y) & =\left(x_{0}+x_{1} e\right)\left(y_{0}+y_{1} e\right) \\
& =x_{0} y_{0}+x_{0} y_{1} e+x_{1} e y_{0}+x_{1} e y_{1} e_{1} .
\end{aligned}
$$

The question is if this equals

$$
\varphi(x y):=\left(x_{0} y_{0}+x_{1} y_{1}\right)+\left(x_{0} y_{1}+x_{1} y_{0}\right) e .
$$

But for example, $x_{1} e y_{0}=(-1)^{\left|y_{0}\right|} x_{1} y_{0} e$, and $y_{0}$ is even. Similarly, $x_{1} e y_{1} e=-x_{1} y_{1} e^{2}=x_{1} y_{1}$.

## 43 Wednesday, April 28

Remark 43.0.1: Last time: we defined $\operatorname{Pin}(n) \subseteq \mathrm{Cl}\left(\mathbb{R}^{n}\right)$ which was generated by $S^{1}\left(\mathbb{R}^{n}\right)$. These were units because $v^{2}=-\|v\|^{2}=-1$, so $v^{-1}=-v$, and formed a group contained in $\mathrm{Cl}\left(\mathbb{R}^{n}\right)^{\times}$. There is a decomposition $\mathrm{Cl}(V)=\mathrm{Cl}_{0}(V) \oplus \mathrm{Cl}_{1}(V)$ with a $\mathbb{Z} / 2$-grading, and we defined

$$
\operatorname{Spin}(V):=\operatorname{Pin}(V) \cap \mathrm{Cl}_{0}(V)=\left\langle v w \mid v, w \in S^{1}\left(\mathbb{R}^{n}\right)\right\rangle
$$

There is a map

$$
\begin{aligned}
\operatorname{Pin}(n) & \rightarrow O(n) \\
v & \mapsto\left(u \mapsto v u v^{-1}\right)=-R_{v^{\perp}},
\end{aligned}
$$

which preserves $V^{\otimes 1} \subset \mathrm{Cl}(V)$, and was reflection about the hyperplane $v^{\perp}$. There is also a SES

$$
0 \rightarrow \mathbb{Z} / 2 \rightarrow \operatorname{Spin}(n) \xrightarrow{\pi} \mathrm{SO}(n) \rightarrow 0
$$

where we used the fact that $\operatorname{ker} \pi \subset Z \mathrm{Cl}\left(\mathbb{R}^{n}\right)$. It turns out that $\operatorname{Spin}(n)=\overline{\mathrm{SO}(n)}$, using that $\pi_{1}(\mathrm{SO}(n), \mathrm{pt})=\mathbb{Z} / 2$ and checking that $\pm 1 \in \operatorname{Spin}(n)$, yielding a nontrivial kernel.

Remark 43.0.2: This is local, at a single vector space, so we'll now try to globalise this to the tangent space of a manifold.

Definition 43.0.3 (Clifford Bundle)
Let $(V, g)$ be an oriented smooth Riemannian manifold where $g$ is a metric on $T X$. Define the Clifford bundle of $X$ by

$$
\mathrm{Cl}(X):=\mathrm{Cl}\left(T^{\vee} X, g^{\vee}\right)
$$

where we've used the dual metric $g^{\vee}$ on the cotangent bundle.

Remark 43.0.4: We showed that $\operatorname{gr} \operatorname{Cl}\left(\mathbb{R}^{n}\right)=\bigwedge \mathbb{R}^{n}$, and so there is a bundle isomorphism

$$
\mathrm{Cl}(X) \xrightarrow{\sim} \bigwedge^{*} T^{\vee} X
$$

but the ring structure is different. On the right, we have a way of multiplying sections, namely $\omega_{1} \wedge \omega_{2}$, but on the left we have the Clifford multiplication $\alpha_{1} \cdot \alpha_{2}$. Note that $\omega^{\wedge 2}=0$, but $\alpha^{2} \in \mathbb{R}$ is some scalar. We define $\omega \cdot \omega=g^{*}(\omega, \omega)$, so we use the metric fiberwise to define a Clifford multiplication.

Definition 43.0.5 (The principal oriented frame bundle)
Given an oriented bundle with a metric, there is a principal $\mathrm{SO}(n)$ bundle $P:=$ OFrame, the space of orthogonal oriented frames.

Remark 43.0.6: This is principal since any two elements are related by a unique element of $\mathrm{SO}(n)$. Recall that we had an associated bundle construction, so taking the standard representation $\rho: \mathrm{SO}(n) \rightarrow\left(\mathbb{R}^{n}, g\right)$ where elements act by their transformations (?), there is an oriented bundle $P \times \mathbb{R}^{n}$. If the bundle is $T X$ with a metric $g$, this yields a distinguished $\mathrm{SO}(n)$ bundle $P \rightarrow X$.
$\rho$
Definition 43.0.7 (Spin Structures)
A spin structure is a lift $\tilde{P}$ of $P$ to a principal $\operatorname{Spin}(n)$ bundle.

## Proposition 43.0.8(Spin iff nontrivial $w_{2}$ ).

$X$ admits a spin structure iff the second Stiefel-Whitney class $w_{2}(X)=0$ in $H^{2}(X ; \mathbb{Z} / 2)$. If $w_{2}(X)=0$, then the spin structures are torsors over $H^{1}(X ; \mathbb{Z} / 2)$.

Remark 43.0.9: Recall that a $G$-torsor is a set with a free transitive $G$-action. For example, the fibers of a principal bundle are torsors. Given any two torsors, we can compare them using elements of $G$, but there is no distinguished element. For example, $\mathbb{A}_{n}$ is a torsor over the vector space $k^{n}$.

