Chapter 9

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1 | Background, Notation, Setup

Goals

Theorem 1.1(Arnold Conjecture (Symplectic Morse Inequalities?)).

Let (W, ω) be a compact symplectic manifold and

$$H:W\to\mathbb{R}$$

a time-dependent Hamiltonian with nondegenerate 1-periodic solutions. Then

{1-Periodic trajectories of
$$X_H$$
} $\geq \sum_{k \in \mathbb{Z}} \dim_2 HM_k(W; \mathbb{Z}/2\mathbb{Z}).$

Here $HM_*(W)$ is the Morse homology, and *nondegenerate* means the differential of the flow at time 1 has no fixed vectors.

Important Ideas for This Chapter:

Theorem 1.2 (Use Broken Trajectories to Compactify). $\mathcal{L}(x, y)$ is compact, where the compactification is given by adding in

 $\partial \mathcal{L}(x, y) = \{ "Broken Trajectories" \}$

Theorem 1.3 (Gluing Yields a Chain Complex).

 $\partial^2 = 0$

Strategy:

In the background, have a Hamiltonian $H: W \to \mathbb{R}$. Basic idea: cook up a gradient flow.

1. Define the action functional \mathcal{A}_H

On an infinite-dimensional space, critical points are periodic solutions of ${\cal H}$

2. Construct the chain complex (graded vector space) CF_* .

Uses analog of the index of a critical point.

3. Define the vector field X_H using $-\text{grad } \mathcal{A}_H$.

This will be used to define ∂ later.

- 4. Count the trajectories of X_H
- 5. Show finite-energy trajectories connect critical points of \mathcal{A}_H .
- 6. Show *Gromov Compactness* for space of trajectories of finite energy
- 7. Define ∂

Uses another compactness property

- 8. Show space of trajectories is a manifold, plus analog of "Smale property"
- 9. Show that $\partial^2 = 0$ using a gluing property
- 10. Show that HF_* doesn't depend on \mathcal{A}_H or X_H
- 11. Show $HF_* \cong HM_*$, and compare dimensions of the vector spaces CM_* and CF_* .

Ingredients:

- (W, ω, J) with $\omega \in \Omega^2(W)$ is a symplectic manifold
 - With $J: T_pW \to T_pW$ an almost complex structure, so $J^2 = -\mathrm{id}$.
- $H \in C^{\infty}(W; \mathbb{R})$ a Hamiltonian
 - $-X_H$ the corresponding symplectic gradient.
 - Defined by how it acts on tangent vectors in $T_x M$:

 $\omega_x(\,\cdot\,,X_H(x))=(dH)_x(\,\cdot\,).$

- Zeros of vector field X_H correspond to critical points of H:

 $X_H(x) = 0 \iff (dH)_x = 0.$

– Take the associated flow, assumed 1-periodic:

 $\psi^t \in C^\infty(W, W) \qquad \psi^1 = \mathrm{id},$

- Critical points of ${\cal H}$ are periodic trajectories.
- $u \in C^{\infty}(\mathbb{R} \times S^1; W)$ is a solution to the Floer equation.
- The Floer equation and its linearization:

$$\mathcal{F}(u) = \frac{\partial u}{\partial s} + J \frac{\partial u}{\partial t} + \text{grad }_{u}(H) = 0$$
$$(d\mathcal{F})_{u}(Y) = \frac{\partial Y}{\partial s} + J_{0} \frac{\partial Y}{\partial t} + S \cdot Y$$

$$Y \in u^*TW, \ S \in C^{\infty}(\mathbb{R} \times S^1; \operatorname{End}(\mathbb{R}^{2n})).$$

- $\mathcal{L}W$ is the *free loop space* on W, i.e. space of contractible loops on W, i.e. $C^{\infty}(S^1; W)$ with the C^{∞} topology
 - Elements $x \in \mathcal{L}W$ can be viewed as maps $S^1 \to W$.
 - Can extend to maps from a closed disc, $u: \overline{\mathbb{D}}^2 \to M$.
 - Loops in $\mathcal{L}W$ can be viewed as maps $S^2 \to W$, since they're maps $I \times S^1 \to W$ with the boundaries pinched:

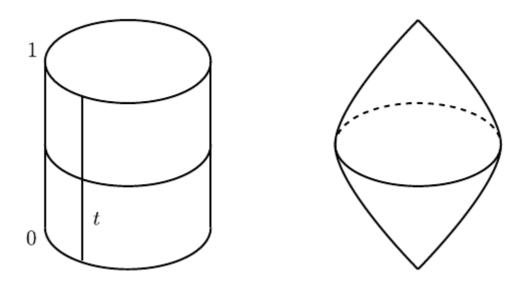


Figure 1: Loops in $\mathcal{L}W$

• The action functional is given by

$$\mathcal{A}_{H} : \mathcal{L}W \to \mathbb{R}$$
$$x \mapsto -\int_{\mathbb{D}} u^{*}\omega + \int_{0}^{1} H_{t}(x(t)) dt$$
$$- \text{Example: } W = \mathbb{R}^{2n} \implies A_{H}(x) = \int_{0}^{1} (H_{t} dt - p dq).$$
$$- \text{A correspondence}$$
$$\left\{ \begin{cases} \text{Solutions to the} \\ \text{Floer equation} \end{cases} \right\} \iff \left\{ \begin{cases} \text{Trajectories} \\ \text{of grad } \mathcal{A}_{H} \end{cases} \right\}.$$

• x, y periodic orbits of H (nondegenerate, contractible), equivalently critical points of \mathcal{A}_H .

• Assumption of *symplectic asphericity*, i.e. the symplectic form is zero on spheres. Statement: for every $u \in C^{\infty}(S^2, W)$,

$$\int_{S^2} u^* \omega = 0 \quad \text{or equivalently} \quad \langle \omega, \pi_2 W \rangle = 0.$$

• Assumption of *symplectic trivialization*: for every $u \in C^{\infty}(S^2; M)$ there exists a symplectic trivialization of the fiber bundle u^*TM , equivalently

 $\langle c_1 TW, \ \pi_2 W \rangle = 0.$

Locally a product of base and fiber, transition functions are symplectomorphisms.

- Maslov index: used the fact that
 - Every path in $\gamma : I \to \operatorname{Sp}(2n, \mathbb{R})$ can be assigned an integer coming from a map $\tilde{\gamma} : I \to S^1$ and taking (approximately) its winding number.
- $\mathcal{M}(x, y)$, the moduli space of contractible finite-energy solutions to the Floer equation connecting x, y.
 - After perturbing H to get transversality, get a manifold
 - * Dimension:

$$\dim \mathcal{M}(x,y) = \mu(x) - \mu(y).$$

- How we did it:
 - * Describe as zeros of a section of a vector bundle over $\mathcal{P}^{1,p}(x,y)$
 - (Banach manifold modeled on the Sobolev spaces $W^{1,p}$),
 - * Apply Sard-Smale to show $\mathcal{M}(x, y)$ is the inverse image of a regular value of some map.
- Needed tangent maps to be Fredholm operators, proved in Ch. 8 and used to show transversality.
 - * Showed $(d\mathcal{F})_u$ is a Fredholm operator of index $\mu(x) \mu(y)$.

2 | Reminder of Goals

Overall Goal:

Theorem 2.1 (Symplectic Morse Inequalities).

{1-Periodic trajectories of
$$X_H$$
} $\geq \sum_{k \in \mathbb{Z}} HM_k(W; \mathbb{Z}/2\mathbb{Z}).$

Important Ideas for This Chapter:

Theorem 2.2 (Using Broken Trajectories to Compactify). $\mathcal{L}(x, y)$ is compact,

 $\partial \mathcal{L}(x, y) = \{$ "Broken Trajectories" $\}$

Theorem 2.3 (Using Gluing to Get a Chain Complex).

 $\partial^2 = 0$

$\mathbf{3}\mid$ 9.1 and Review

• Defined moduli space of (parameterized) solutions:

 $\mathcal{M}(x, y) = \{$ Contractible finite-energy solutions connecting $x, y\}$

 $\mathcal{M} = \{ \text{All contractible finite-energy solutions to the Floer equation} \}$ $= \bigcup_{x,y} \mathcal{M}(x,y).$

• The moduli space of (unparameterized) **trajectories** connecting x, y:

 $\mathcal{L}(x,y) \coloneqq \mathcal{M}(x,y)/\mathbb{R}.$

- Use the quotient topology, define sequentially:

 $\tilde{u}_n \stackrel{n \to \infty}{\longrightarrow} \tilde{u} \quad \iff \quad \exists \{s_n\} \subset \mathbb{R} \text{ such that } u_n(s_n + s, \cdot) \stackrel{n \to \infty}{\longrightarrow} u(s, \cdot).$

– When $|\mu(x) - \mu(y)| = 1$, get a compact 0-manifold, so the number of trajectories

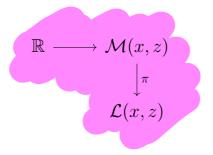
$$n(x,y) \coloneqq \#\mathcal{L}(x,y)$$

is well-defined.

- $C_k(H) \coloneqq \mathbb{Z}/2\mathbb{Z}[\{\text{Periodic orbits of } X_H \text{ of Maslov index } k\}].$
 - Finitely many since they are nondegeneracy implies they are isolated.

Remark 1.

Some notation:



Hats will generally denote maps induced on quotient.

• Defined a differential

$$\partial: C_k(H) \to C_{k-1}(H)$$

$$x \mapsto \sum_{\mu(y)=k-1} n(x, y)y$$

$$n(x, y) \coloneqq \# \{ \text{Trajectories of grad } \mathcal{A}_H \text{ connecting } x, y \} \mod 2$$

$$= \# \mathcal{L}(x, y) \mod 2.$$

• Examined ∂^2 :

$$\begin{split} \partial^2 &: C_k(H) \to C_{k-2}(H) \\ &x \mapsto \partial(\partial(x)) \\ &= \partial \left(\sum_{\mu(y)=\mu(x)-1} n(x,y)y \right) \\ &= \sum_{\mu(y)=\mu(x)-1} n(x,y)\partial(y) \\ &= \sum_{\mu(y)=\mu(x)-1} n(x,y) \left(\sum_{\mu(z)=\mu(y)-1} n(y,z)z \right) \\ &= \sum_{\mu(z)=\mu(y)-1} \sum_{\mu(z)=\mu(y)-1} n(x,y)n(y,z)z \\ &= \sum_{\mu(z)=\mu(y)-1} \left(\sum_{\mu(y)=\mu(x)-1} n(x,y)n(y,z) \right) z \qquad \text{(finite sums, swap order),} \\ \text{so it suffices to show} \\ &\sum_{\mu(y)=\mu(x)-1} n(x,y)n(y,z) = 0 \quad \text{when} \quad \mu(z) = \mu(x) - 2. \end{split}$$
Easier to examine parity, so we'll show it's zero mod 2.

- When $\mu(z) = \mu(x) 2$, $\mathcal{L}(x, z)$ is a non-compact 1-manifold, so we compactify by adding in *broken trajectories* to get $\overline{\mathcal{L}}(x, y)$.
- We'll then have

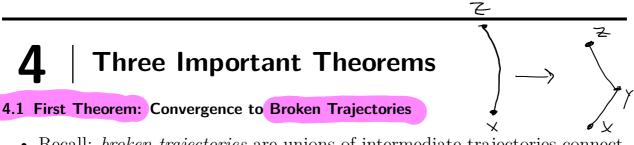
$$\overline{\mathcal{L}}(x,z) = \mathcal{L}(x,z) \cup \partial \overline{\mathcal{L}}(x,z), \qquad \partial \overline{\mathcal{L}}(x,z) = \bigcup_{\mu(y) = \mu(x) - 1} \mathcal{L}(x,y) \times \mathcal{L}(y,z),$$

which "space-ifies" the equation we want.

• We'll show $\partial \overline{\mathcal{L}}(x, z)$ is a 1-manifold, which must have an even number of points, and thus

$$\sum_{\mu(y)=\mu(x)-1} n(x,y)n(y,z) = \#(\partial \overline{\mathcal{L}}(x,z)) \equiv 0 \mod 2.$$

Image here of relations between spaces!