Proof (?).

Consider transitions for $P \rightarrow X$ :

$$
t_{i j}: U_{i} \cap U_{j} \rightarrow \mathrm{SO}(n)
$$

where $t_{i j}=t_{j i}^{-1}$ and the cocycle condition $t_{i j} t_{j k} t_{k i}=1$ is satisfied. We want a lift:


Link to Diagram
We can always lift to some $\tilde{t}_{i j}$ using the path-lifting property of covers if $U_{i} \cap U_{j}$ is contractible, using that $\mathbb{Z} / 2$ is discrete. We can arrange $\tilde{t}_{i j}=\tilde{t}_{j i}^{-1}$ since $U_{i} \cap U_{j}=U_{j} \cap U_{i}$, but we may not have the cocycle condition on the lift. We have $t_{i j} t_{j k} t_{k i}=1$, so

$$
\tilde{t}_{i j} \tilde{t}_{j k} \tilde{t}_{k i} \in \operatorname{ker}(\operatorname{Spin}(n) \rightarrow \mathrm{SO}(n))=\{ \pm 1\},
$$

using that everything in sight needs to be a group morphism. So define

$$
\tilde{t}_{i j k}:=\left(\tilde{t}_{i j} \tilde{t}_{j k} \tilde{t}_{k i}\right)_{i, j, k} \in \check{C}_{\mathcal{U}}^{2}(X, \underline{\mathbb{Z} / 2}) .
$$

The claim is that $\partial^{2}\left(\tilde{t}_{i j k}\right)=0$, but it turns out that regardless of choice of lift we obtain

$$
\partial^{2}\left(\tilde{t}_{i j k}\right)=\tilde{t}_{i j k} \tilde{t}_{i k l}^{-1} \tilde{t}_{i j l} \tilde{t}_{i j k}^{-1}=0 \Longrightarrow\left[\tilde{t}_{i j k}\right] \in \check{H}^{2}(X, \underline{\mathbb{Z} / 2}) .
$$

Is this class well-defined? Consider replacing $\tilde{t}_{i j}$ with $-\tilde{t}_{i j}$. In general, we have

$$
i, j \in\{a, b, c\} \Longrightarrow \tilde{t}_{a b c} \mapsto-\tilde{t}_{a b c},
$$

and so this is a Čech coboundary in $\partial^{1}(1, \cdots, 1,-1,1, \cdots, 1)$ where the -1 occurs in the $t_{i j}$ coordinate. Thus $\tilde{t}_{i j k}$ is well-defined moduli $\partial^{1} C_{\mathcal{U}}^{1}(X, \underline{\mathbb{Z} / 2})$.

Note that $w_{2}(X)$ was produced from the pair $(X, g)$, but the space of metrics is connected and thus $w_{2}(X)$ depends only on $X$. Suppose $w_{2}(X)=0$, then $\left[\tilde{t}_{i j k}\right]=0$ which implies that there is some $\left(s_{i j}\right)$ with $\partial^{1}\left(s_{i j}\right)=\left(\tilde{t}_{i j k}\right)$. So replace each $\tilde{t}_{i j}$ with $\tilde{\tilde{t}}_{i j}:=s_{i j} \tilde{t}_{i j}$ is a new lift which satisfies the cocycle condition. Thus they define the transition functions of a principal $\operatorname{Spin}(n)$ bundle lifting $P \rightarrow X$.

To see the claim about torsors, given any $\ell_{i j} \in \operatorname{ker} \partial^{1}$, note that any $\tilde{t}_{i j} \ell_{i j}$ also satisfies the cocycle condition. There is a map

$$
\begin{aligned}
\{\text { Spin structures }\} & \leftarrow \operatorname{ker} \partial^{1} \\
\tilde{\tilde{t}}_{i j} \ell_{i j} & \leftarrow \ell_{i j},
\end{aligned}
$$

which is a torsor because we needed to start with a given lift $\tilde{t}_{i j}$. Then $\tilde{P}_{1} \cong \tilde{P}_{2}$ iff there exists an $\left(m_{i}\right) \in \check{C}_{\mathcal{U}}^{0}(X, \underline{Z} / 2)$ such that $\left(\ell_{i j}\right)_{1}=\left(\ell_{i j}\right)_{2}+\partial^{0}\left(m_{i}\right)$, which are different trivializations of the same bundle.

Remark 43.0.10: This is a nice example to get a hang of the use and importance of Čech cohomology. We then use the isomorphism $\check{H} \rightarrow H_{\text {Sing }}$.

Theorem 43.0.11(Existence of spin representation of Clifford algebras in even dimension).
Assume $n:=\operatorname{dim} V$ is even, then $\mathrm{Cl}(V)$ has a unique nontrivial irreducible finite dimensional complex representation $S$ of dimension $\operatorname{dim} S=2^{n / 2}$, the spin representation.

Remark 43.0.12: It turns out that $\mathrm{Cl}(V) \otimes_{\mathbb{R}} \mathbb{C} \cong \operatorname{End}(S)$. The left-hand side contains $\operatorname{Spin}(n)$, so given $\rho: \mathrm{Cl}(V) \rightarrow \operatorname{End}(S)$ a representation (i.e. a ring homomorphism) in matrices, we can restrict $\rho$ to $\operatorname{Spin}(n)$ to get $\left.\rho\right|_{\operatorname{Spin}(n)}: \operatorname{Spin}(n) \rightarrow \mathrm{GL}(S)$. Next time: spin representations. Spinor bundle will be sections of associated bundle of the Clifford bundle.

## 44 Friday, April 30

Remark 44.0.1: Last time: we defined

$$
\begin{aligned}
& \mathrm{Cl}(V, \cdot):=\bigoplus_{n} V^{\otimes n} /\left\langle v \otimes v=-\|v\|^{2} 1\right\rangle \\
& \operatorname{Pin}(V):=\langle v \mid\|v\|=1\rangle \subseteq \mathrm{Cl}(V)
\end{aligned}
$$

There is a $\mathbb{Z} / 2$ grading $\mathrm{Cl}(V)=\mathrm{Cl}_{0}(V) \oplus \mathrm{Cl}_{1}(V)$ where $\mathrm{Cl}_{0}(V)$ is the image of even tensors and $\mathrm{Cl}_{1}(V)$ is the image of odd tensors. We also had

$$
\operatorname{Spin}(V):=\operatorname{Pin}(V) \cap \mathrm{Cl}_{0}(V)=\langle v \cdot w \mid v, w \in V,\|v\|=\|w\|=1\rangle
$$

There was a map

$$
\begin{aligned}
\operatorname{Pin}(V) & \rightarrow O(V) \\
v & \mapsto-R_{v}
\end{aligned}
$$

where $R_{v}$ was reflection about $v^{\perp}$, where we identified this as an action on $V^{\otimes 1} \subset \mathrm{Cl}(V)$ where $u \rightarrow v u v^{-1}$. For any Riemannian manifold $(X, g)$, we could define the Clifford bundle $\mathrm{Cl}(X)=$ $\mathrm{Cl}\left(T^{\vee} X, g^{\vee}\right)$ to globalise this from vector spaces to bundles with metrics. We defined a spin structure on $X$ as any lift of the principal $\operatorname{SO}(n)$ bundle over $\left(T^{\vee} X, g\right)$ (namely $\left.\operatorname{Frame}(X)\right)$ to a $\operatorname{Spin}(n)$ bundle.

## § Warning 44.0.2

Each fiber is a metric space, so what happens if you just try to define

$$
Y:=\coprod_{x \in X}\left\langle v \mid\|v\|^{2}=1, v \in T_{x}{ }^{\vee} X\right\rangle ?
$$

This seems to be isomorphic to a spin structure, but we do not have a distinguished action of any fixed group $\operatorname{Spin}(n)$. We would have to choose isomorphisms to the standard spin group at each fiber, but the isomorphisms are not unique - there is ambiguity up to the entire spin group. So this does not define a spin structure.

Remark 44.0.3: We showed that there exists a spin structure iff some cohomology class $w_{2}(K) \in$ $H^{2}(X ; \mathbb{Z} / 2)$ vanishes.

Theorem 44.0.4 (Classification of complex representations of Clifford algebras).
If $\operatorname{dim}_{k} V$ is even, there is a unique finite-dimensional complex irreducible $\mathrm{Cl}(V)$ representation of dimension $2^{n / 2}$. If $\operatorname{dim}_{k} V$ is odd, there are two complex conjugate representations of dimension $2^{\lfloor n / 2\rfloor}$.

Example 44.0.5(?): Consider $\mathrm{Cl}\left(\mathbb{R}^{2}\right) \cong \mathbb{H}$. There is an irreducible complex representation of dimension 2 :

$$
\begin{aligned}
& 1 \mapsto\left[\begin{array}{ll}
1 & 0 \\
0 & 1
\end{array}\right] \\
& i \mapsto \sigma_{1}:=\left[\begin{array}{ll}
0 & i \\
i & 0
\end{array}\right] \\
& j \mapsto \sigma_{2}:=\left[\begin{array}{cc}
i & 0 \\
0 & -i
\end{array}\right] \\
& k \mapsto \sigma_{3}:=\left[\begin{array}{cc}
0 & 1 \\
-1 & 0
\end{array}\right] .
\end{aligned}
$$

Definition 44.0.6 (Pauli matrices)
The $\sigma_{i}$ defined above are referred to as the Pauli matrices.

Example 44.0.7(?): Consider $\mathrm{Cl}\left(\mathbb{R}^{4}\right)$. By the theorem, there is a unique complex representation of $2^{4 / 2}=2^{2}=4$, although the 4 here matching the dimension of $\mathbb{R}^{4}$ is coincidental. We'd like to find an isomorphism

$$
\mathrm{Cl}\left(\mathbb{R}^{4}\right) \xrightarrow{\sim} \operatorname{End}\left(\left(\mathbb{C}^{2}\right)^{\otimes 2}\right) \cong \operatorname{End}\left(\mathbb{C}^{4}\right)=\operatorname{Mat}(4 \times 4 ; \mathbb{C})
$$

Note that $\operatorname{Cl}\left(\mathbb{R}^{4}\right) \xrightarrow{\sim} \operatorname{End}\left(\left(\mathbb{C}^{2}\right)^{\otimes 3}\right)$, which is why the dimensions multiply. We can write

$$
\mathrm{Cl}\left(\mathbb{R}^{4}\right)=\frac{\mathbb{R}\left\langle e_{1}, e_{2}, e_{3}, e_{4}\right\rangle}{e_{i} e_{j}+e_{j} e_{i}=2 \delta_{i j}}
$$

So define a map

$$
\begin{aligned}
& e_{1} \mapsto \gamma_{1}:=1 \otimes \sigma_{1} \\
& e_{2} \mapsto \gamma_{2}:=1 \otimes \sigma_{2} \\
& e_{3} \mapsto \gamma_{3}:=\sigma_{1} \otimes i \sigma_{3} \\
& e_{4} \mapsto \gamma_{4}:=\sigma_{2} \otimes i \sigma_{3} .
\end{aligned}
$$