- Recall: *broken trajectories* are unions of intermediate trajectories connecting intermediate critical points.
- Shown last time: a sequence of trajectories can converge to a broken trajectory, i.e. there are broken trajectories in the closure of $\mathcal{L}(x, z)$.
- This theorem describes their behavior:

Theorem 4.1 (9.1.7: Convergence to Broken Trajectories). Let $\{u_n\}$ be a sequence in $\mathcal{M}(x, z)$, then there exist

- A subsequence $\left\{u_{n_j}\right\}$
- Critical points $\{x_0, x_1, \cdots, x_{\ell+1}\}$ with $x_0 = x$ and $x_{\ell+1} = z$
- Sequences $\{s_n^1\}, \{s_n^2\}, \cdots, \{s_n^\ell\}.$

• Elements $u^k \in \mathcal{M}(x_k, x_{k+1})$ such that for every $0 \le k \le \ell$,

• Upshots:

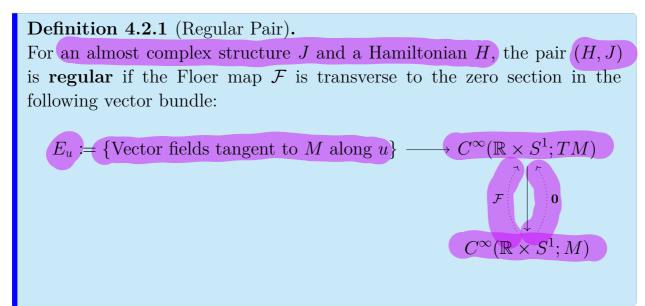
- Every sequence upstairs has a subsequence which (after reparameterizing) converges

 $u_{n_j} \cdot s_n^k \stackrel{n \to \infty}{\longrightarrow} u^k$

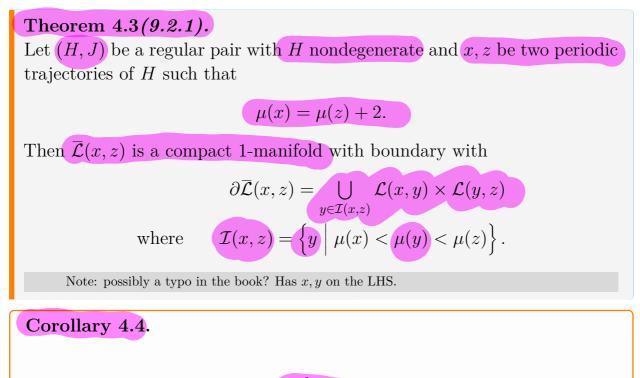
- This descends to actual convergence after quotienting by $\mathbb{R}?$
- Yields uniqueness of limits in $\mathcal{L}(x, z)$, thus a separated topology
- Sequentially compact \iff compact since $\mathcal{L}(x, z)$ is a metric space?

Corollary 4.2(Compactness). $\overline{\mathcal{L}}(x, z)$ is compact.

4.2 Second Theorem: Compactness of $\overline{\mathcal{L}}(x,z)$



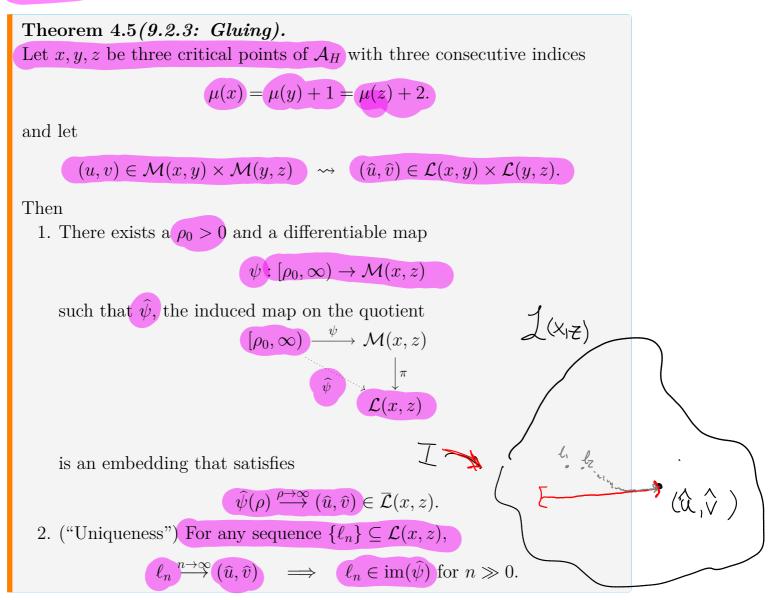
Most of chapter 9 is spent proving this theorem:



 $\partial^2 = 0.$

4.3 Third Theorem: Gluing

4.3 Third Theorem: Gluing



- We already know that $\overline{\mathcal{L}}(x, z)$ is compact and $\mathcal{L}(x, z)$ is a 1-manifold, so we look at neighborhoods of boundary points.
- Why unique: will show that the broken trajectory (\hat{u}, \hat{v}) is the endpoint of an embedded interval in $\overline{\mathcal{L}}(x, z)$.
 - Then show that any other sequence converging to (\hat{u}, \hat{v}) must approach via this interval, otherwise could have cuspidal points:

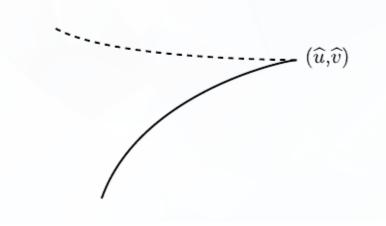


Figure 2: Cuspidal Point on Boundary

5 Gluing Theorem

Broken into three steps:

1. Pre-gluing:

- Get a function w_{ρ} which interpolates between u and v in the parameter ρ .
 - Not exactly a solution itself, just an "approximation".

2. Newton's Method:

• Apply the Newton-Picard method to w_p to construct a true solution

$$\psi: [-\rho, \infty) \to \mathcal{M}(x, z)$$
$$\rho \mapsto \exp_{w_p}(\gamma(p))$$

for some $\gamma(p) \in W^{1,p}(w_p^*TW) = T_{w_p}\mathcal{P}(x,z)$

• GIF of Newton's Method

3. Project and Verify Properties:

• Check that the projection $\hat{\psi} = \pi \circ \psi$ satisfies the conditions from the theorem.

6 | 9.3: Pre-gluing, Construction of w_{ρ}

- Choose (once and for all) a bump function β on $B_{\varepsilon}(0)^c \subset \mathbb{R} \to [0, 1]$ which is 1 on $|x| \ge 1$ and 0 on $|x| < \varepsilon$
- Split into positive and negative parts $\beta^{\pm}(s)$:

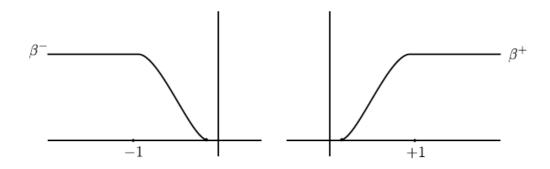


Figure 3: Bump away from zero

• Define an interpolation w_{ρ} from u to v in the following way: let

$$-\exp\left[\cdot\right] \coloneqq \exp_{y(t)}(\cdot) \text{ and} \\ -\ln(\cdot) \coloneqq \exp_{y(t)}^{-1}(\cdot),$$

then

$$w_{\rho}: x \to z$$

$$w_{\rho}(s,t) \coloneqq \begin{cases} u(s+\rho,t) & s \in (-\infty,-1] \\ \exp\left[\beta^{-}(s)\ln(u(s+\rho,t)) + \beta^{+}(s)\ln(u(s-\rho,t))\right] & s \in [-1,1] \\ u(s-\rho,t) & s \in [1,\infty) \end{cases}$$

• Why does this make sense?

$$|s| \le 1 \implies u(s \pm \rho, t) \in \left\{ \exp_{y(t)} Y(t) \mid \sup_{t \in S^1} \|Y(t)\| \le r_0 \right\} \subseteq \operatorname{im} \exp_{y(t)}(\cdot),$$

so we can apply $\exp_{y(t)}^{-1}(\cdot).$

• Can make $|s| \leq 1$ for large ρ , since

$$\begin{array}{ccc} u(s,t) \stackrel{s \to \infty}{\longrightarrow} & y(t) \\ v(s,t) \stackrel{s \to -\infty}{\longrightarrow} & y(t). \end{array}$$

- So pick a ρ_0 such that this holds for $\rho > \rho_0$.
- Might have to increase ρ_0 later in the proof, so $\rho > \rho_0$ just means $\rho \gg 0$.
- Some properties:

$$\begin{split} -w_{\rho} \in C^{\infty}(x,z) \text{ and is differentiable in } \rho. \\ -s \in [-\varepsilon,\varepsilon] \implies w_{\rho}(s,t) = y(t). \\ w_{\rho}(s-\rho,t) \xrightarrow{\rho \to \infty} u(s,t) \quad \text{in} \quad C_{\text{loc}}^{\infty} \\ w_{\rho}(s,t) \xrightarrow{\rho \to \infty} y(t) \quad \text{in} \quad C_{\text{loc}}^{\infty}. \end{split}$$