Definition 44.0.8(Dirac matrices)
The matrices appearing above are called the Dirac matrices.
Exercise 44.0.9(?)
Determine a similar map for $\mathrm{Cl}\left(\mathbb{R}^{6}\right)$ continuing this pattern.
We can check that this is a representation. Note that we can tensor matrices in a simple way:
$e_{1} e_{2} \quad f_{1} \quad f_{2}$

| $e_{1}$ | $a$ | $b$ | $f_{1}$ | $e$ | $f$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $e_{2}$ | $c$ | $d$ | $f_{2}$ | $g$ | $h$ |

## Link to Diagram

Checking $e_{2} \cdot e_{2}=-1$, we have

$$
\begin{aligned}
\left(1 \otimes \sigma_{2}\right) \cdot\left(1 \otimes \sigma_{2}\right) & =? \\
1_{2} \otimes \sigma_{2}^{2} & =-I_{2} \oplus I_{2} \\
\gamma_{2} \gamma_{3} & =-\gamma_{3} \gamma_{2} .
\end{aligned}
$$

Todo: messed up!
One can similarly check

$$
\left(1 \otimes \sigma_{2}\right) \cdot\left(\sigma_{1} \otimes i \sigma_{3}\right)=-\left(\sigma_{1} \otimes i \sigma_{2}\right)\left(1 \otimes \sigma_{2}\right)
$$

Remark 44.0.10: We thus have $\mathrm{Cl}\left(\mathbb{R}^{4}\right) \curvearrowright \mathbb{C}^{4}$ by sending $e_{i} \mapsto \delta_{i}$, the Dirac matrices. Using that $\operatorname{Pin}(4) \cap \mathrm{Cl}\left(\mathbb{R}^{4}\right)=\operatorname{Spin}(4) \subseteq \mathrm{Cl}\left(\mathbb{R}^{4}\right)$, we can a spin representation, but this may no longer be irreducible. In fact, as a $\operatorname{Spin}(4)$ representation this splits into two irreducible representations. We know that $\operatorname{Spin}(4) \subseteq \mathrm{Cl}_{0}\left(\mathbb{R}^{4}\right)=\mathrm{Cl}\left(\mathbb{R}^{3}\right)$ which has two complex conjugate irreducible representations. The key is to define an element $\omega_{\mathbb{C}} \in \operatorname{Cl}(V) \otimes_{\mathbb{R}} \mathbb{C}$ with $\omega_{\mathbb{C}}^{2}=1$, which yields a decomposition of $\mathbb{S}=\mathbb{S}^{+} \oplus \mathbb{S}^{-}$as the $\pm 1$ eigenspaces of the action. Here $\omega_{C}:=-e_{1} e_{2} e_{3} e_{4} \mapsto \gamma_{5}$. One can define

$$
\gamma_{5}:=\operatorname{im}\left(\omega_{\mathbb{C}}\right)=-\gamma_{1} \gamma_{2} \gamma_{3} \gamma_{4}=-\sigma_{3} \otimes \sigma_{3}
$$

and one obtains the matrix

$$
-\sigma_{3} \otimes \sigma_{3}=\left[\begin{array}{cccc}
0 & 0 & 0 & -1 \\
0 & 0 & 1 & 0 \\
0 & 1 & 0 & 0 \\
-1 & 0 & 0 & 0
\end{array}\right]
$$

One can check that $\gamma_{5}$ anticommutes with the $\delta_{i}$ for $1 \leq i \leq 4$, and thus commutes with $\mathrm{Cl}_{0}\left(\mathbb{R}^{4}\right)$. We can write $\mathbb{S}^{+}$, the positive 1 eigenspace of $\gamma_{5}$, as $\mathbb{C}\left(s_{1}-s_{4}\right) \oplus \mathbb{C}\left(s_{1}+s_{2}\right)$. So we have $\operatorname{Spin}(4)=$ $\mathrm{Cl}\left(\mathbb{R}^{4}\right) \curvearrowright \mathbb{C}^{2} \oplus \mathbb{C}^{2}=\mathbb{S}$, which splits into $\gamma_{5}$-eigenspaces $\mathbb{S}^{+} \oplus \mathbb{S}^{-}$, the positive and negative spinors. This means that $\gamma_{5}$ commutes with the image of $\operatorname{Spin}(4) \hookrightarrow \operatorname{GL}\left(\mathbb{C}^{2} \oplus \mathbb{C}^{2}\right)$.

## Fact 44.0.11

If the action commutes with everything in the representation, the representation splits. (??? missed)

Remark 44.0.12: Let $g \in \operatorname{Spin}(4)$, and $v^{+} \in \mathbb{S}^{+} \subseteq \mathbb{S}$. Question: is it true that $g \cdot v^{+} \in \mathbb{S}^{+}$? If so, this yields a subrepresentation. If so, $\gamma_{5} v^{+}=v^{+}$since we're in the +1 eigenspace, and on the other hand, $g \cdot v^{+}=g \cdot \gamma_{5} v^{+}=g \omega_{\mathbb{C}} \cdot v^{+}$where the last identification comes from the map $\gamma_{5} \mapsto \omega_{\mathbb{C}}$, and this is equal to $\omega_{\mathbb{C}} g \cdot v^{+}$using commutativity. So $g \cdot v^{+}$is in the +1 eigenspace of $\gamma_{5}$.

Remark 44.0.13: Now take $\gamma_{i}$. This actually switches spinors: by anticommutativity of the $\gamma_{i}$ with $\gamma_{5}$, we have

$$
\gamma_{i} \cdot v^{+}=\gamma_{i} \gamma_{5} v^{+}=-\gamma_{5} \gamma_{i} v^{+}
$$

which means $\gamma_{i} v^{+}$is in the -1 eigenspace for $\gamma_{5}$, i.e. $\gamma_{i} v^{+} \in \mathbb{S}^{-}$.

Remark 44.0.14: Suppose one has a spin structure and $\tilde{P} \rightarrow X$ is a principal $\operatorname{Spin}(n)$ bundle. There are bundles over this of the form $\rho: \operatorname{Spin}(n) \rightarrow \mathrm{GL}\left(\mathbb{S}^{ \pm}\right)$, yielding the spinor bundle

$$
\underset{\operatorname{Spin}(n)}{\times} \mathbb{S}=\mathbb{S}_{x}^{+} \oplus \mathbb{S}_{x}^{-}
$$

Remark 44.0.15: Let $G \stackrel{\rho}{\rightarrow} \mathrm{GL}(V)$ be any representation. If $\varphi \in \operatorname{End}(V)$ commutes with $\rho(G)$, then the eigenspaces of $\varphi$ are subrepresentations. In other words, $G \curvearrowright V=\bigoplus_{i=1}^{n} V_{\lambda_{i}}$, then $G \curvearrowright V_{\lambda_{i}}$ is a subrepresentation, using that

$$
\varphi(v)=\lambda v \Longrightarrow g v=g \varphi\left(\lambda^{-1} v\right)=\varphi \rho(g) \lambda^{-1} v
$$

which says $\varphi(\rho(g) \cdot v)=\lambda(\rho(g) \cdot v) \Longrightarrow \rho(g) \cdot v \in V_{\lambda}$. We used it here by This rephrases Schur's lemma!

## 45 <br> Spin Bundles and Dirac Operators (Monday, May 03)

Remark 45.0.1: Last time: we defined a Spin structure on an oriented manifold $M$ as a lift of the principal $\mathrm{SO}(n)$ bundle $P \rightarrow M$ (unassociated to $T M$ ) to a $\operatorname{Spin}(n)$ bundle $\tilde{P}$. There was a spin representation $\operatorname{Spin}(n) \curvearrowright \mathbb{S}$, which is irreducible for $\mathrm{Cl}\left(\mathbb{R}^{n}\right)$ and splits as $\mathbb{S}=\mathbb{S}^{+} \oplus \mathbb{S}^{-}$, which are $\operatorname{Spin}(n)$ subrepresentations. We defined spinor bundles

$$
\tilde{P} \underset{\operatorname{Spin}(n)}{\times} \mathbb{S}=\mathbb{S}_{M}=\mathbb{S}_{M}^{+} \oplus \mathbb{S}_{M}^{-}
$$

Example 45.0.2(Dimension 4): If $\operatorname{dim}_{\mathbb{R}} M=4$, then $\mathbb{S}_{M}^{ \pm} \in \operatorname{Vect}_{\mathbb{C}}^{r a n k}=2$, i.e. they are complex vector bundles of rank 2 . Consider the eigenspaces $-e_{1} e_{2} e_{3} e_{4} \curvearrowright \mathbb{S}$, then $e_{i} \cdot(-): \mathbb{S}^{ \pm} \rightarrow \mathbb{S}^{\mp}$.

Remark 45.0.3: Principal bundle: fibers are left $G$-torsors. In the fiber product, the group sits in the middle and acts on each factor. So $\tilde{P}$ eats the right $G$-action, and $\mathbb{S}$ eats the left action. Remarkably, for Spin bundles, there is an action leftover.

Proposition 45.0.4(The spin bundle is a Clifford module).
The spin bundle $\mathbb{S}_{M}$ naturally has the structure of a $\mathrm{Cl}(M)$-module.

Proof (?).
We have a Clifford action

$$
\begin{aligned}
\mathrm{Cl}\left(\mathbb{R}^{n}\right) & \otimes \mathbb{S} \\
x & \rightarrow \mathbb{S} \\
x & \mapsto x \cdot s
\end{aligned}
$$

Recall that we have a natural conjugation action $\operatorname{Spin}(n) \curvearrowright \mathrm{Cl}\left(\mathbb{R}^{n}\right)$ where $g \mapsto g(-) g^{-1}$, and similarly $\operatorname{Spin}(n) \curvearrowright \mathbb{S}$ by $g \mapsto g \cdot(-)$. Given any $V \rightarrow W$ of $G$-modules, any $P \in \operatorname{Bun}^{\text {prin }}(G)$ yields an induced module

$$
\underset{G}{P \times V} \rightarrow P \underset{G}{P \times} W
$$

and moreover $\tilde{P} \underset{\operatorname{Spin}(n)}{\times} \mathrm{Cl}\left(\mathbb{R}^{n}\right)=\mathrm{Cl}(M)$. We then conclude that there is an action $\mathrm{Cl}(M) \otimes \mathbb{S}_{M} \rightarrow$ $\mathbb{S}_{M}$, the Clifford multiplication.

Remark 45.0.5: We have an isomorphism of bundles (not of algebras) $\mathrm{Cl}(M) \cong \bigwedge T^{\vee} M$, and any one form $\omega$ is an analogue of an element of $V^{\otimes 1}$, and $\omega \cdot\left(\mathbb{S}^{+}, \mathbb{S}^{-}\right) \in \mathbb{S}_{M}^{-} \oplus \mathbb{S}_{M}^{+}$.

Definition 45.0.6 (Clifford connection)
A connection $\nabla$ on $\mathbb{S}$ is a Clifford connection if

$$
\nabla(x \cdot s)=x \cdot \nabla(s)+d(x) \cdot s \quad x \in H^{0} \mathrm{Cl}(M)=H^{0}\left(\bigwedge^{*} T^{\vee} M\right), s \in H^{0}\left(\mathbb{S}_{M}\right)
$$

where $d$ is the de Rham differential.