- Now carry out the linearized version on tangent vectors, to which we will apply Newton-Picard:
 - Let $Y \in T_u \mathcal{P}(x, y)$
 - Let $Z \in T_v \mathcal{P}(x, y)$
 - Replace w_{ρ} with the interpolation

$$Y \#_{\rho} Z \in T_{w_{\rho}} \mathcal{P}(x, y) = W^{1, p}(w_{\rho}^* T W).$$

defined by

$$(Y \#_{\rho} Z)(s,t) = \begin{cases} Y(s+\rho,t) & s \in (-\infty,-1] \\ \exp_{T} \left[\beta^{-}(s) \ln_{T} (Y(s+\rho,t)) + \beta^{+}(s) \ln_{T} (Z(s-\rho,t)) \right] & s \in [-1,1] \\ \\ Z(s-\rho,t) & s \in [1,\infty) \end{cases}$$

where the subscript T indicates taking tangents of the exponential maps at appropriate points.

>7 Wp (linearized) Step 1

7 9.4: Construction of ψ .

7.1 Summary

- Newton-Picard method, general idea:
 - Allows finding zeros of f given an approximate zero x_0 , using the extra information of the 1st derivative f'.
 - Original method and variant: find the limit of a sequence

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}, \qquad \qquad x_{n+1} = x_n - \frac{f(x_n)}{f'(x_0)}.$$

- Second variant more useful: only need derivative at one point:

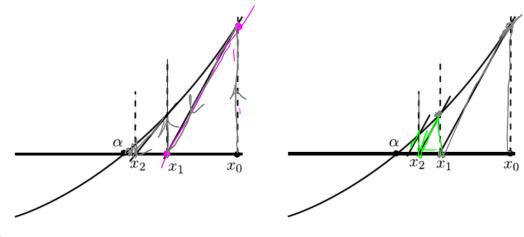




Figure 4: Newton Method Variants

- Pregluing function $w_{\rho} \in C^{\infty}_{\searrow}(x, z)$ from previous section
 - Exponential decay
- Want to construct true solution $\psi_{\rho} \in \mathcal{M}(x, z)$, so $\mathcal{F}(\psi_p) = 0$.
 - Suffices to get a weak solution
 - Automatic continuity + elliptic regularity \implies strong solution
- Define \mathcal{F}_{ρ} as $\mathcal{F} \circ \exp_{w_{\rho}}$ expanded bases Z_i from trivialization of TW.
- $L_{\rho} = (d\mathcal{F}_{\rho})_0$ will be the linearization of the Floer operator at zero.
- Adapting Newton-Picard to operators:
 - $-L_{\rho}$ won't be invertible on entire space, but

$$\frac{1}{f'(x_0)} \iff L_{\rho}^{-1},$$

$$T_{w_{\rho}}\mathcal{P}(x,z) = W^{1,p}(w_{\rho}^*TW) = W^{1,p}(\mathbb{R} \times S^1; \mathbb{R}^{2n}) = \ker(L_{\rho}) \oplus W_{\rho}^{\perp},$$

where L_{ρ} will have a right inverse on W_{ρ}^{\perp} . * Where does W_{ρ}^{\perp} come from? Essentially the kernel of some linear functional given by an integral:

$$W_{\rho}^{\perp} \coloneqq \left\{ Y \in W^{1,p} \mid \int_{\mathbb{R} \times S^1} \langle Y, \cdots \rangle \, ds \, dt = 0, \text{ plus conditions} \right\}.$$

– Run Newton-Picard in W_{ρ}^{\perp}

Decompose

• Will obtain for every $\rho \ge \rho_0$ an element $\gamma(\rho) \in W_{\rho}^{\perp}$ with

$$\mathcal{F}_{\rho}(\boldsymbol{\gamma}(\boldsymbol{\rho})) = 0.$$

• Where does γ come from? Intersection-theoretic interpretation on page 320:

$$\left(\exp_{w_{\rho}} \right)^{-1} \mathcal{M}(x, z) \cap W_{\rho}^{\perp} \subseteq T_{w_{\rho}} \mathcal{P}(x, z) \qquad \rightsquigarrow \gamma$$
$$\mathcal{M}(x, z) \cap \left\{ \exp_{w_{\rho}} W_{\rho}^{\perp} \mid \rho \ge \rho_{0} \right\} \subseteq \mathcal{P}(x, z) \qquad \rightsquigarrow \psi(\rho),$$

which we get by exponentiating.

• This gives a codimension 1 subspace in $\mathcal{M}(x, z)$, which we take to be $\psi(\rho)$:

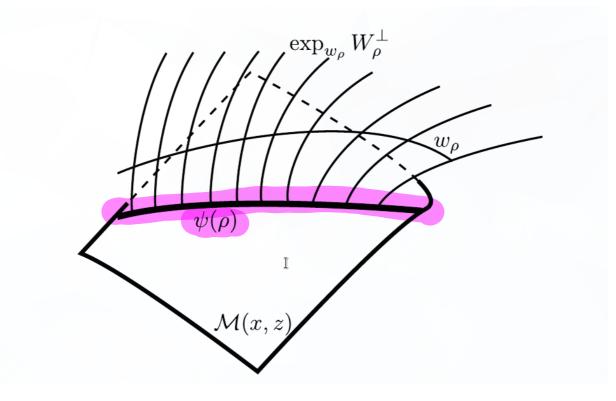
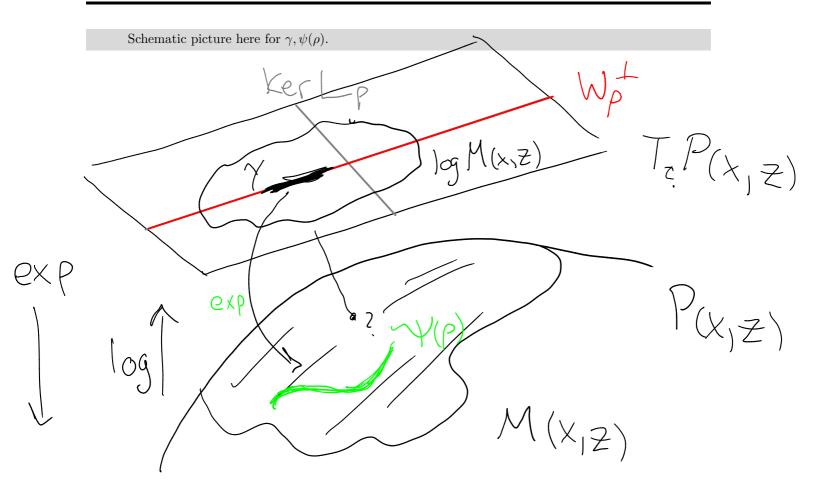


Figure 5: Intersection interpretation



- Apply the implicit function theorem to show differentiability of γ in ρ .
- Use a trivialization Z_i^{ρ} of TW to get a vector field along w_{ρ}

– This is exactly an element of $T_{w_{\rho}}\mathcal{P}(x,z)$

• Exponentiate to get an element of $\mathcal{M}(x, z)$:

$$\psi(\rho) \coloneqq \exp_{w_{\alpha}}(\gamma(\rho)).$$

• Final Result: project onto $\mathcal{L}(x, z)$ to get $\hat{\psi}$.

Checking Properties:

- Existence: show $\hat{\psi}$ is a proper injective immersion \implies embedding.
- Uniqueness: show the broken trajectory (\hat{u}, \hat{v}) is the endpoint of an embedded interval in $\overline{\mathcal{L}}(x, z)$.
 - Show that any other sequence converging to (\hat{u}, \hat{v}) must approach via this interval, otherwise could have cuspidal points:

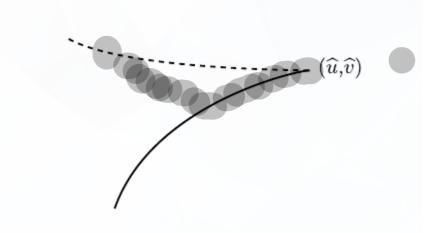


Figure 6: Cuspidal Point on Boundary

Probably not worth going farther than this! Extremely detailed analysis.