Remark 45.0.7: It is not obvious that a Clifford connection exists! We have $\mathbb{S}_{M}=\tilde{P} \underset{\text { Spin }(n)}{\times} \mathbb{S}$, so it suffices to give a connection on $\tilde{P}$ which is $\operatorname{Spin}(n)$ invariant, since any associated bundle will inherit the connection. Idea: we need a notion of parallel transport. This is a principal $\operatorname{Spin}(n)$ bundle, so the fibers look like $\operatorname{Spin}(n)$, and we want to lift paths in $M$ to paths in $\tilde{P}$ :

## $\operatorname{Spin}(n)$



It suffices to give a connection on $P$, and using that $\tilde{P} \rightarrow P$ is a 2 to 1 covering map, we can take a connecting on $P$ coming from $\operatorname{OFrame}\left(T^{\vee} M, g^{\vee}\right)$. So it further suffices to produce a connection on $T^{\vee} M$ preserving orthogonality of frames under parallel transport, which is essentially the definition of the Levi-Cevita connection $\nabla^{\mathrm{LC}}$. Then the $\nabla$ associated to $\nabla^{\mathrm{LC}}$ on $P$ is a Clifford connection, yielding existence.

Remark 45.0.8: The set of Clifford connections is a torsor over $\Omega^{1}(M)$. The association is $\nabla \mapsto \nabla-\nabla^{\mathrm{LC}}$, and one can compute

$$
\left(\nabla-\nabla^{\mathrm{LC}}\right)(x \cdot s)=x \cdot\left(\nabla-\nabla^{\mathrm{LC}}\right)(s),
$$

which exactly says that this is a $\mathrm{Cl}(M)$-linear map $\mathbb{S}_{M} \rightarrow \mathbb{S}_{M} \otimes \Omega^{1}$. We can write $\mathrm{Cl}(M) \cong \operatorname{End}\left(\mathbb{S}_{M}\right)$, and one can check that $\left[E n d \mathbb{S}_{M}, E n d \mathbb{S}_{M}\right]$ consists only of scalars.

Definition 45.0.9 (Dirac Operator)
Let $\nabla$ be a Clifford connection on $\mathbb{S}_{M}$ and $s \in H^{0}\left(\mathbb{S}_{M}\right)$, so $\nabla(s) \in \mathbb{S}_{M} \otimes \Omega^{1}(M)$. Then the
Dirac operator is defined as

$$
\begin{aligned}
\partial: H^{0}(\mathbb{S}) & \rightarrow H^{0}(\mathbb{S}) \\
s & \mapsto \sum_{e_{i} \in \operatorname{Fr}\left(T^{\vee} M\right)} e_{i} \cdot \nabla_{e_{i} \vee}(s)
\end{aligned}
$$

where

- $\nabla(s)=H^{0}\left(\mathbb{S}_{M} \otimes \Omega^{1}\right)$
- $\nabla_{e_{i} \vee}(s)=\nabla(s)\left(e_{i}{ }^{\vee}\right) \in H^{0}\left(\mathbb{S}_{M}\right)$

Remark 45.0.10: This makes sense locally, and is well-defined independent of choice of frame. Henceforth, we'll take $\nabla=\nabla^{\mathrm{LC}}$ - in this case, if $s^{+} \in H^{0}\left(\mathbb{S}^{ \pm}\right)$then $\nabla_{v}^{\mathrm{LC}}\left(s^{ \pm}\right) \in H^{0}\left(\mathbb{S}^{ \pm}\right)$. This is an order 1 differential operator:

$$
\not \partial_{\nabla^{\mathrm{LC}}}=\not \partial: H^{0}\left(\mathbb{S}^{ \pm}\right) \rightarrow H^{p}\left(\mathbb{S}^{\mp}\right)
$$

## Proposition 45.0.11(Relation between Dirac operator and Laplacian).

$$
\not \partial^{2}=-\Delta
$$

## Proof (?).

Given $\psi \in H^{0}(\mathbb{S})$, write $\psi=\sum_{i=1}^{4} \psi_{i} s_{i}$ with the $s_{i}$ forming a local frame of $\mathbb{S}=\mathbb{S}^{+} \oplus \mathbb{S}^{-}$. We can write

$$
\not \partial \psi=\sum e_{i} \partial_{x_{i}} \psi=\sum_{i=1}^{4} \gamma_{i} \psi_{x_{i}}
$$

where $\psi_{x_{i}}=\left[\left(\psi_{1}\right)_{x_{i}},\left(\psi_{2}\right)_{x_{i}}, \cdots\right]$. We then have

$$
\begin{aligned}
\not \partial^{2} \psi & =\sum_{i, j} \gamma_{i} \gamma_{j} \psi_{x_{i} x_{j}} \\
& =-\sum_{i j} 2\left(e_{i} \cdot{ }_{g} e_{j}\right) \psi_{x_{i} x_{j}} \\
& =-2 \sum_{i j} \delta_{i j} \psi_{x_{i} x_{j}} \\
& =-2 \sum_{i} \psi_{x_{i} x_{i}} \\
& =-2\left(\sum_{i=1}^{4} \partial_{x_{i}}^{2}\right) \psi \\
& =-2 \Delta
\end{aligned}
$$

where we sum over all $i, j$ and can pair terms, and we use that $\gamma_{i} \gamma_{j}+\gamma_{j} \gamma_{i}=-2 e_{1} \cdot e_{j}$
Upshot: $\not \partial \mathcal{}$, which is why the Dirac is an invariant in quantum mechanics. This reduces the 2 nd order Schrödinger operator a 1 st order operator. Note that $\not \partial \psi=0$ is the equation for a massless particle.

## 46 Wednesday, May 05

### 46.1 Fun Physics Aside

Remark 46.1.1: Last time: we showed $\mathrm{Cl}(X):=\mathrm{Cl}\left(T^{2} X, g^{2}\right)$ acts on the spinor bundle $\mathbb{S}_{X}:=$ $\tilde{P} \underset{\text { Spin }(n)}{\times} \mathbb{S}$ by Clifford multiplication. For $\operatorname{dim}_{\mathbb{R}} X=4$, we have a splitting $\mathbb{S}^{+} \oplus \mathbb{S}^{-}$as complex rank $\operatorname{spin}(n)$
2 vector bundles. If $\omega \in H^{0} \mathrm{Cl}(X)$ is a one form, then $\omega \mathbb{S}_{X}^{ \pm} \subset \mathbb{S}^{\mp}$.
Definition 46.1.2 (Clifford Connection)
A Clifford connection is a map

$$
\nabla: \mathbb{S}_{X} \rightarrow \mathbb{S}_{X} \otimes \Omega^{1}
$$

where $\alpha \cdot s \mapsto \alpha \cdot \nabla s+d x \cdot s$.

Remark 46.1.3: There is a distinguished Clifford connection associated to $\nabla^{\mathrm{LC}}$. Also recall that we defined a Dirac operator $\not \partial 0$ and showed $\not \partial^{2}=-2 \Delta$.

Definition 46.1.4 (The Dirac Equation)
The Dirac equation is defined on $\psi \in H^{0}(X, \mathbb{S})$ as

$$
(i \not \partial+m \omega) \psi=0
$$

Here $m$ denotes a mass, $\omega=\omega_{\mathbb{C}}=\prod_{i=1}^{4} \gamma_{i}$.

Remark 46.1.5: This describes fermions in a vacuum, e.g. an electron where $\psi$ is its wave function. Applying this to $\mathbb{R}^{4}$ with $g=(d t)^{2}-(d x)^{2}-(d y)^{2}-(d z)^{2}$, then this equation in $\psi$ is invariant under the Lorentz group $O\left(\mathbb{R}^{4}, g\right)$.

### 46.2 Rohklin's Theorem

## Theorem 46.2.1(Rohklin's Theorem).

Let $X$ be a smooth closed oriented spin 4-manifold. Then the signature $\sigma(X):=b_{2}^{+}(X)-b_{2}^{-}(X)$ (the dimensions of positive/negative definite subspaces of $H^{2}(X ; \mathbb{R})$ is divisible by 16 .

Remark 46.2.2: This restricts what topological manifolds can admit smooth structures. Freedman constructed a topological manifold of dimension 4 with signature 8 , which thus can not admit a
smooth structure. Recall that having a spin structure was having a lift of a principal $\mathrm{SO}(n)$ bundle over $\left(T^{\imath} X, g\right)$ (namely $\left.\operatorname{Frame}(X)\right)$ to a $\operatorname{Spin}(n)$ bundle.


### 46.2.1 Proof

Consider $\mathbb{S}_{X}:=\tilde{P} \underset{\operatorname{Spin}(n)}{\times} \mathbb{S}$, then define

$$
\not \partial^{ \pm}: H^{0}\left(\mathbb{S}_{X}^{ \pm}\right) \rightarrow H^{0}\left(\mathbb{S}^{\mp}\right)
$$

Note that we can write $\not \partial=\not \partial^{+}+\not \partial^{-} ;$

- Step 1: Show ind $\not \partial^{+}=-\sigma(X) / 8$,
- Step 2: Show ind $\not \partial^{+}$is even.


### 46.2.2 Step 1

What is the symbol $\operatorname{Symb}(\not \partial)$ ? By definition

$$
\operatorname{Symb} \not \partial: \pi^{*} \mathbb{S} \rightarrow \pi^{*} \mathbb{S} .
$$

where $\pi: T^{\vee} X \rightarrow X$, and the symbol was defined by replacing $\frac{\partial}{\partial x_{i}}$ with a function $y_{i}: T^{\vee} X \rightarrow \mathbb{R}$. We can write

$$
\partial \varphi=\sum_{e_{i} \in \mathrm{Fr}} e_{i} \cdot \nabla_{e_{i} v} \psi,
$$

and so

$$
\operatorname{Symb} \not \partial(\psi)=\sum_{i} y_{i} e_{i}=\psi
$$

We have a tautological form $\alpha \in H^{0}\left(T^{\vee} X, \pi^{*} \Omega^{1}\right)$ where $(p, \alpha) \mapsto \alpha$, and so $\operatorname{Symb}(\not \partial)(-)=\alpha \cdot(-)$.

## Claim:

$$
\not \partial: H^{0}(\mathbb{S}) \circlearrowleft \quad \text { is an elliptic operator. }
$$

We need to check that the map $\alpha \cdot(-)$ is exact if $\alpha \neq 0$.

We have $\alpha \cdot(-): \mathbb{S} \rightarrow \mathbb{S}$ and

$$
(-\alpha)(-) \alpha(-)=(-\alpha \cdot \alpha)=\|\alpha\|^{2} \neq 0
$$

which makes the operator invertible away from zero. Thus we can apply Atiyah-Singer.

## Lemma 46.2.3(Formula for Chern characters).

There is a nice formula for Chern characters:

$$
\operatorname{ch} \mathbb{S}^{+}-\operatorname{ch} \mathbb{S}^{-}=\prod_{i=1}^{n}\left(e^{x_{i} / 2}-e^{-x_{i} / 2}\right)
$$

where $\left\{ \pm x_{i}\right\}$ are the Chern roots of $T^{\vee} X$.

Proof (?).
Use the splitting principle to write

$$
T^{\vee} X \otimes_{\mathbb{R}} \mathbb{C}=\bigoplus_{i=1}^{n} L_{i} \otimes L_{i}^{-1}
$$

Then $\mathbb{S}^{+}$is a sum of all tensor products of $L_{i} \otimes L_{i}^{-1}$ where the number of -1 s appearing is even.

Remark 46.2.4: Note there is ambiguity up to 2-torsion in the formula, but this gets moved into the choice of spin structure, which amounts to choice of a square root of each of these line bundles.

Setting $2 n:=\operatorname{dim} X$, we have

$$
\text { ind } \begin{aligned}
\not \partial^{+} & =(-1)^{n} \int_{X} \frac{\operatorname{ch} \mathbb{S}^{+}-\operatorname{ch} \mathbb{S}^{-}}{\operatorname{eul} X} \operatorname{td}(T X \otimes \mathbb{C}) \\
& =\int_{X} \frac{\prod e^{x_{i} / 2}-e^{-x_{i} / 2}}{(-1)^{n} \prod x_{i}} \prod \frac{x_{i}}{1-e^{x_{i}}} \prod \frac{x_{i}}{1-e^{-x_{i}}} \\
& =\int_{X} \prod \frac{\left(e^{x_{i} / 2}-e^{\left.-x_{i} / 2\right)} x_{i}\right.}{\left(1-e^{x_{i}}\right)\left(1-e^{-x_{i}}\right)} \\
& =(-1)^{n} \int_{X} \prod_{I} \frac{x_{i}}{e^{x_{i} / 2}-e^{-x_{i} / 2}} \\
& =\int_{X}\left(1-\frac{x_{1}^{2}}{24}\right)\left(1-\frac{x_{2}^{2}}{24}\right) \\
& =-\frac{1}{24} \int_{X} x_{1}^{2}+x_{2}^{2}+\left(x_{1}+x_{2}\right)^{2}-2 x_{1} x_{2} \\
& =-\frac{1}{24}\left(c_{1}^{2}-2 c_{2}\right) .
\end{aligned}
$$

Remark 46.2.5: See the $\widehat{A}$ genus.

## Claim:

$$
c_{1}^{2}-2 c^{2}=3 \cdot \sigma(X)
$$

This is another application of Atiyah-Singer, applied to a slightly different operator. Recall the Hodge star operator,

$$
\star: \Omega^{k}(X) \rightarrow \Omega^{4-k}(X) .
$$

Defining $\tau:=i^{\frac{k(k-1)+4}{2}}$, we get $\tau^{2}=1$, so define an operator $\tau \star$. This yields a splitting into $\pm 1$ eigenspaces:

$$
\Omega(X)=\Omega^{+}(X) \oplus \Omega^{-}(X) .
$$

Recalling that $d^{\dagger}$ was the adjoint of $d$, one can check that $d+d^{\dagger}: \Omega^{ \pm}(X) \rightarrow \Omega^{\mp}(X)$ interchanges these. It turns out that $\operatorname{ind}\left(d+d^{\dagger}\right)=\sigma(X)$, which by Atiyah-Singer and Hermite forms will equal $\frac{c_{1}^{2}-2 c_{2}}{3}$. This yields the desired formula for step 1 .

### 46.3 Step 2

We now want to show ind $\not \partial^{+}$is divisible by 2 . The key point is that ker $\not \partial^{+}$and coker $\not \partial^{+}=$ker $\not \partial^{-}$ admit a quaternionic vector space structure. This comes from the fact that

$$
\operatorname{Spin}(4) \cong \mathrm{SU}(2) \times \mathrm{SU}(2) \cong S^{1}(\mathbb{H}) \oplus S^{1}(\mathbb{H}):=\mathbb{S}^{+} \oplus \mathbb{S}^{-}
$$

so we have a splitting into subspaces of unit quaternions. It turns out that $\not \mathscr{D}$ is $\mathbb{H}$-linear. So we get an equality

$$
-\sigma(X) / 8=\operatorname{ind} \not \partial^{+}=2 \lambda
$$

for some $\lambda$, yielding $8 \mid \sigma(X)$.

### 46.4 Remarks

Remark 46.4.1: If $H_{1}(X ; \mathbb{Z})$ has no 2-torsion, e.g. if $\pi_{1} X=0$, then $w_{2}(X)=0$ iff the intersection form on $H^{2}$ is even, where $w_{2}$ is the obstruction to existence of spin structures. Note that this makes sense for topological manifolds and not just smooth manifolds, and in this case $\sigma(X)$ is divisible by 8 . This restriction comes from number theory: since we have a unimodular lattice, it breaks into sums of $E_{8},-E_{8}$, and $H$ if indefinite, and any even unimodular lattice has signature divisible by 8 . So this can work as an obstruction to the existence of smooth structures.

Remark 46.4.2: Note that $\mathbb{C P}^{2}$ has no spin structure, and $\sigma\left(\mathbb{C P}^{2}\right)=1$. There's a way to modify the invariant to set $\sigma(X) / 8=$ ? $(\bmod 2)$.

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[^0]:    ${ }^{1}$ Note that this doesn't start at $C^{0}$, so topological manifolds are genuinely different! There exist topological manifolds with no smooth structure.

[^1]:    ${ }^{2}$ Locally admits a chart to $\mathbb{C}^{n} / \Gamma$ for $\Gamma$ a finite group.

[^2]:    ${ }^{a}$ So $X$ admits an embedding into some $\mathbb{C P}^{N}$.

